



# Radar Meteorology Introduction and Basic Theory

**R Bibraj**  
Scientist D, RMC Chennai

**भारत मौसम विज्ञान विभाग**  
**INDIA METEOROLOGICAL DEPARTMENT**



**भारत मौसम विज्ञान विभाग**  
**INDIA METEOROLOGICAL DEPARTMENT**



# Credits for content included in this Training Material

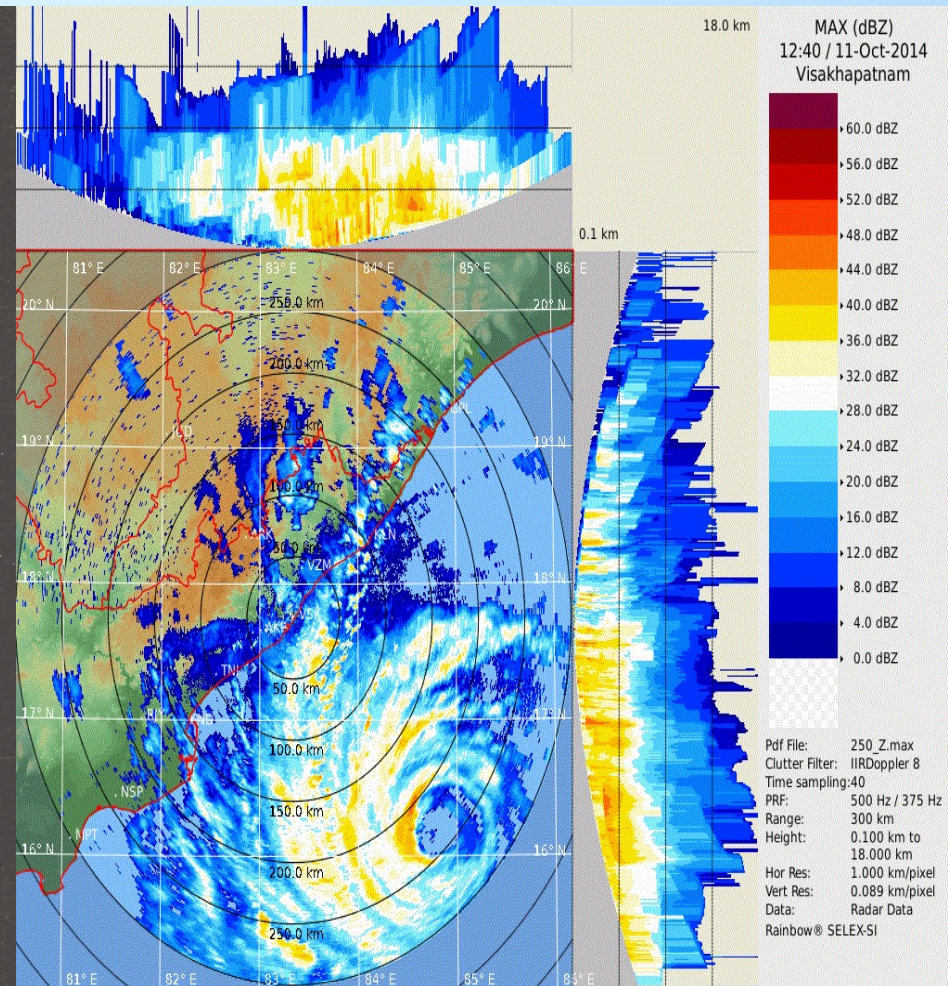
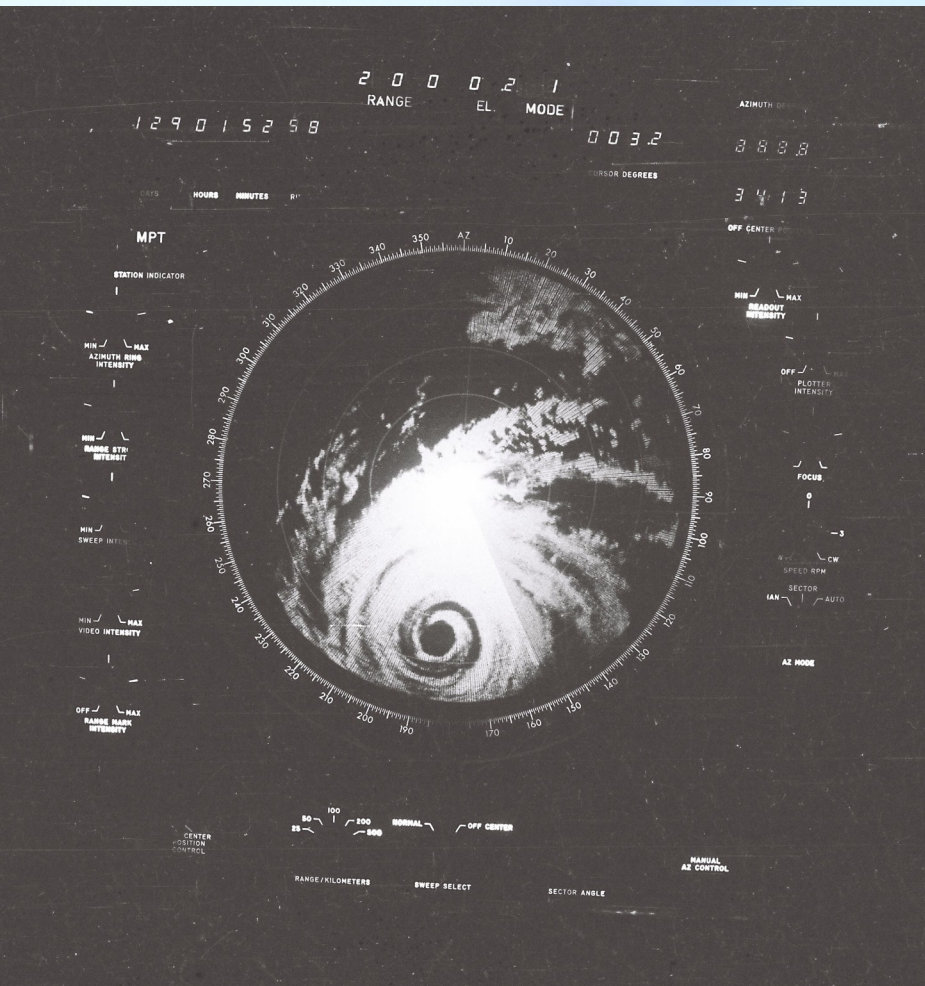
Shri . S.B. Thampi Former-DDGM RMC Chennai  
Shri. Venkateshwarulu, Former- Scientist F, Radar Lab, New Delhi  
Dr. Devendra Pradhan Former- ADGM(Instruments)-New Delhi  
Dr. R. Suresh, Former-DDGM RMC Chennai  
Shri. BAM. Kannan, Director- Doppler weather Radar, Chennai

All former and current operational duty staff of DWR Visakhapatnam, DWR Chennai, DWR Machilipatnam, DWR Kolkata for generating the images





# Evolution of Radar





# Radar Room



भारत मौसम विज्ञान विभाग  
INDIA METEOROLOGICAL DEPARTMENT

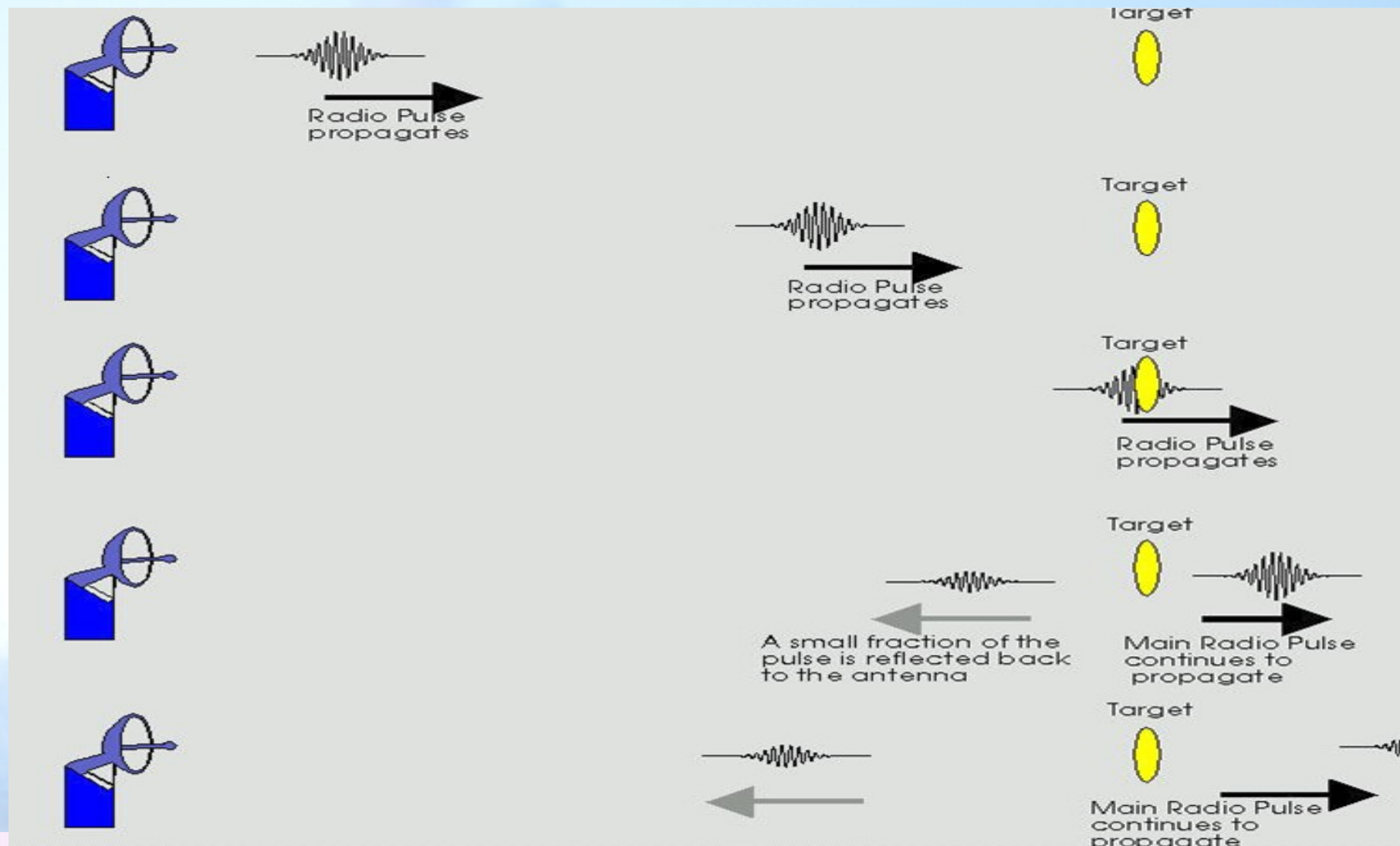




# Radar Equipment : Radome & Antenna



# How RADAR Works?





# Lets find the range

## Range Determination

Pulsing allows a radar system to display the target *range*. By measuring the elapsed time between the broadcast of a pulse and subsequent detection of returned energy from a target, the radar system determines the distance between radar antenna and target.

$$r = (c * t) / 2$$

where,  $r$  - distance (range) in km,  
 $c$  - speed of light in km/s,  
 $t$  - elapsed time since the end  
of the transmission of the pulse (sec)



# Radar – Frequency bands

Band Designation	Frequency	Wavelength
S	2-4 GHz	15-8 cm
C	4-8 GHz	8-4 cm
X	8-12 GHz	4-2.5 cm

	Large Wavelength:	Small Wavelength:
😊	Range; V Measurement	Sensitive; Compact
😞	Dimensions, Costs	Attenuation





# Power Transmission

Light Bulb = 40 W

Peak powers

S Band Radar = 750000W(klystron)

C band Radar = 2500000W(klystron)

X band Radar = 400 W (SSPA)

Received power after hitting the target / minimum detectable signal is

= 0.0000000000000005011 W

=  $5 \times 10^{-15}$  W

=  $10 \log ( 5 \times 10^{-15} / 1 \text{ mW}) \text{ dbm}$

= -113 dbm



# Why do we need db?

10 dBm	10 mW			
9 dBm		8 mW		
8 dBm				6.4 mW
7 dBm			5 mW	
6 dBm		4 mW		
5 dBm				3.2 mW
4 dBm			2.5 mW	
3 dBm		2 mW		
2 dBm				1.6 mW
1 dBm			1.25 mW	
0 dBm	1 mW			





# The Radar Equation

## THE RADAR EQUATION FOR WEATHER TARGETS

$$Z = \frac{1024 \ln(2)}{c\pi^3} \left( \frac{\lambda^2}{P_t \tau G^2 \Theta \Phi} \right) \left( \frac{\bar{P}_r r^2}{|K|^2} \right)$$

constants

Radar  
characteristics

Target  
characteristics



# What is actually Reflectivity?

The quantity  $\frac{\sum_j D_j^6}{V_c}$  is of utmost importance in radar meteorology

It is designated with the symbol  $Z$ , and is called the  
**radar reflectivity factor**

In logarithmic units:

$$dBZ = 10 \log \left( \frac{Z}{1 \text{ mm}^6 / \text{m}^3} \right)$$

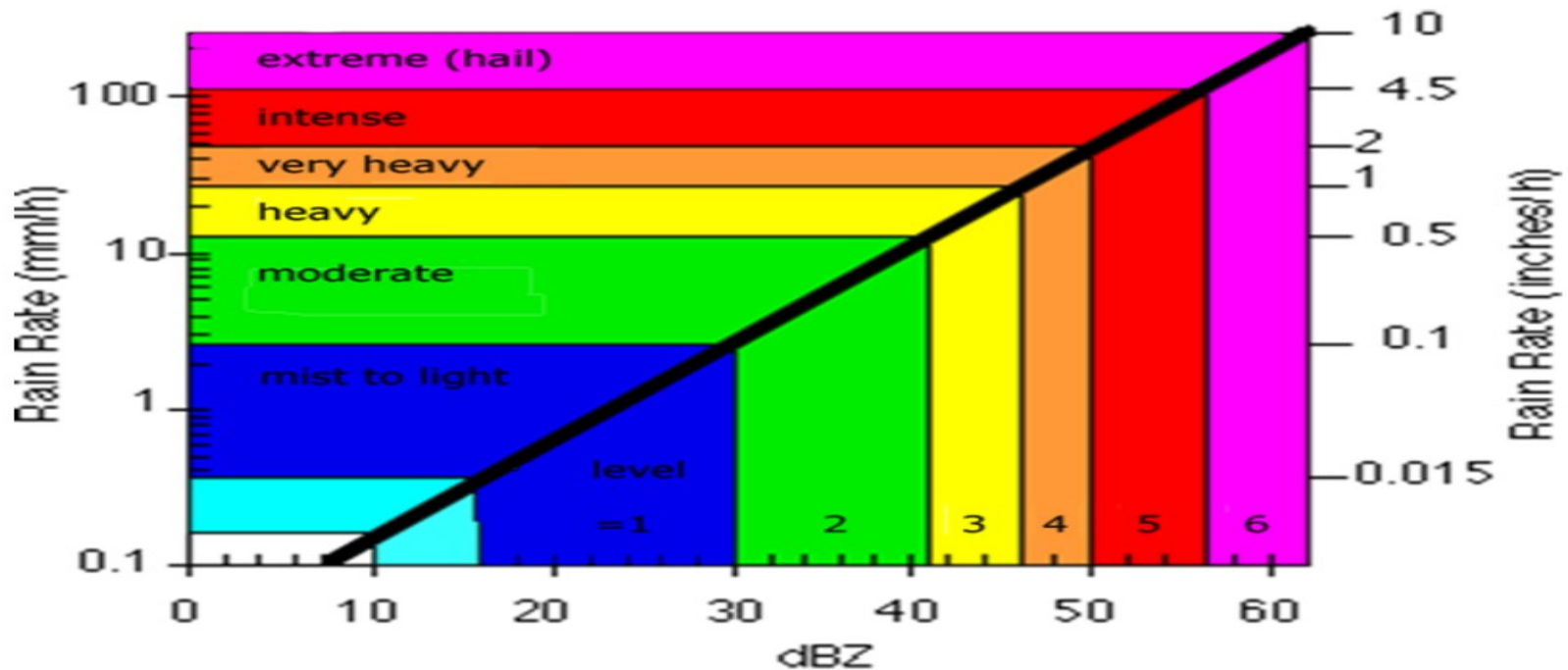




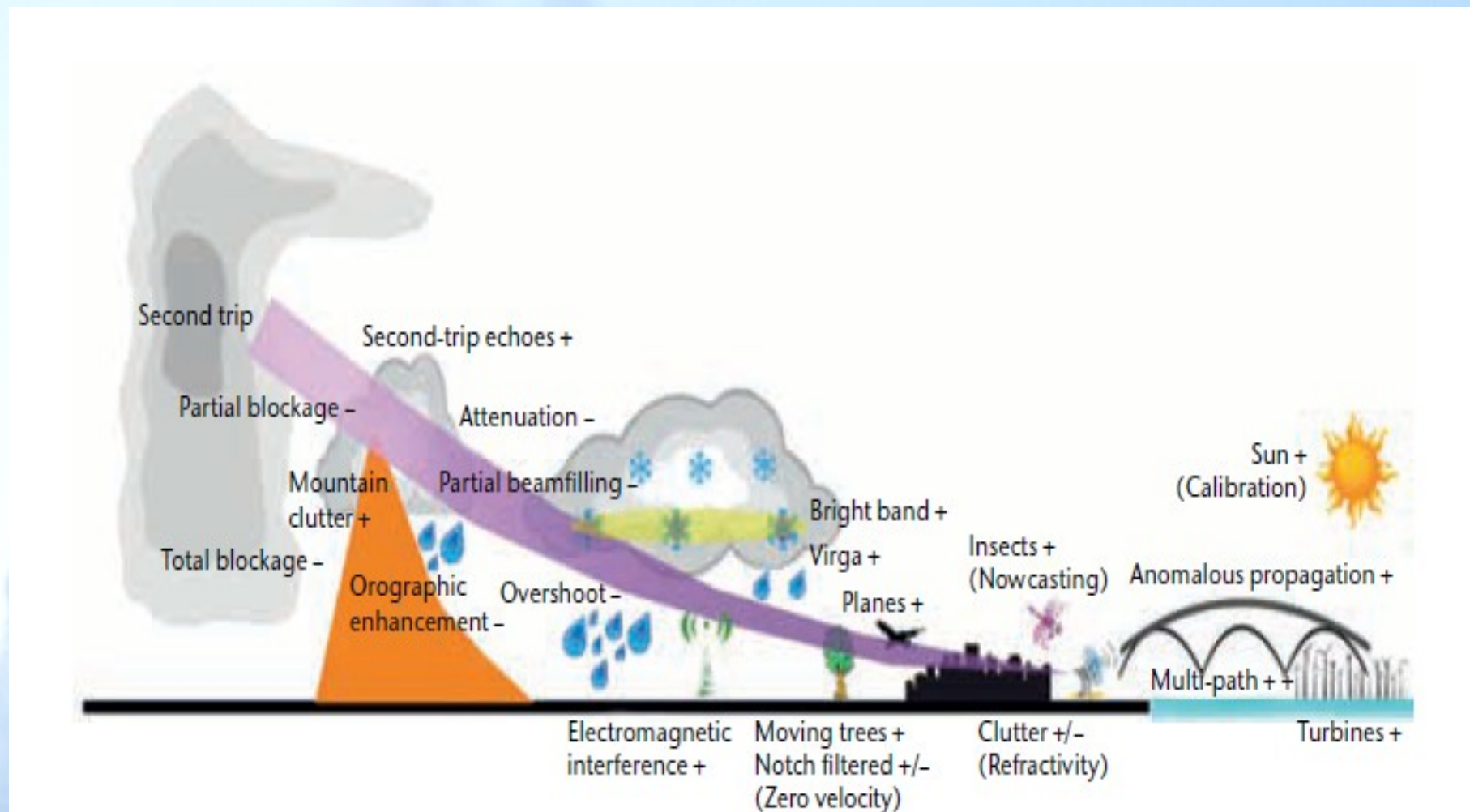
# Decibels

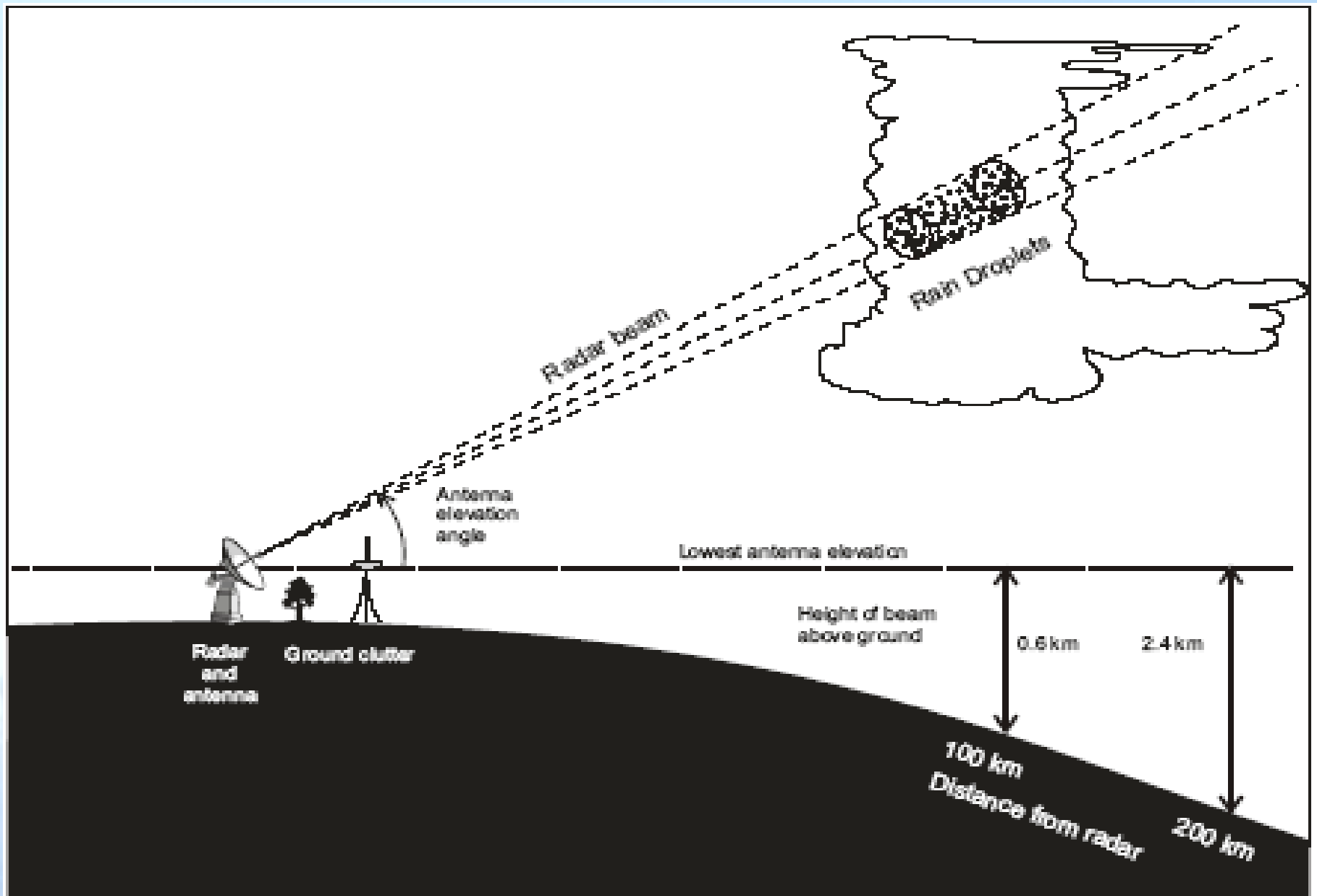
40 dbZ is equal to 10 times 30dbZ

## RAINFALL CATEGORY



# Factors affecting Radar Propagation



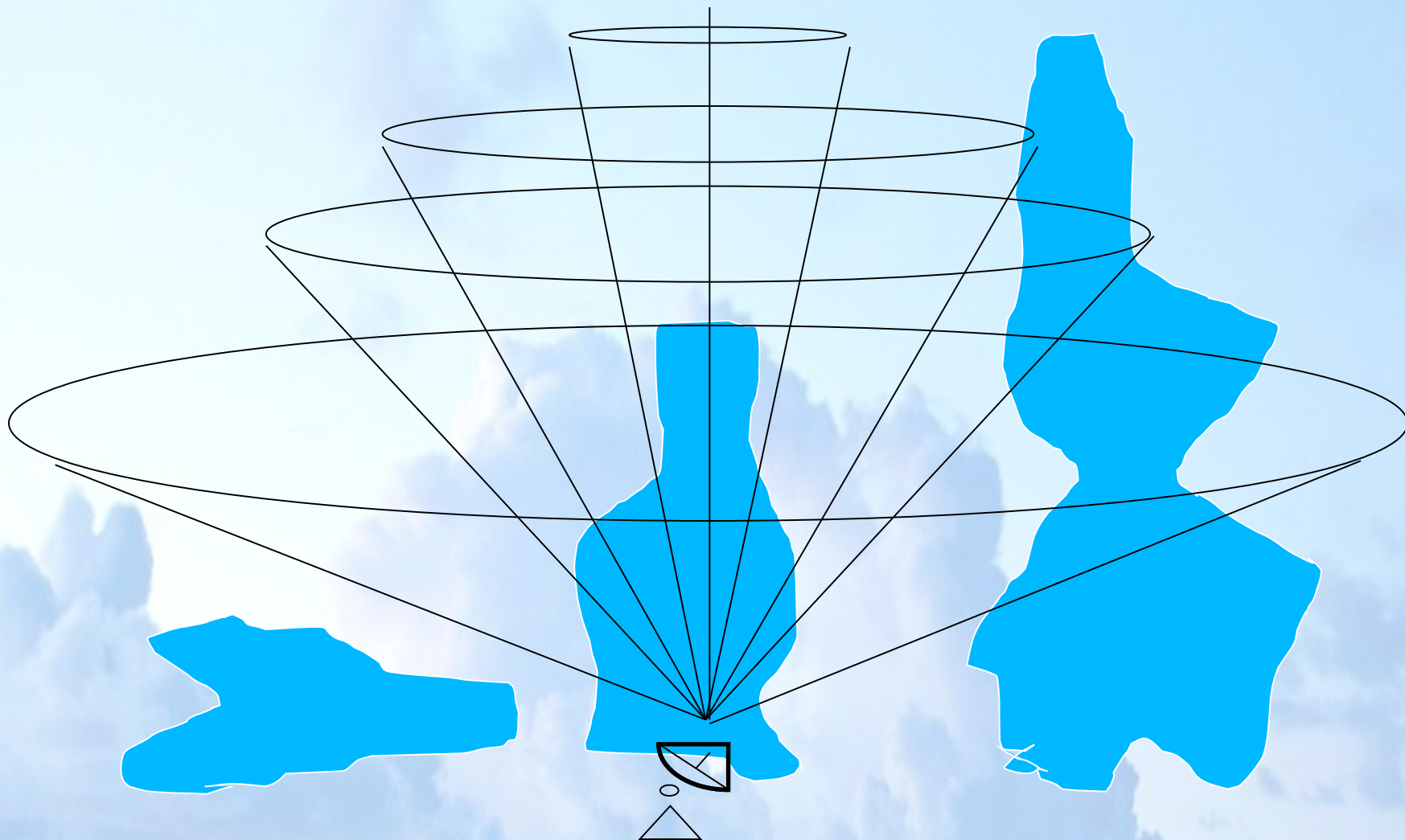


Radar scans this entire volume by raising and lowering the beam as the antenna rotates.



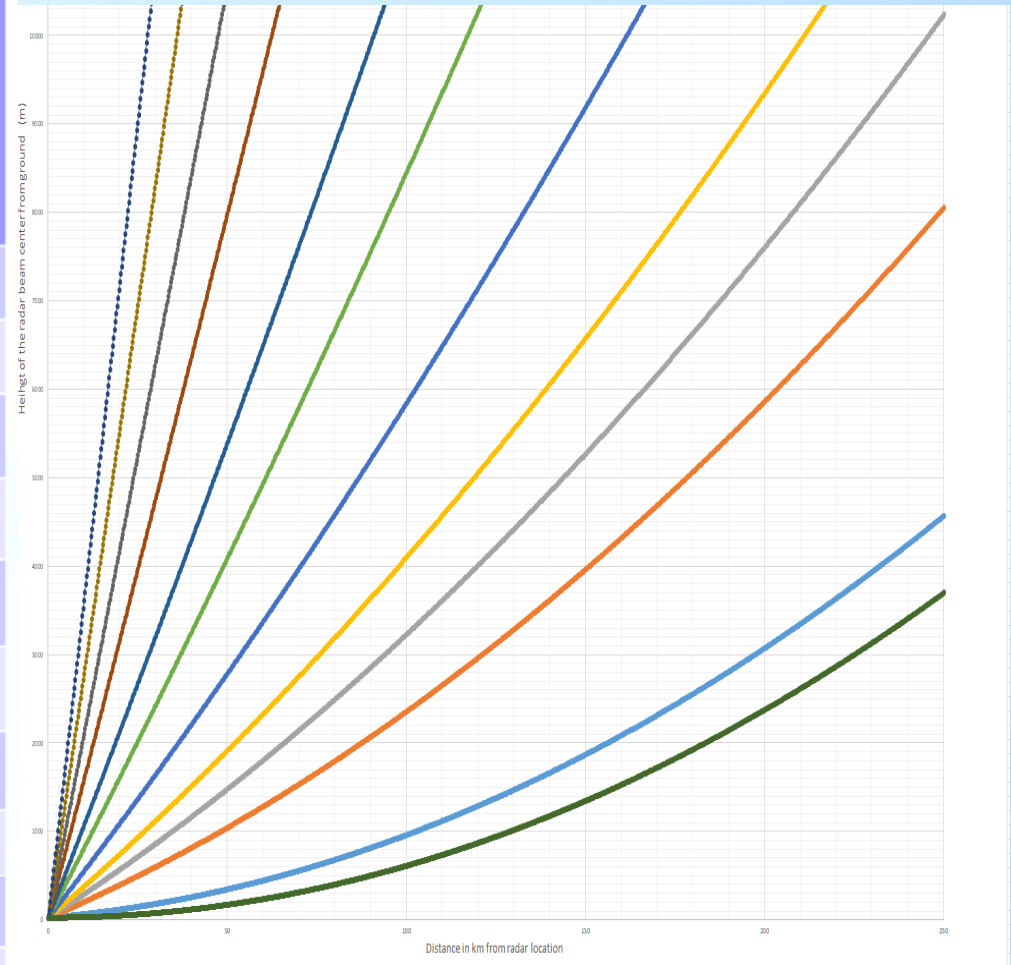


# The Radar Volume Scan



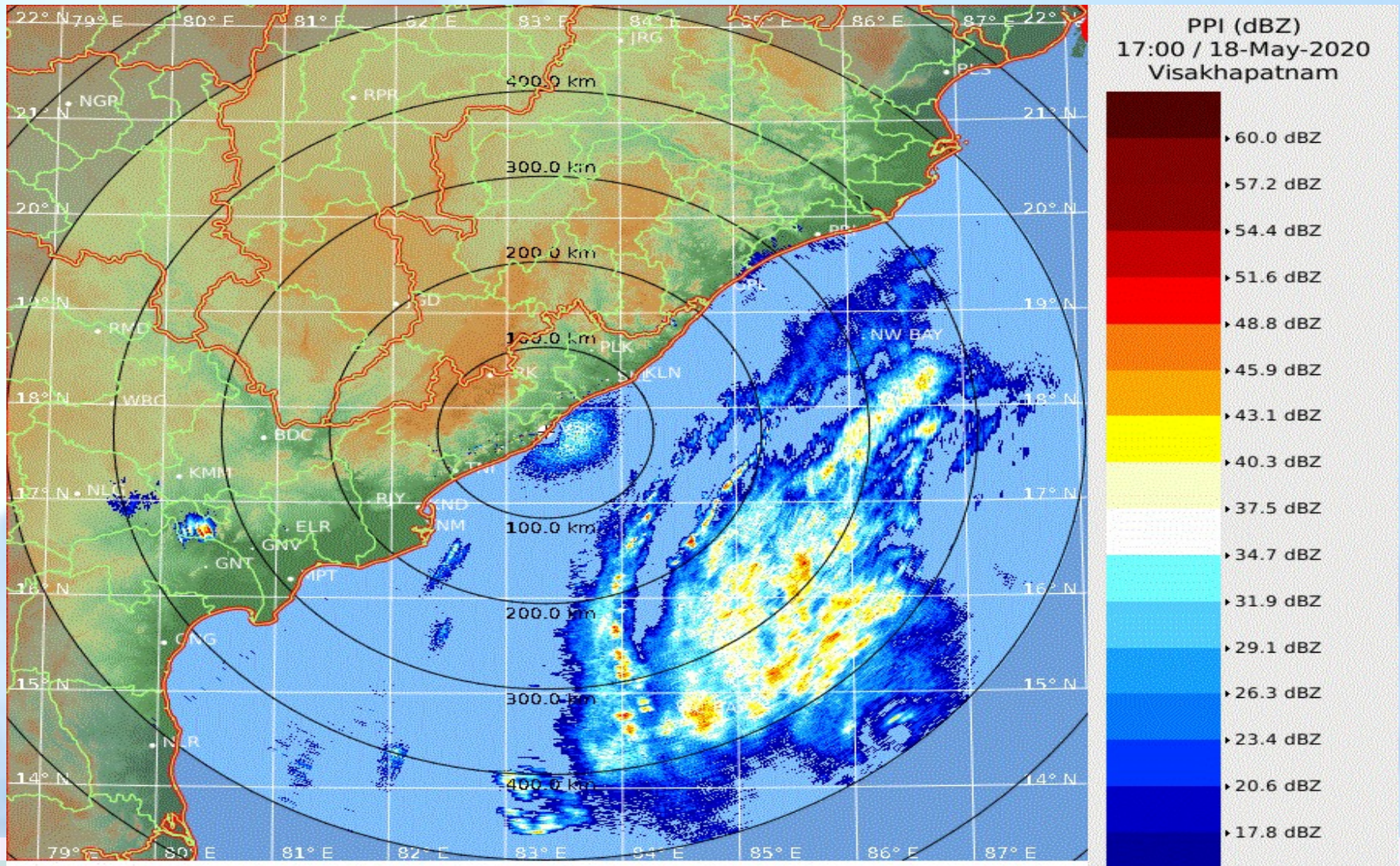
# What Height am I looking at?

Distance From radar	Height of Centre Beam at lowest Elevation (0.2 Deg) in km(170MSLP)
50 km	0.5km
100km	1.10km
150km	2.01km
200km	3.22km
250km	4.71km
300km	6.51km
350km	8.6km
400km	11km
450km	13.65km
500km	16.61km





# Super Cyclone AMPHAN





# Sub and Super Refraction

The radar assumes the beam is undergoing standard refraction. The beam height will be misrepresented under super/sub-refractive conditions.

Subrefraction

Standard Refraction

Superrefraction

Max cores may be displayed at wrong heights

**Superrefraction:** The beam refracts more than standard. The beam height is lower than the radar indicates.

**Subrefraction:** The beam refracts less than standard. The beam height is higher than the radar indicates. Beam can overshoot developing storms.

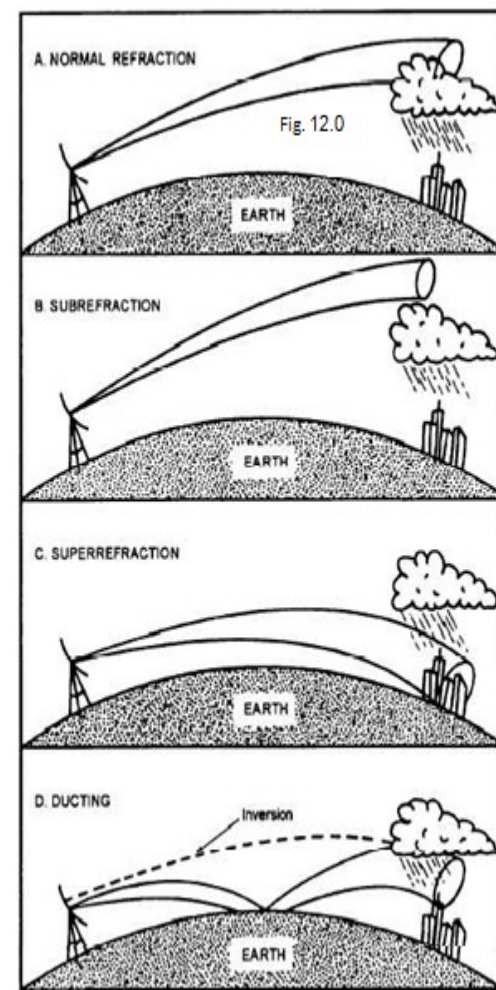


Fig. 12.0



# Different types of clutter

**Clutter can be classified into 3 groups**

- (i) Ground clutter (land clutter(Buildings/wind turbine and sea clutter – Lower elevations)**
- (ii) Air borne clutter (Biological targets (insects/bird)/Air-planes/ Aerosols/Particulate matter)**
- (iii) Interference clutter (sun/Transmitting Antenna).**

*“An analysis of Anomalous propagation parameters and its effect on the intensity of clutter in weather radars”,  
R.Bibraj, B.Arul Malar kannan, K. Ramachandra Rao and K.C.Saikrishnan, Mausam ,71,1(January 2020), 11-20*





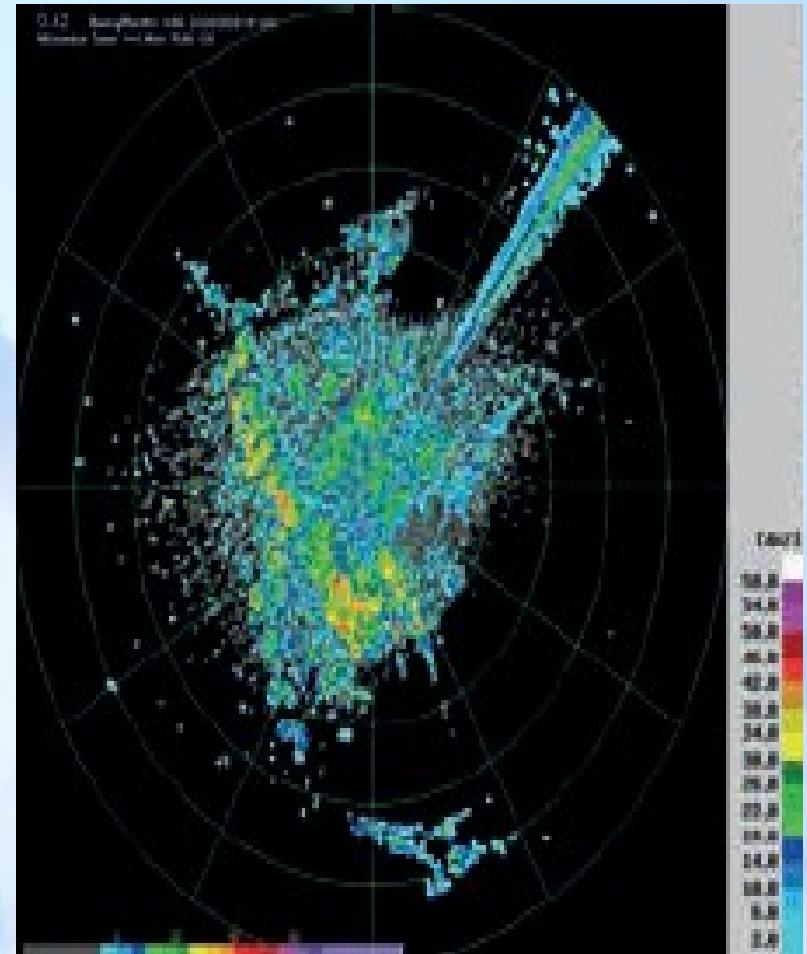
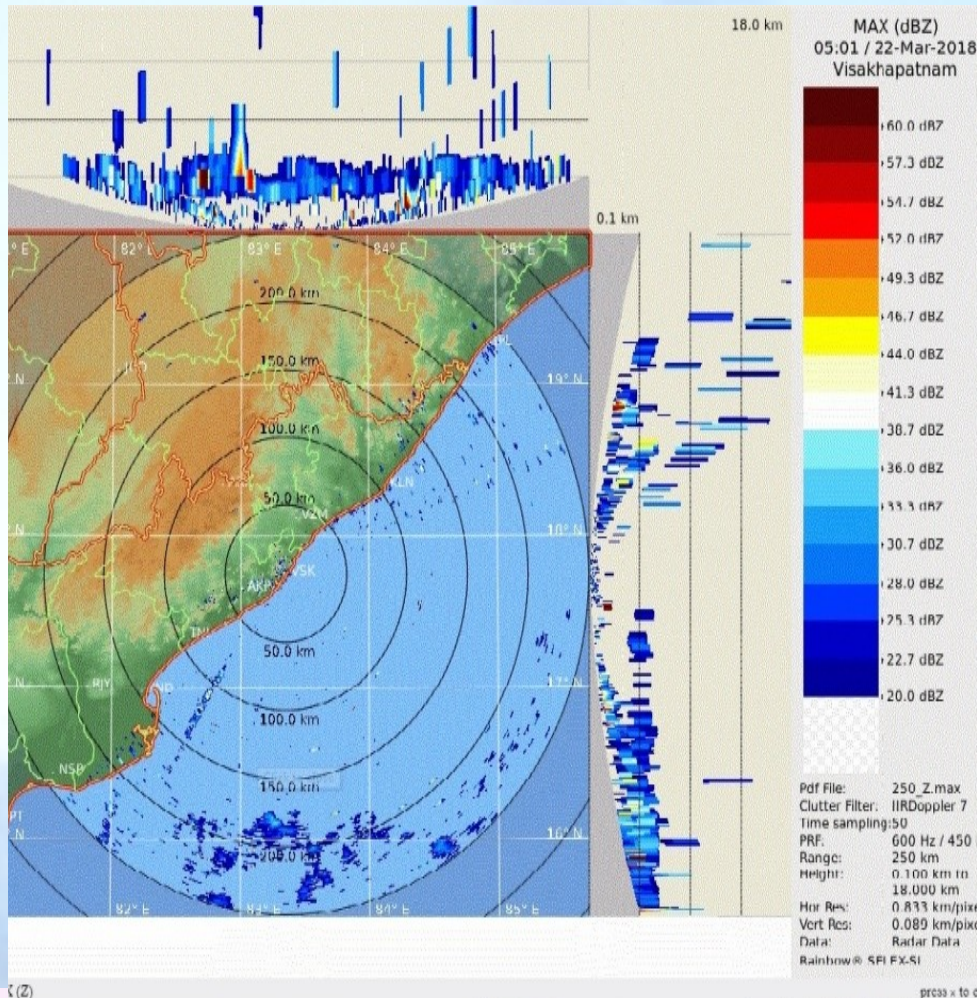
# Clutter Echoes

- Multi Radar Radars

## Velocity

## Standard Echoes

## Dual Polarization

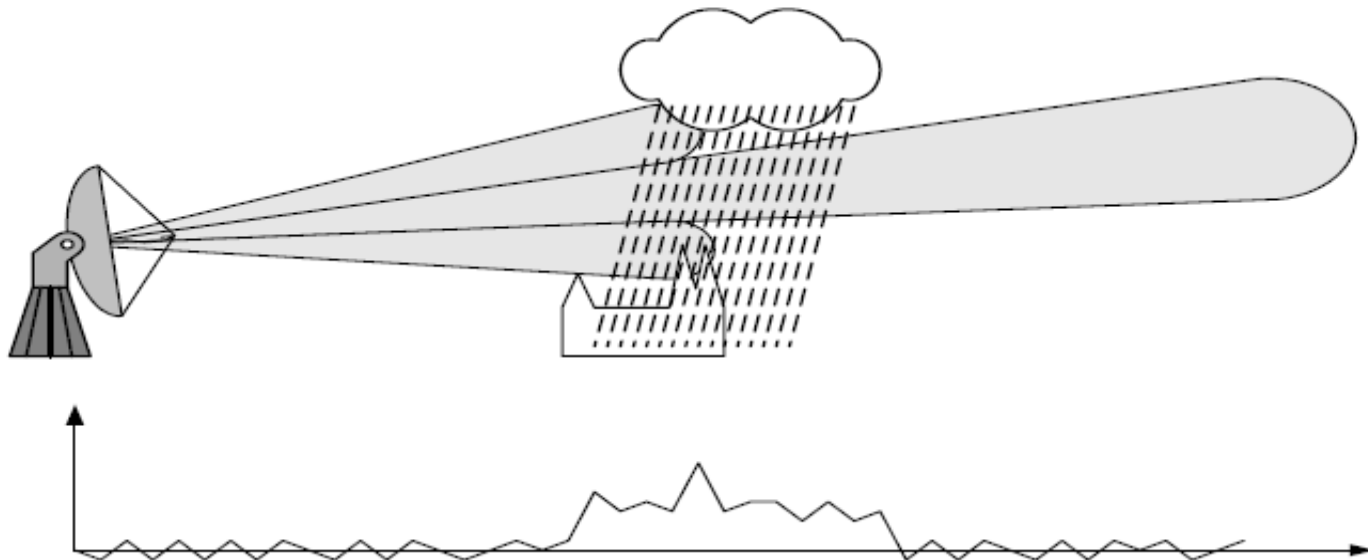


# Side Lobes in the beam

## Side Lobes

All the energy not contained in the “main lobe” tends to travel in some preferred directions forming the so called “side lobes”. Side lobes are presently an unavoidable and detrimental part of any weather radar system.

The main effects of the side lobes are in producing multiple displays of the same target. Side lobes increase the ground clutter.

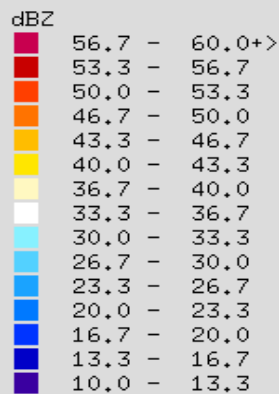
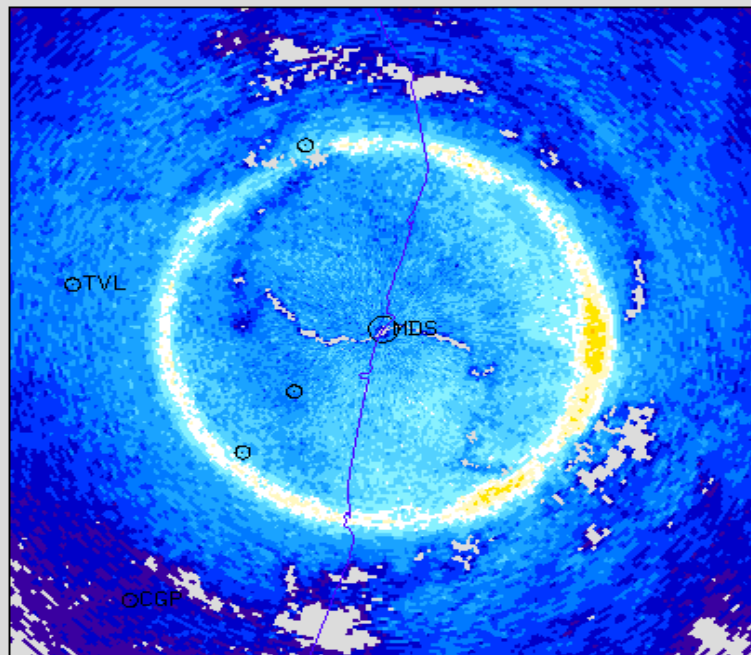




# Bright band

File : 2005102609151101.ppz  
Type : PPI(Z)  
Range: 50.0 km

26.10.2005  
09:15:11



CHENNAI  
Scan R : 150 km  
Scan Res: 0.50 km  
Disp R : 50 km  
Disp Res: 0.250 km  
PW : Short  
PRF: 1000 / 0  
AS : 15.00 deg/s  
TS : 66  
RS : 2  
CC : Doppler 7  
SQI: 0.20  
CSR: 10.0 dB  
LOG: 2.0 dB  
AZ : 0.0-359.0  
EL : 9.0 deg

CDR Chennai

- Just below freezing level
- Ice crystals are surrounded in the surface by water droplets during melting
- Gives very high reflectivity



# Attenuation

Attenuation	S- Band	C -Band	X- band
Clear Air(500km) Two way	4.5 db	5 db	6 db
Two way attenuation Rainfall(100mm/hr) (10 km)	0.6db	9.6 db	62 db

<i>Wavelength (cm)</i>	<i>Relation (dB km<sup>-1</sup>)</i>
10	0.000 343 $R^{0.97}$
5	0.00 18 $R^{1.05}$
3.2	0.01 $R^{1.21}$

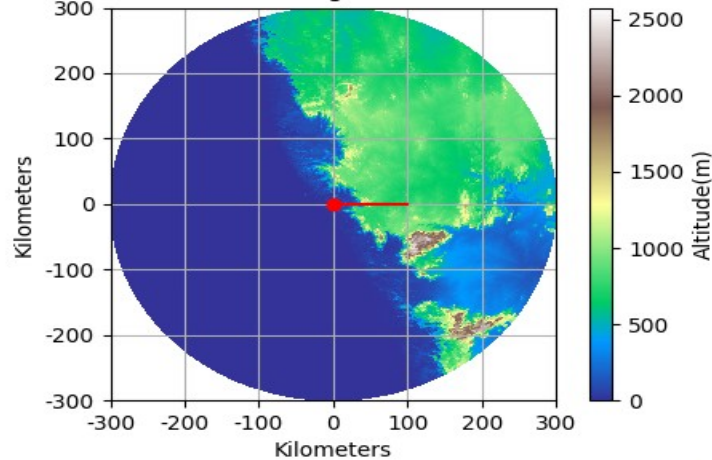
Note: After Burrows and Attwood (1949).  
One-way specific attenuations at 18 °C.  
 $R$  is in units of mm hr<sup>-1</sup>.

**Attenuation correction using Dual Polarization Techniques**

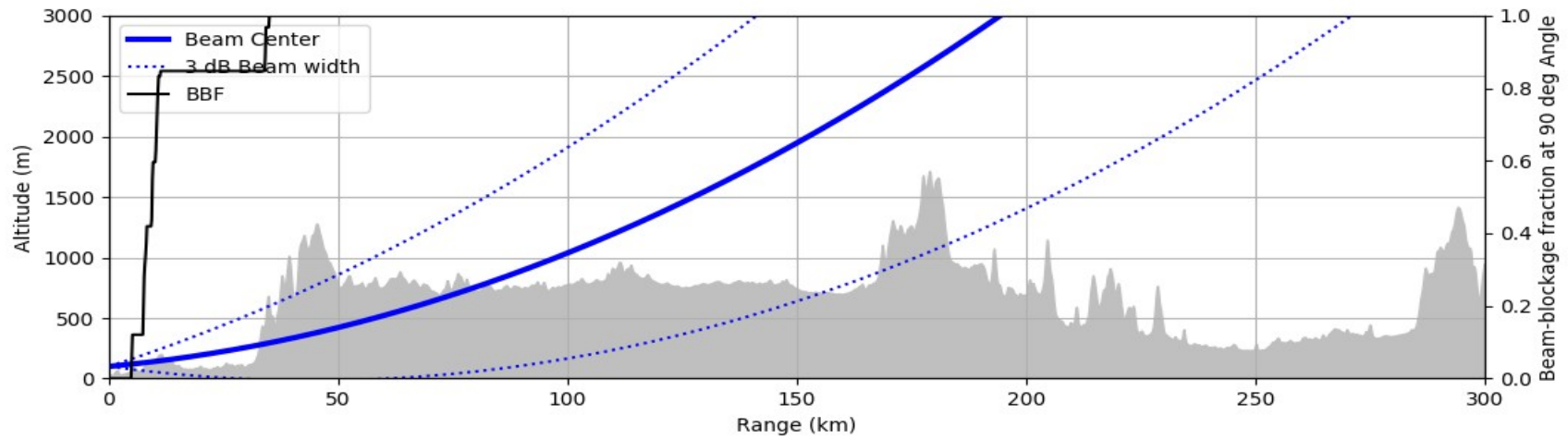
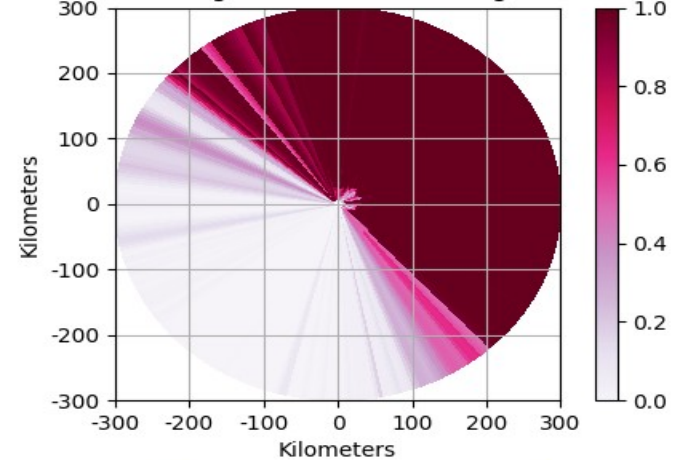


# Beam Blockage

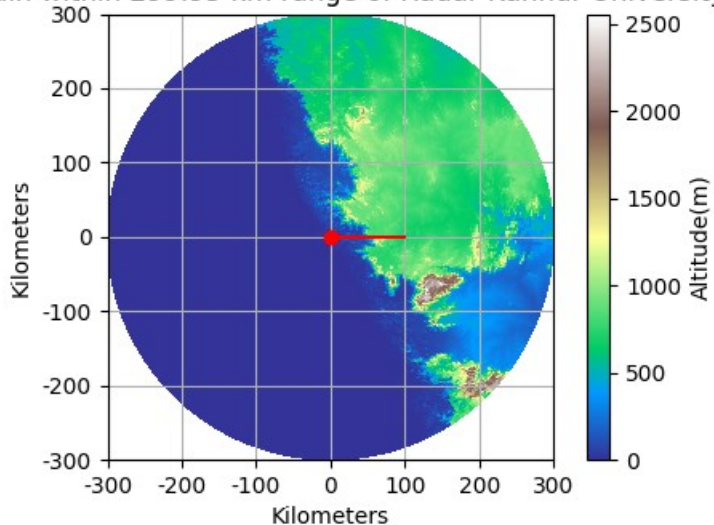
Terrain within 299.95 km range of Radar OLDSITE KANNUR



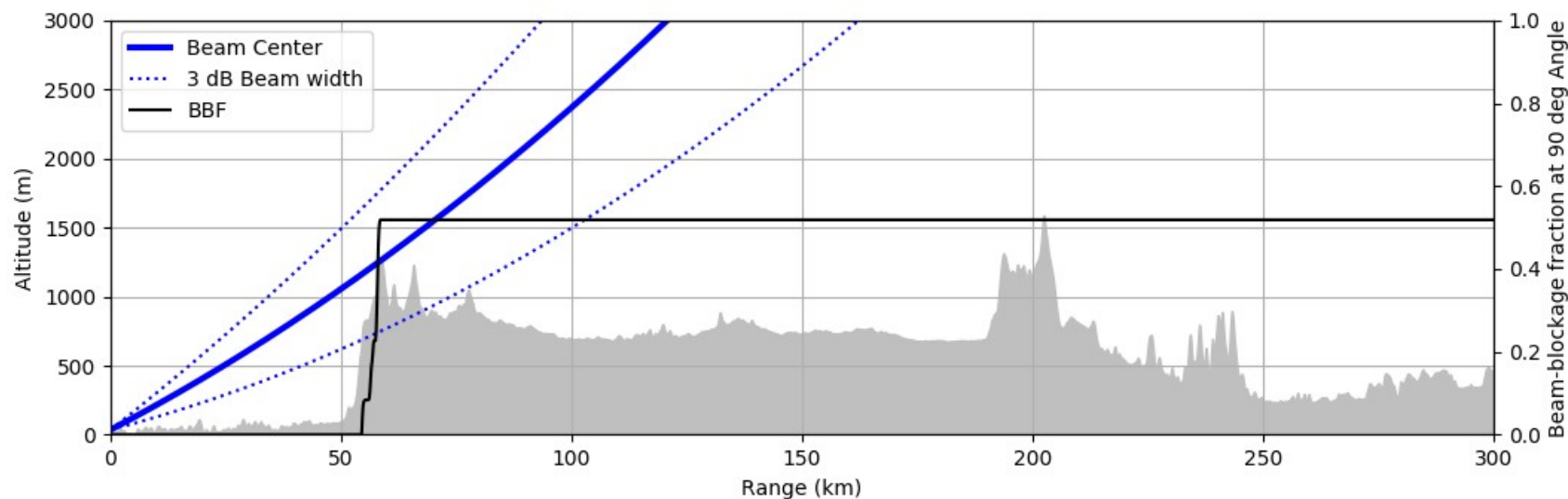
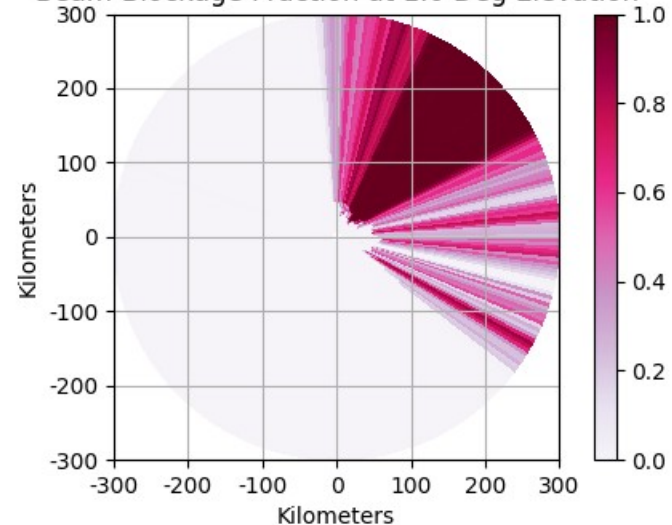
Beam-Blockage Fraction at 0.2 Deg Elevation



Terrain within 299.95 km range of Radar Kannur University

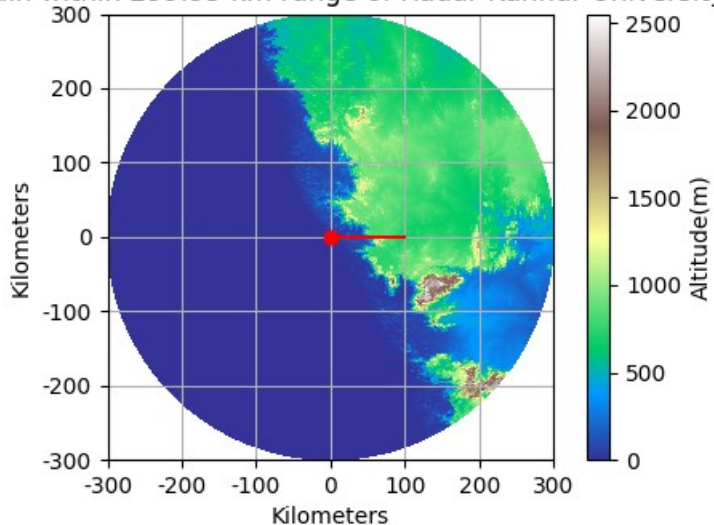


Beam-Blockage Fraction at 1.0 Deg Elevation

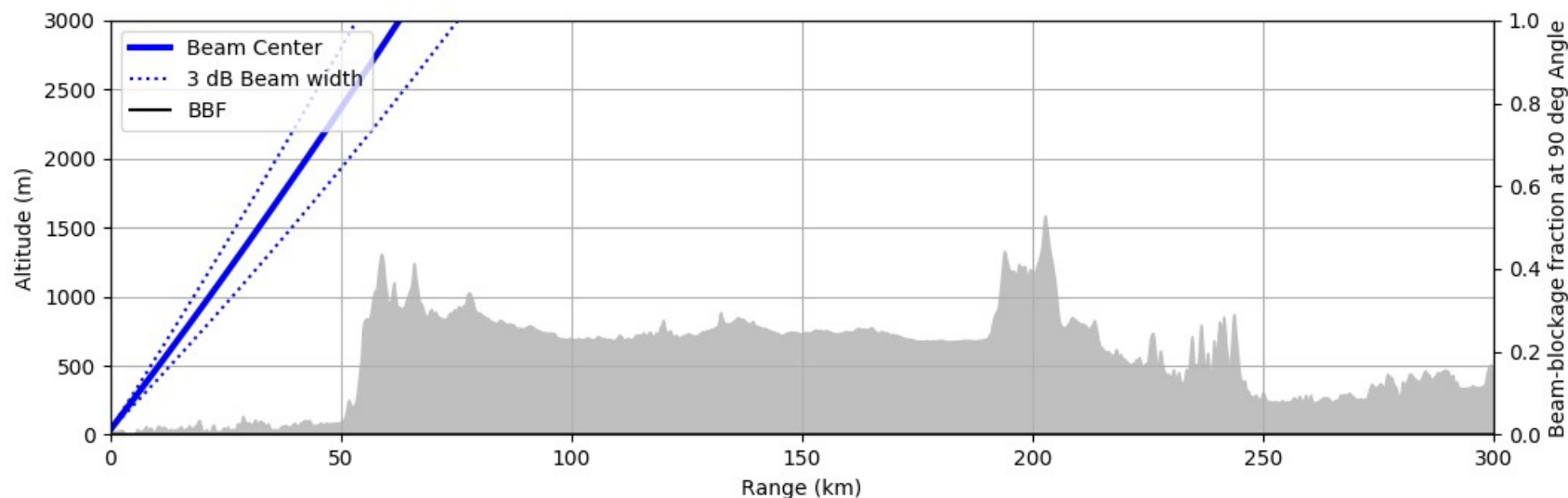
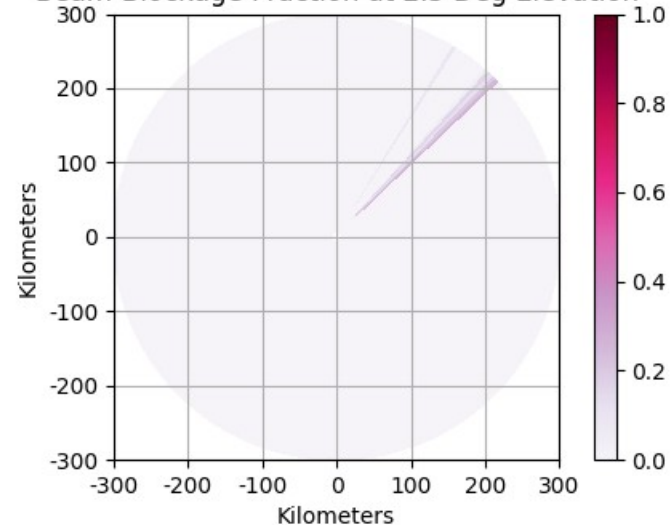




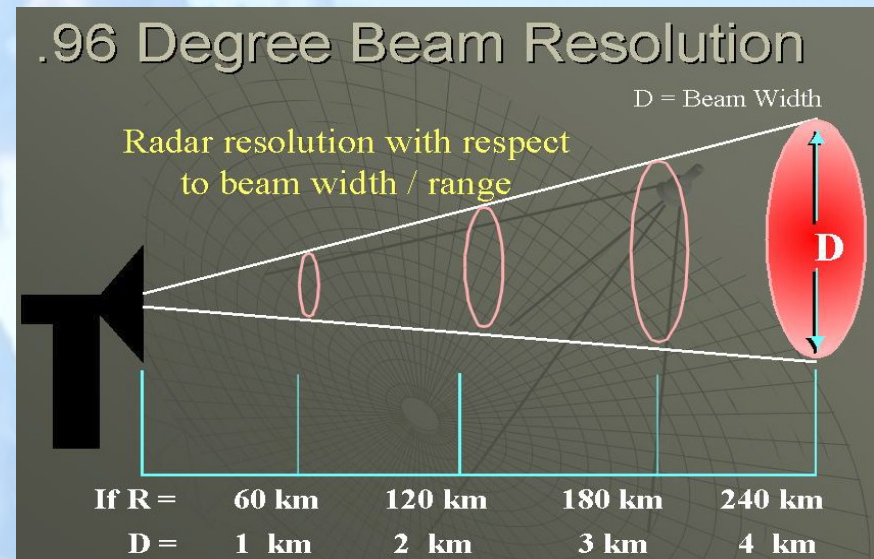
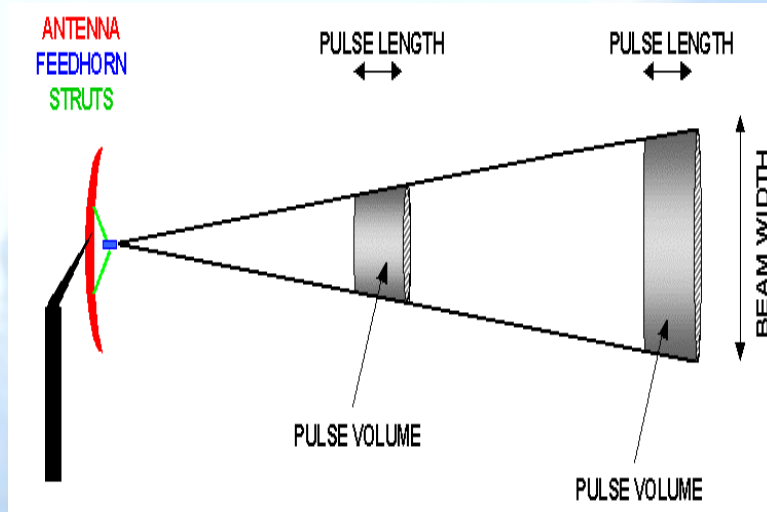
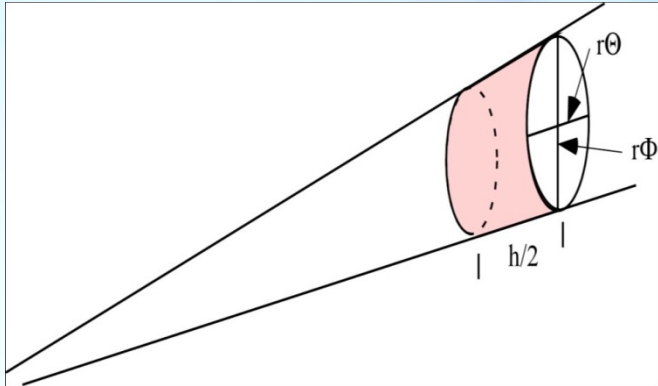
Terrain within 299.95 km range of Radar Kannur University



Beam-Blockage Fraction at 2.5 Deg Elevation

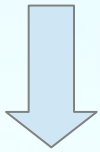


# Radar Resolution

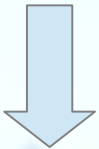


# Bin Resolution and Beam Width

Range res



Pulse width



Peak Power



**Beam Width =  $70\lambda / D$**

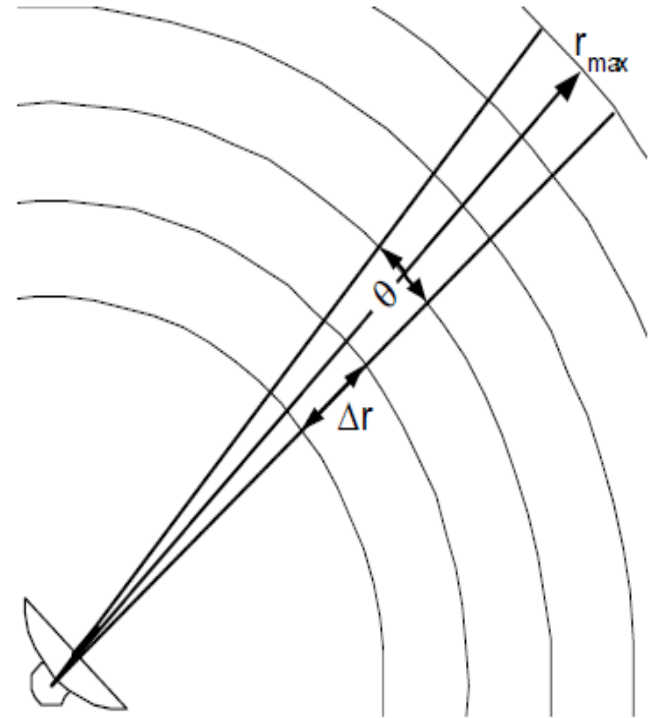
## Azimuth Resolution

$\Theta[^\circ]$ : 3dB Antenna Beam Width

## Radial (Range) Resolution

$$\Delta r = c \cdot \Delta t / 2$$

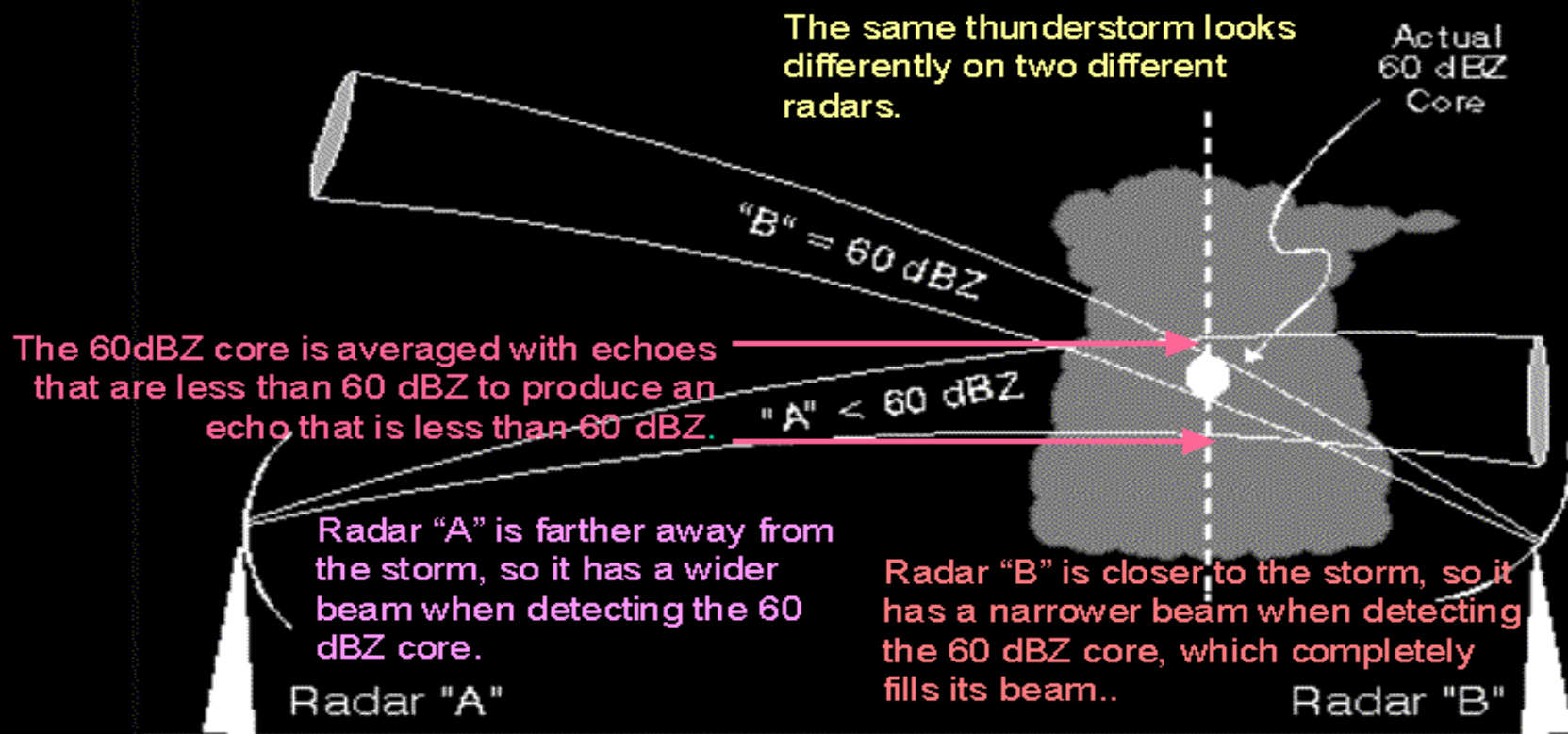
(With:  $\Delta t$  = Pulse Length)



	S- Band	C-Band	X-Band
1 Deg	23 ft/7m	11ft/ 3.5m	7 ft/2.1m

# Beam Broadening

## Radar Beam Broadening and Comparing Two Radars





# Pulse Repetition frequency

## Pulse

The rate at which pulses are transmitted is called **Pulse Repetition Frequency (PRF)**. PRF is usually expressed in terms of number of pulses per second.

The reciprocal of PRF,  $1/\text{PRF}$ , is referred to as **Pulse Repetition Time (PRT)**.

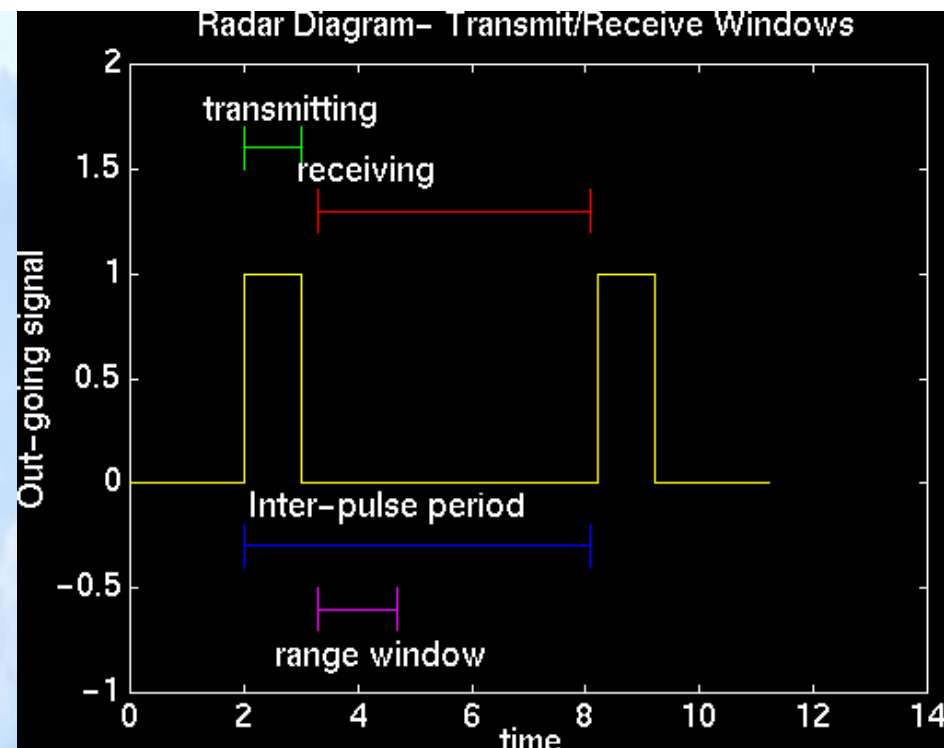
Lets say,  
Pulse has to travel 500 km  
(to and fro 1000km)  
Speed is  $3 \times 10^8$  m/sec

Time taken: distance/speed

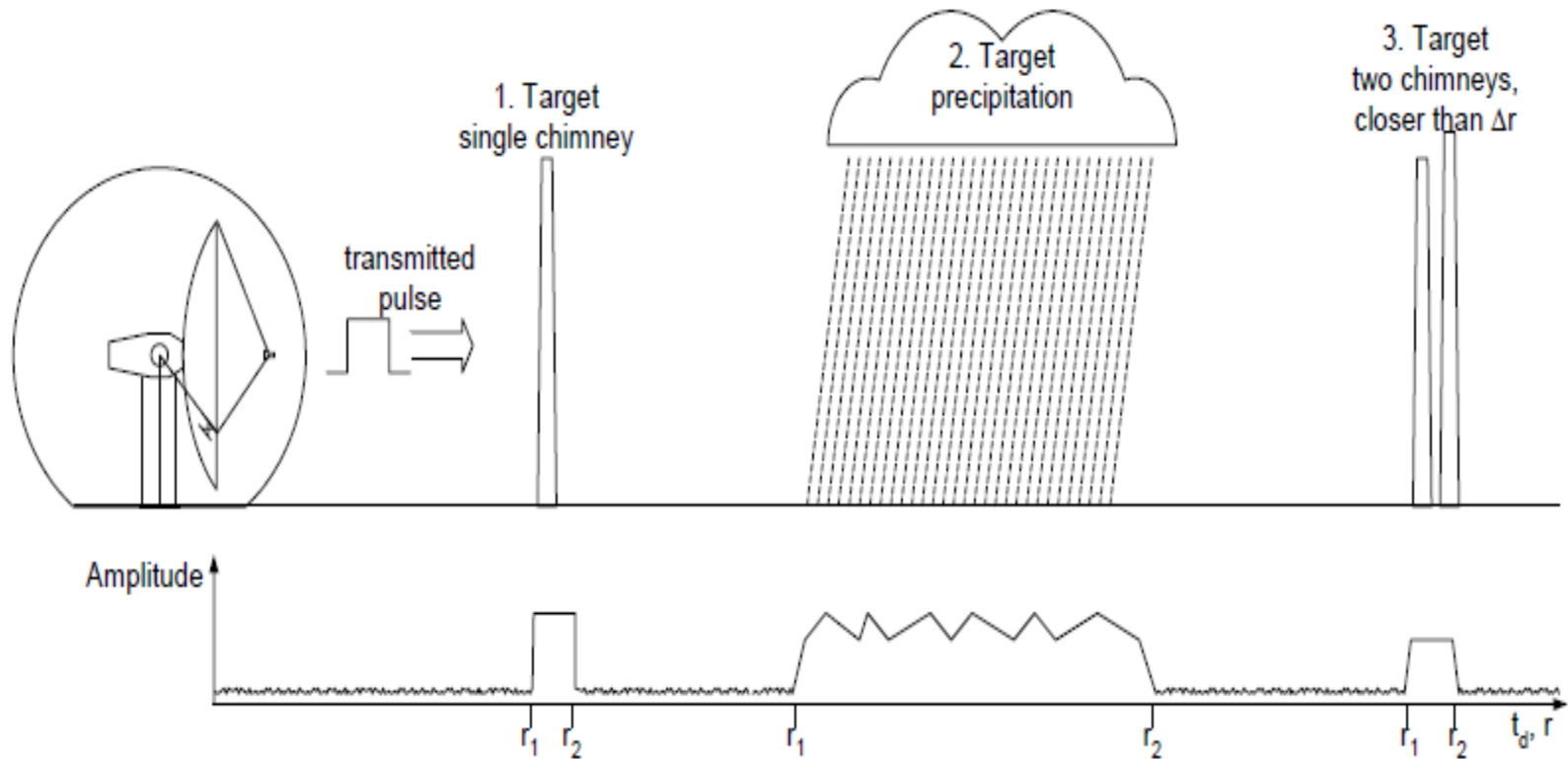
PRT = 3 milli seconds

PRF =  $1/\text{PRT}$

PRF = 300 pulses /sec (Hz)



# How Radar detects the signal

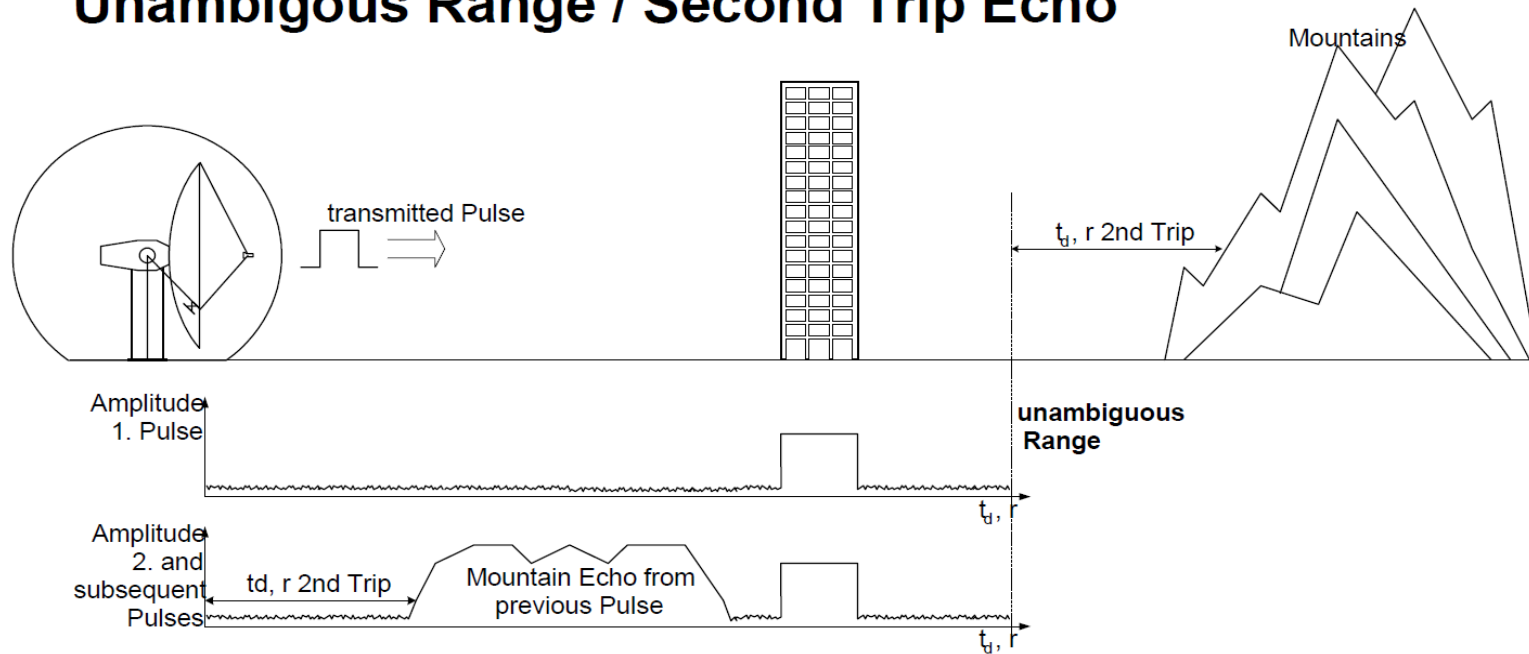


# Range Folding

**FOR LONGER RANGE – LOW PRF, HIGH PRT**

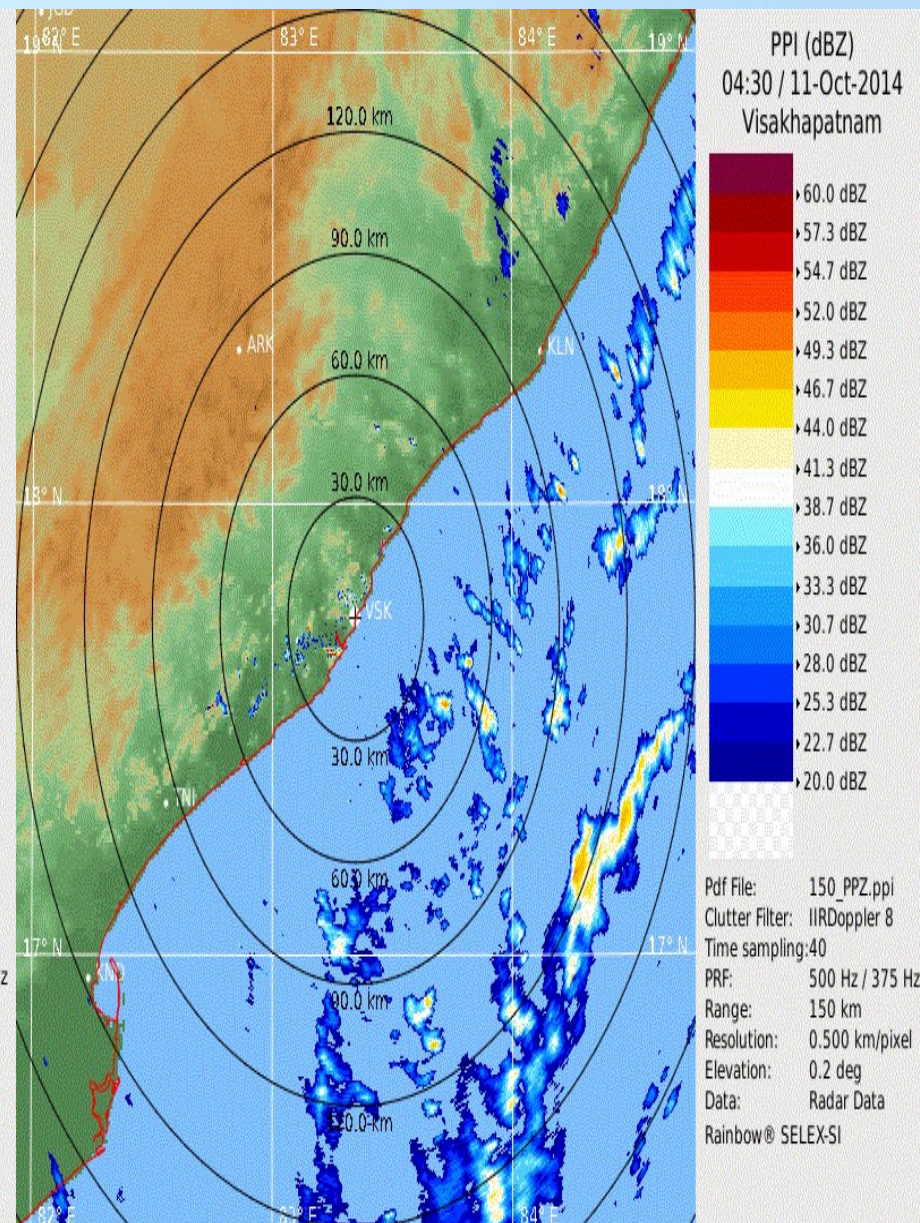
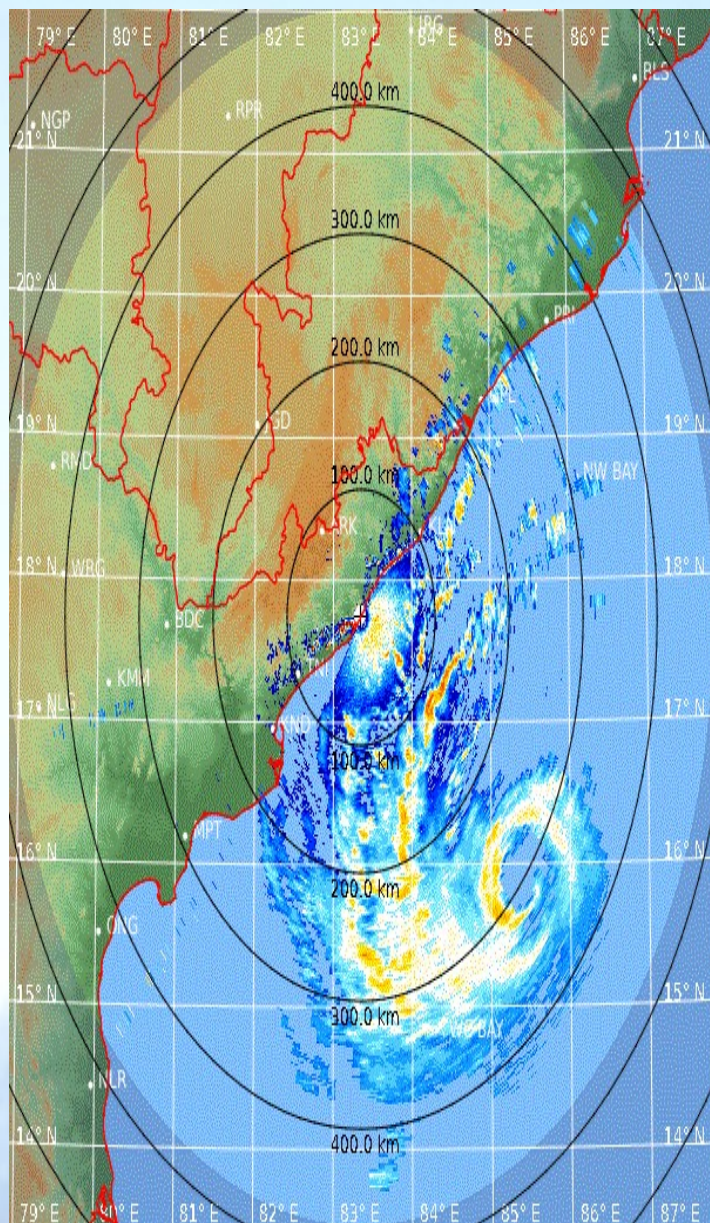
$$\text{Unambiguous Range} = \frac{c \times (\text{PRT})}{2} = \frac{c}{2 \times (\text{PRF})}$$

## Unambiguous Range / Second Trip Echo



Change PRF: second trip echo will shift position

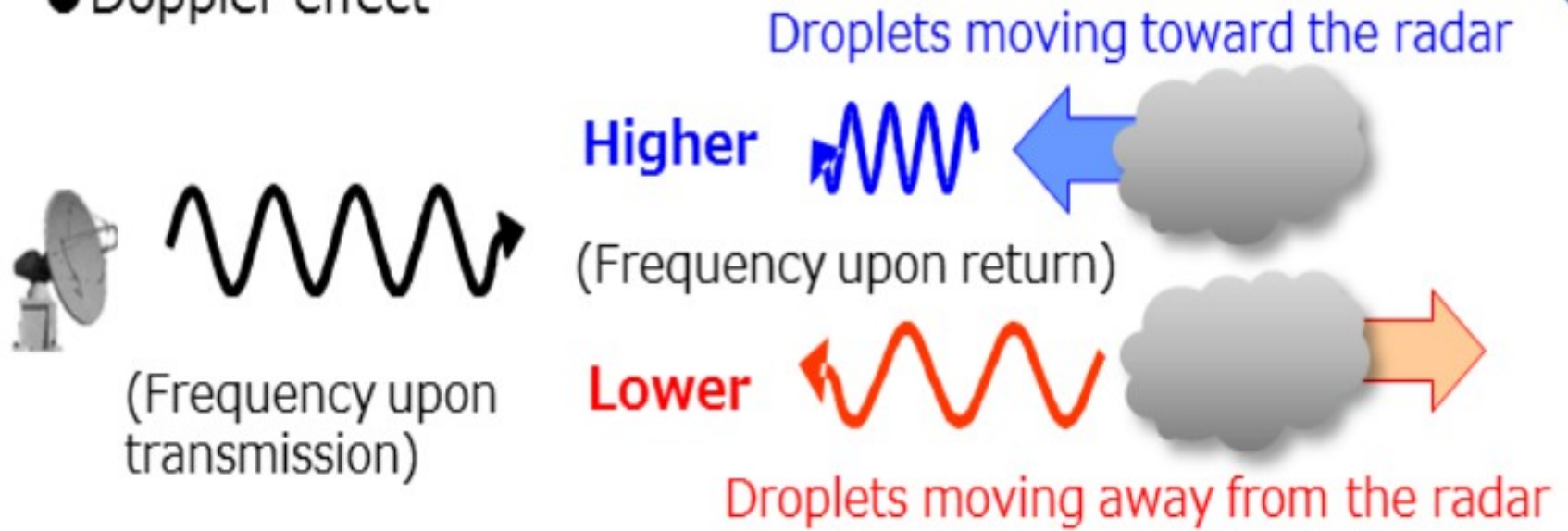






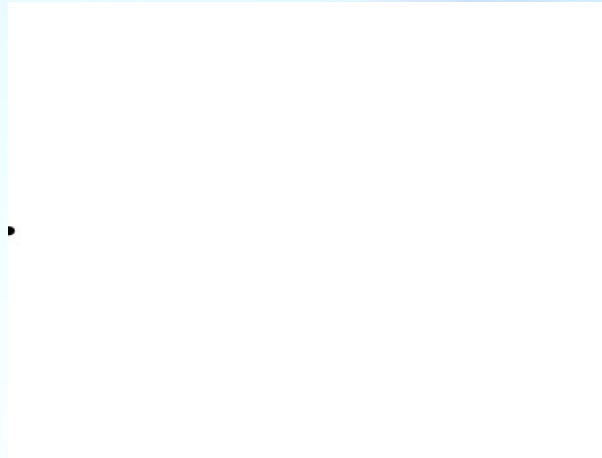
# Doppler radar principle

## ● Doppler effect

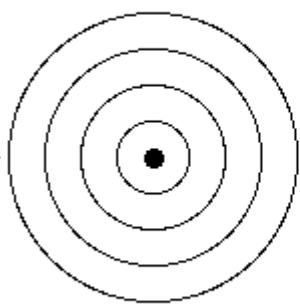


Based on the difference between transmission and return frequency, radar can be used to determine three-dimensional wind distribution in precipitation areas.

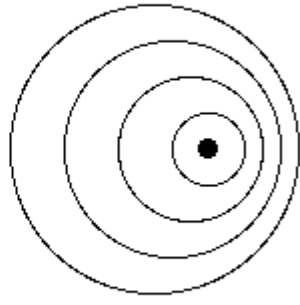
# Doppler radar principle



## Doppler Effect

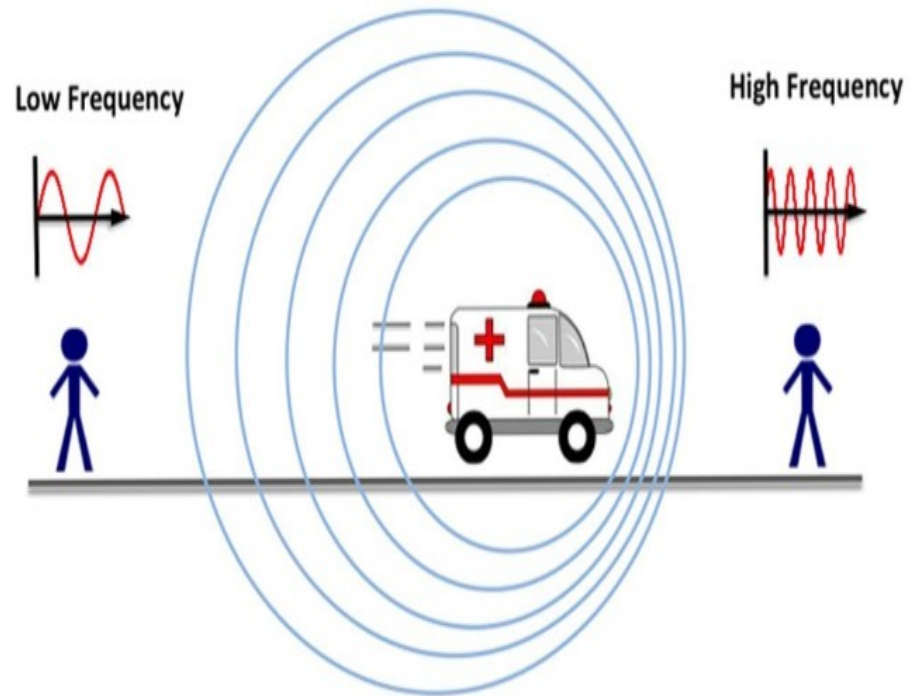


(a) stationary source

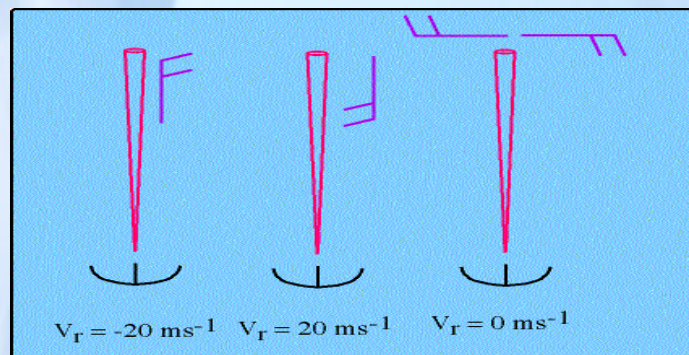
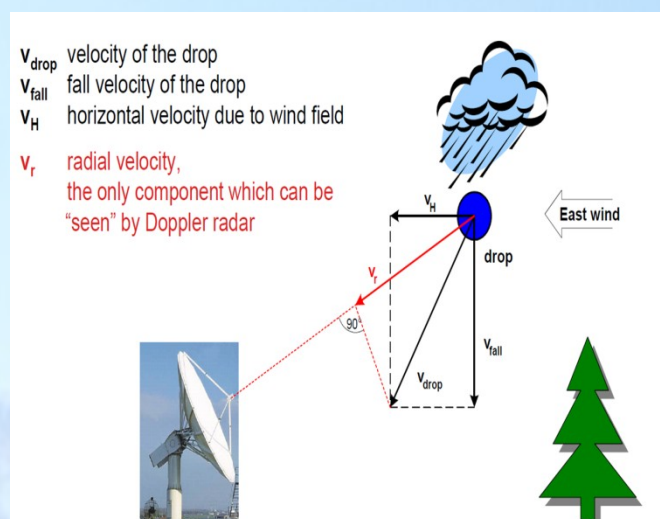
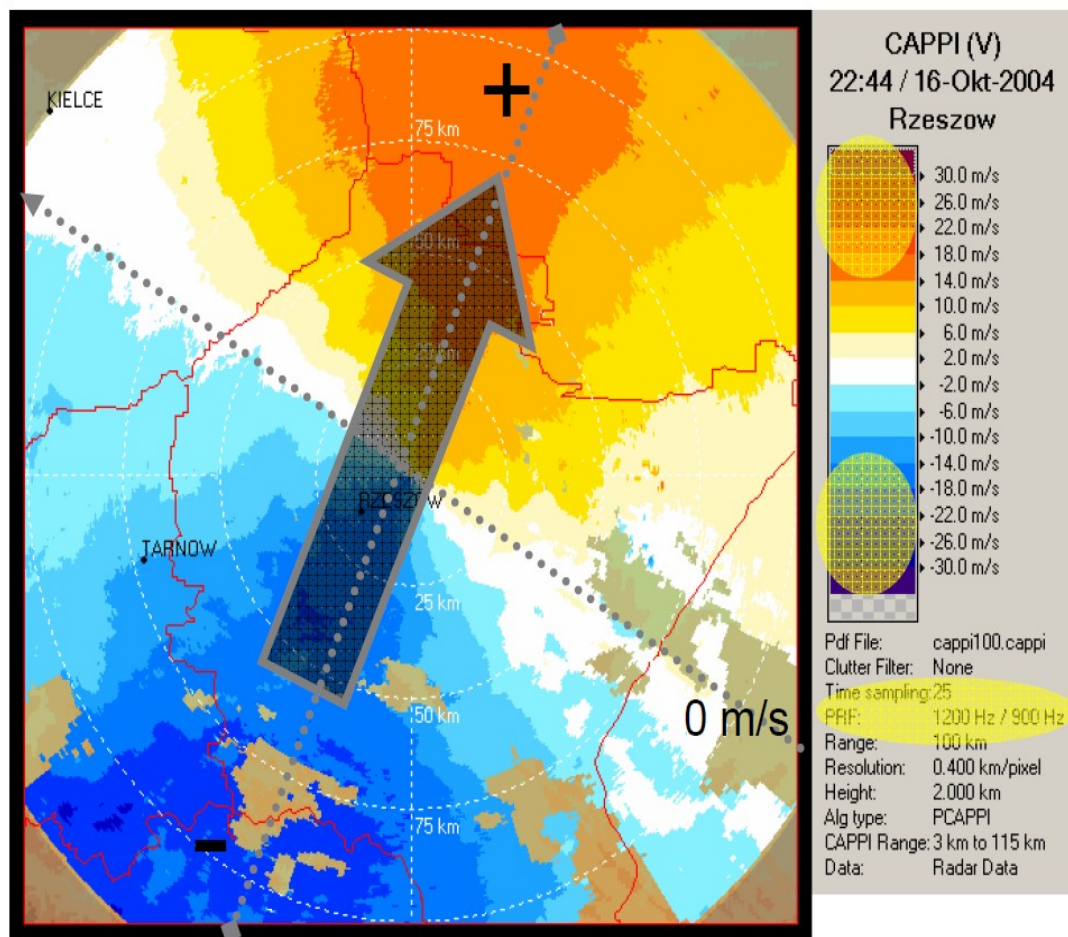


(b) moving source

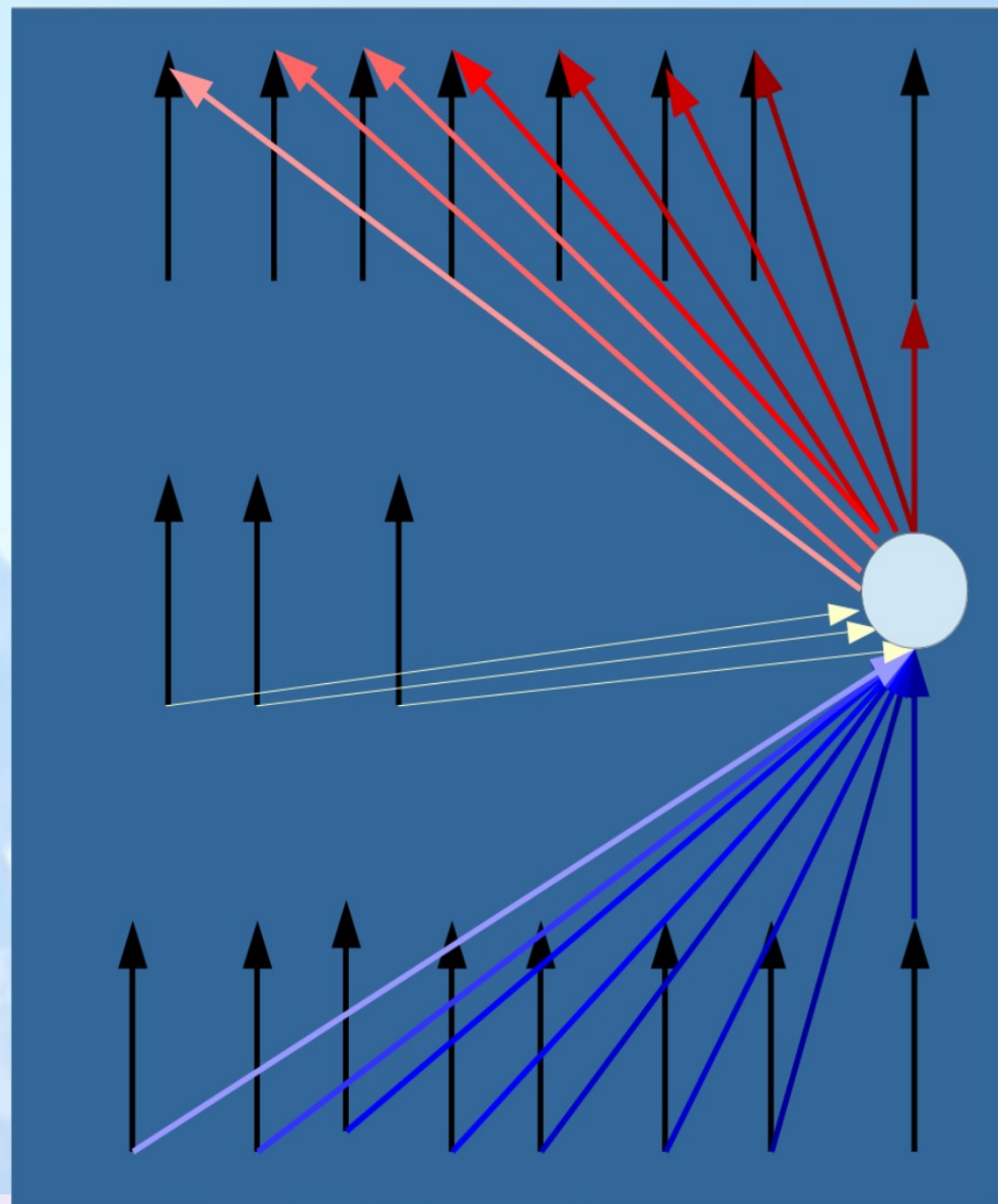
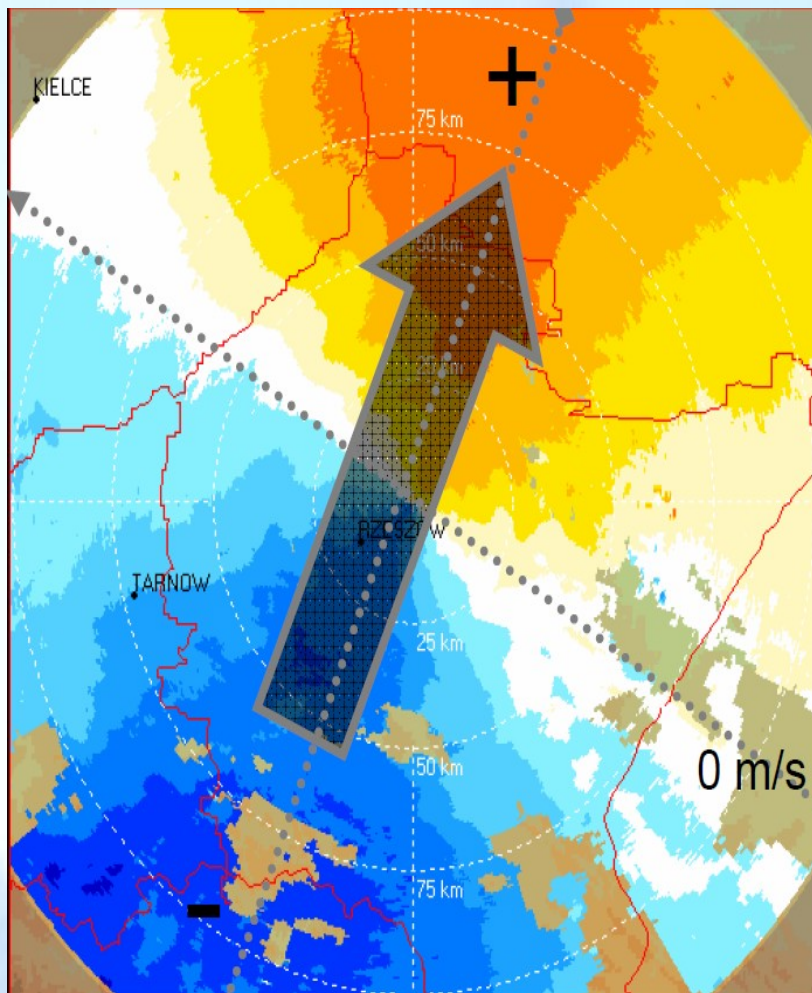
## Doppler's Effect



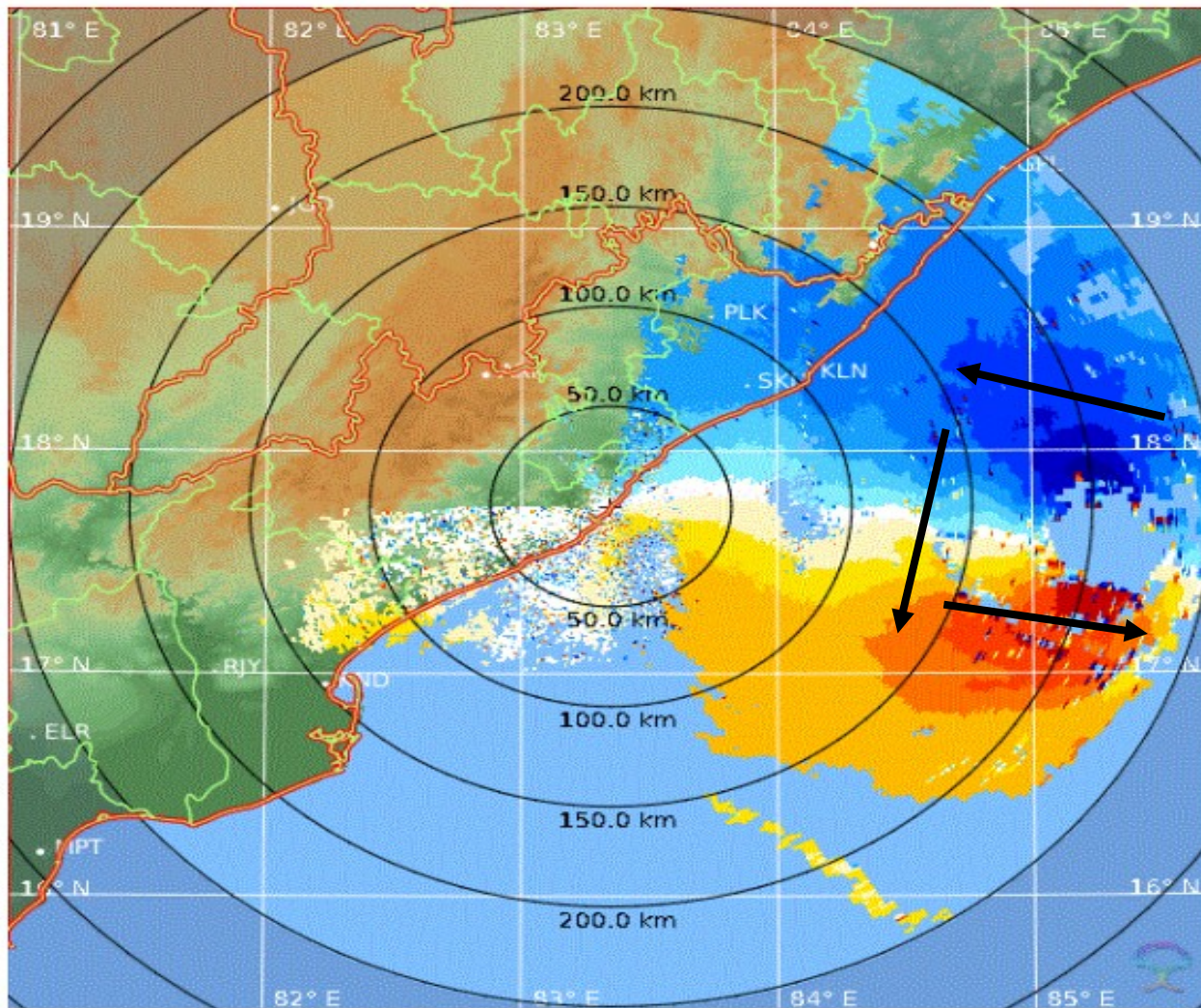
# PPI(V)



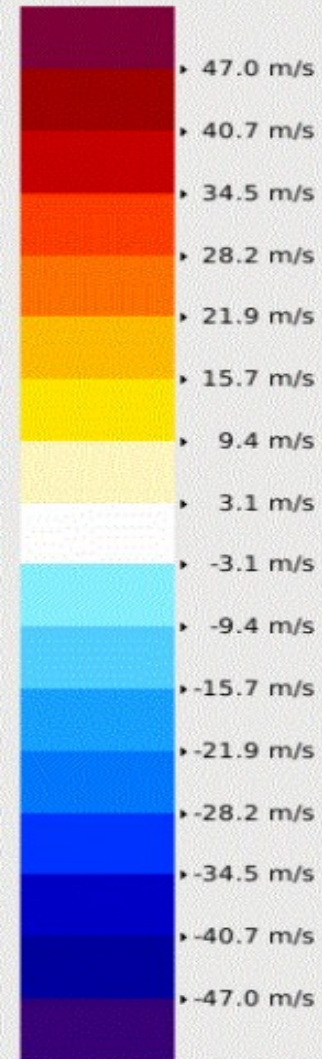


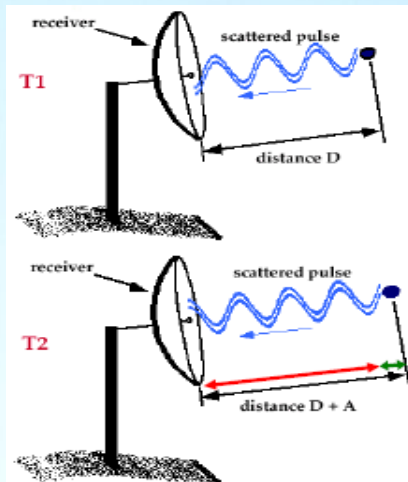






PPI (V)  
13:41 / 10-Oct-2018  
Visakhapatnam





Pulse at time **T1** is sent towards a target.

Another pulse at time **T2** is sent towards the same target.

→ Distance to target has changed, resulting in a phase shift  $\Delta\Phi$ .

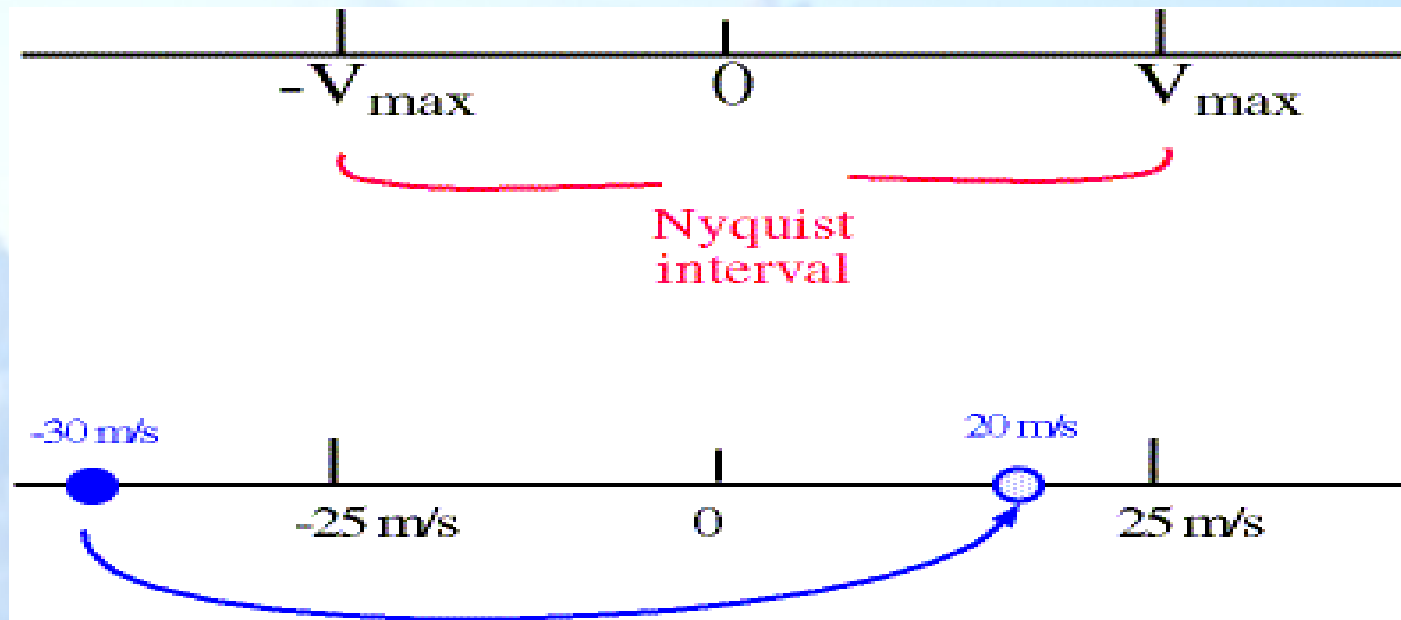
## Radial Velocity

From the phase shift  $\Delta\phi$  between two pulses (pulse repetition time  $\Delta t$ ) the radial velocity  $v_r$  can be derived:

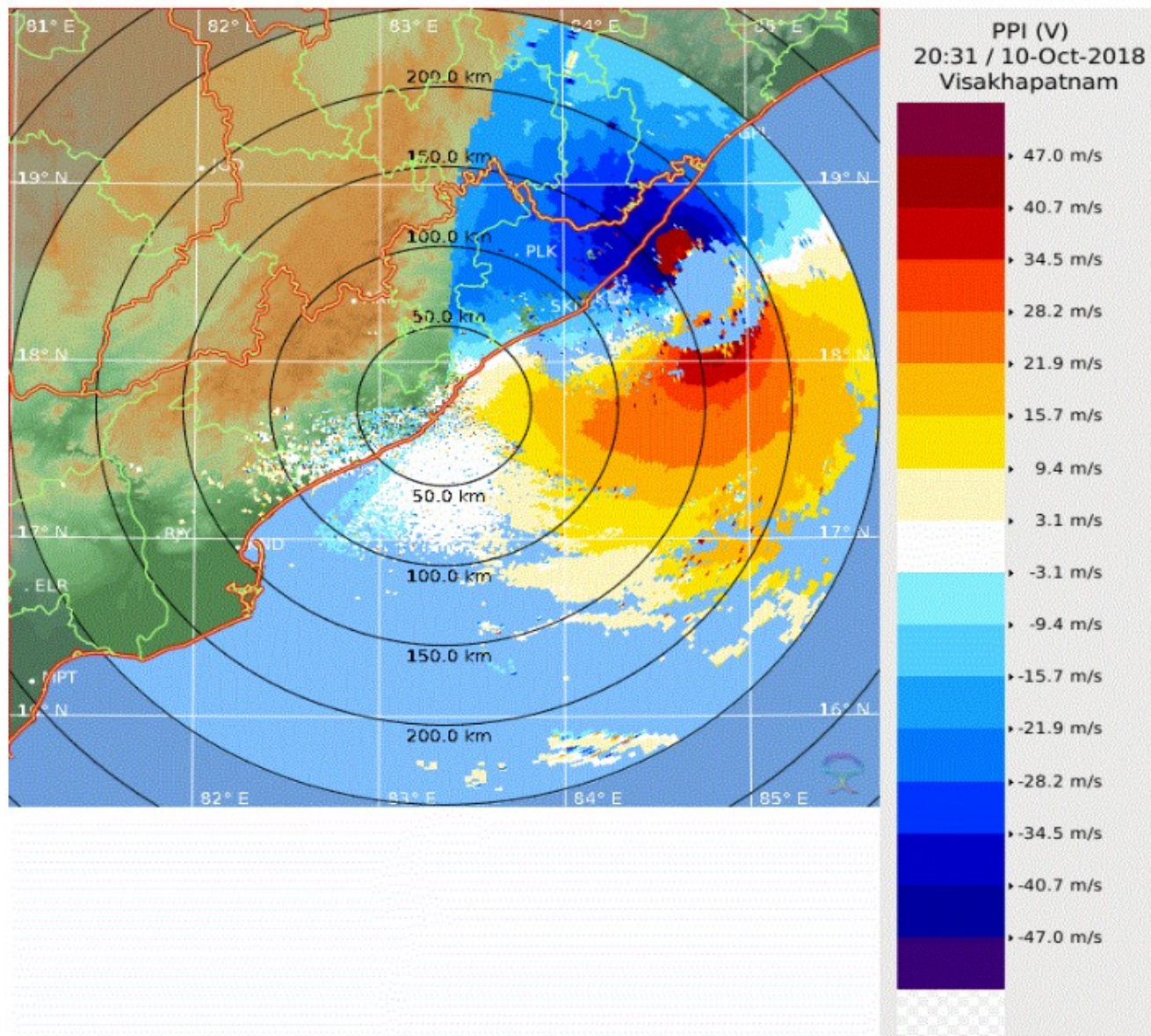
$$v_r = \frac{\Delta r}{\Delta t} = \frac{\lambda}{4\pi} \frac{\Delta\phi}{\Delta t}$$

# Velocity Folding

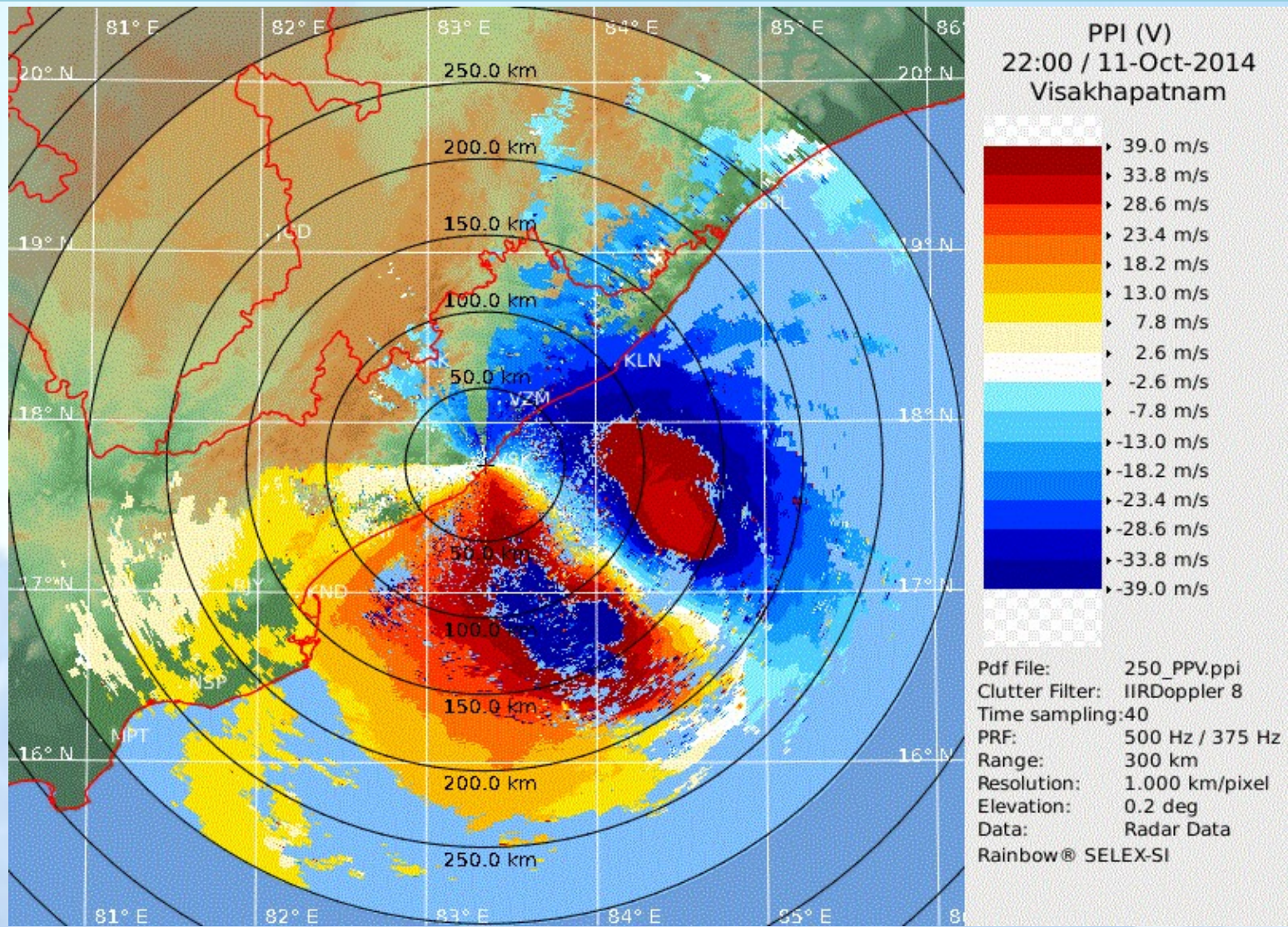
- If a particle's radial velocity is outside the range of the interval, then the radial velocity will be **aliased, or folded**. This is called **velocity folding/aliasing**.
- Example: if max velocity is -25 m/s and the particle's radial velocity is -30 m/s, then it will fold over and the radar will interpret it as +20 m/s -->>
- **$V_{\max}$  = Nyquist Velocity**

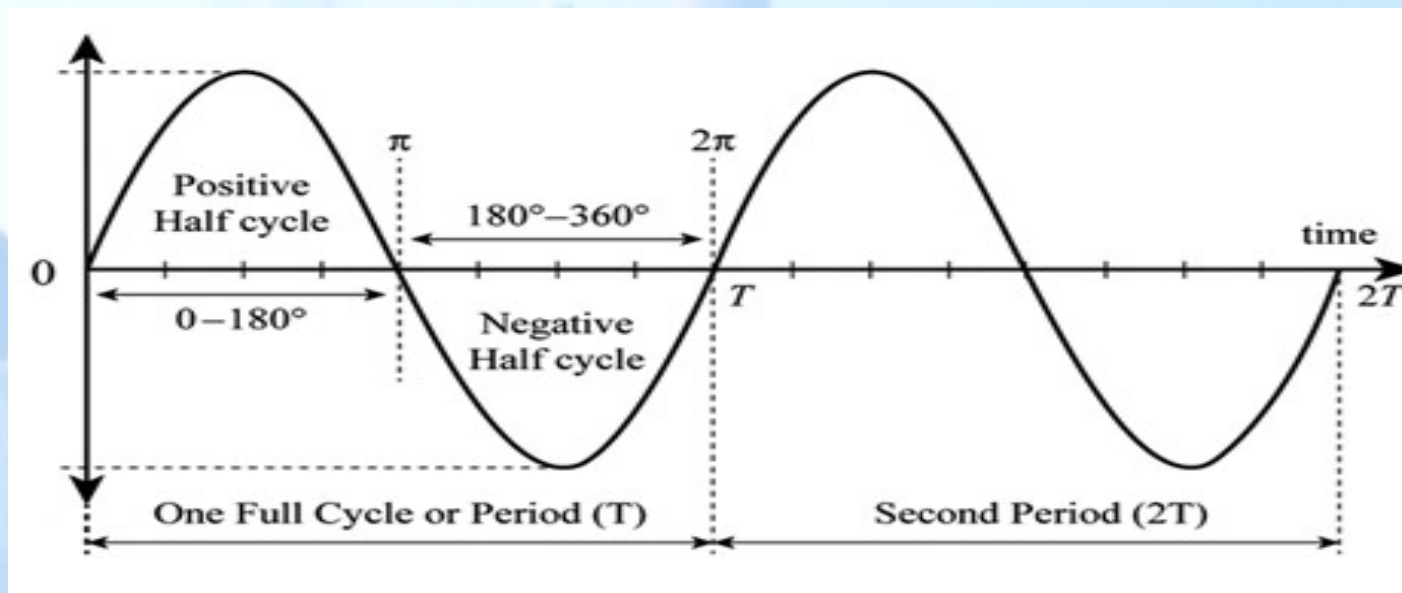
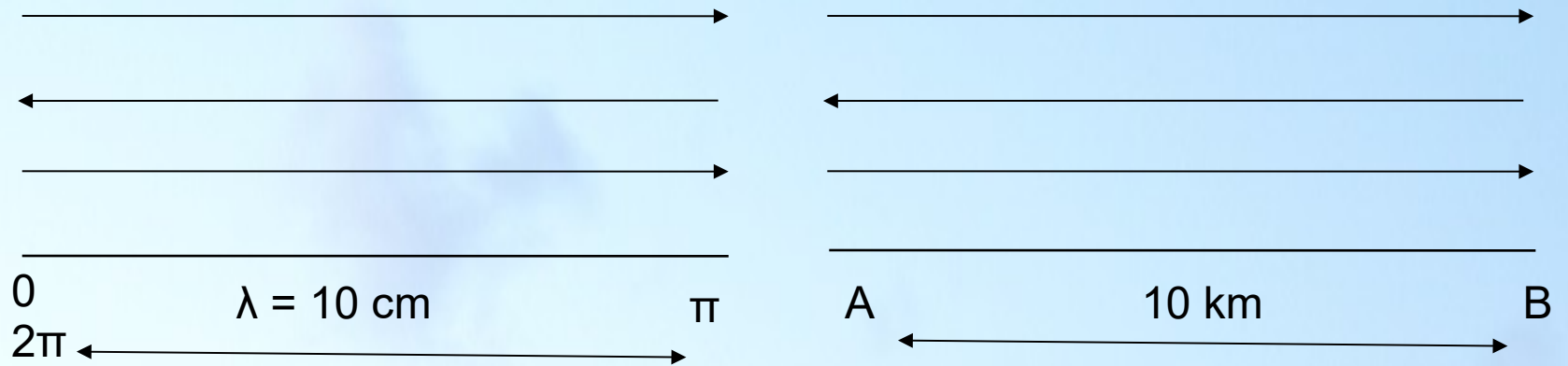






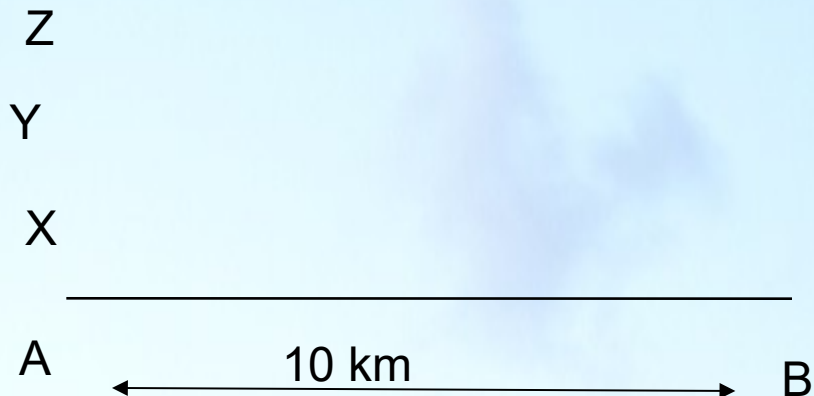




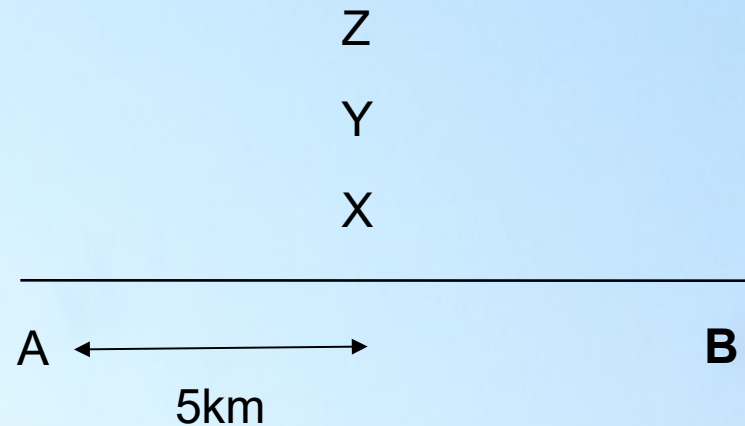




Time is 0 minutes

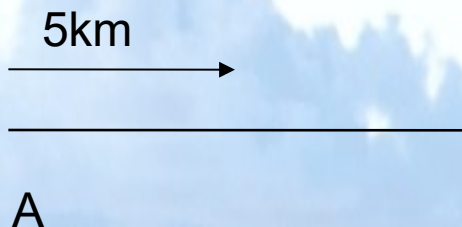


Time is 60 minutes

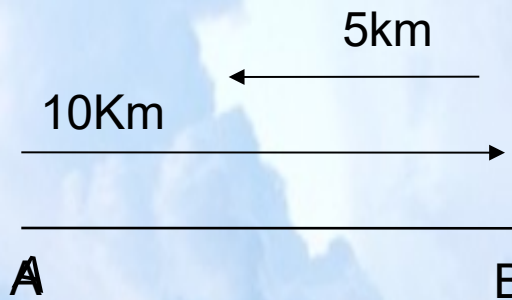


**SPEED OF X Y Z IS 5 Km/hr ?????**  
**UNAMBIGUOUS MAX SPEED IS ONLY 10KM/HR**

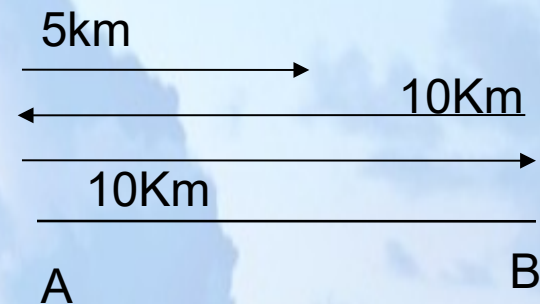
**X** 5km/hr



**Y** 15km/hr

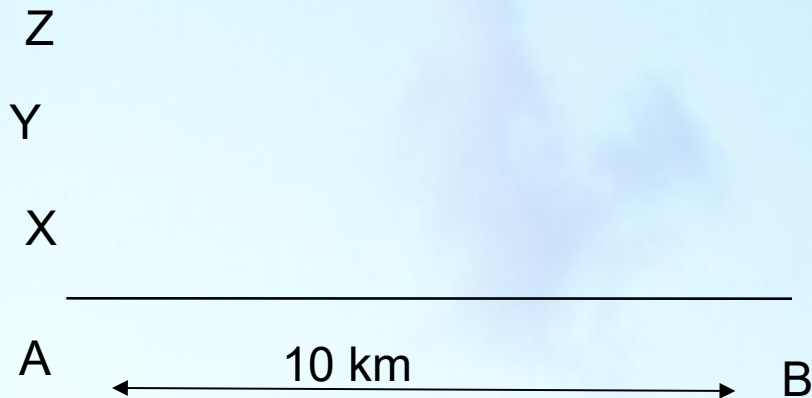


**Z** 25km/hr

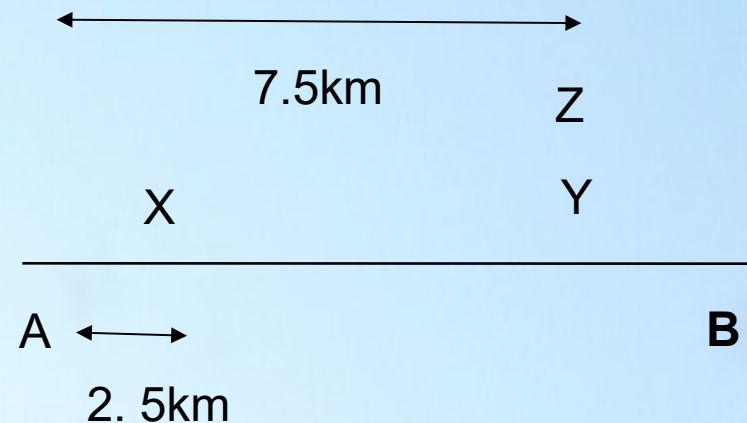




Time is 0 minutes



Time is 30 minutes



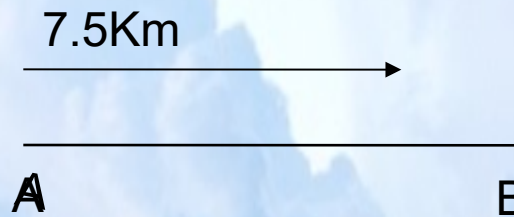
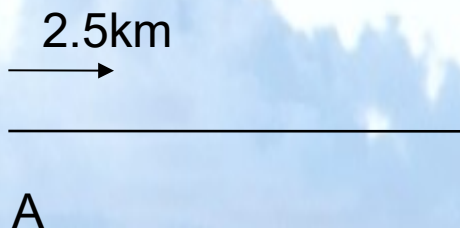
**SPEED OF Y Z IS 15 Km/hr ?????**

**UNAMBIGUOUS max SPEED is  $10\text{km}/0.5\text{ hr} = 20\text{ km/hr}$**

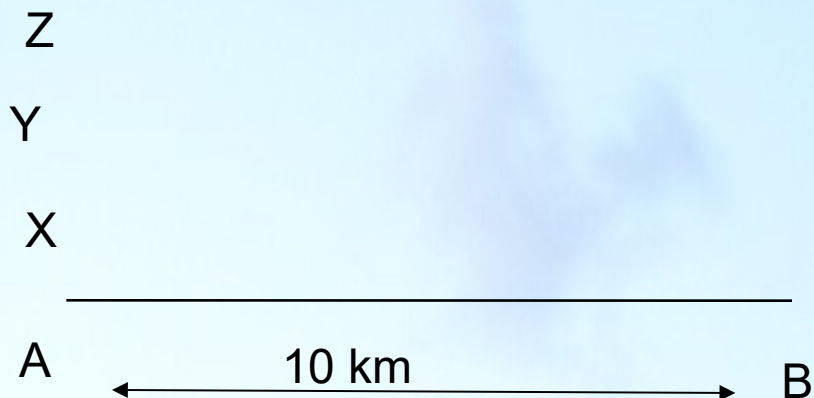
**X** 5km/hr

**Y** 15km/hr

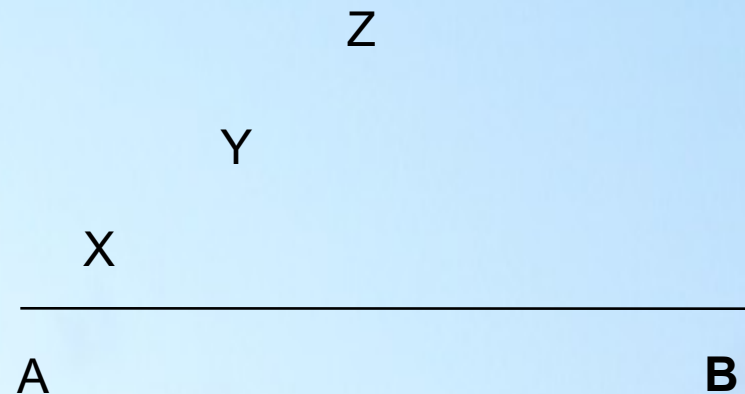
**Z** 25km/hr



Time is 0 minutes



Time is 15 minutes



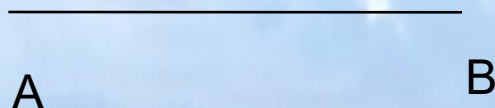
**SPEED OF X Y Z are not ambiguous**  
**UNAMBIGUOUS max SPEED is  $10\text{km}/0.25\text{ hr} = 40\text{ km/hr}$**

**X** 5km/hr

**Y** 15km/hr

**Z** 25km/hr

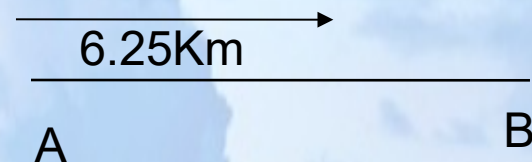
1.25km  
→



3.75Km  
→



6.25Km  
→



# DOPLER DILEMMA

**For Higher Velocity – High PRF, Low PRT**  
**For Longer Range – Low PRF, High PRT**

$$\text{Unambiguous Range} = \frac{c \times (PRT)}{2} = \frac{c}{2 \times (PRF)}$$

Maximum unambiguous Doppler velocity,  $v_{\max}$ , is

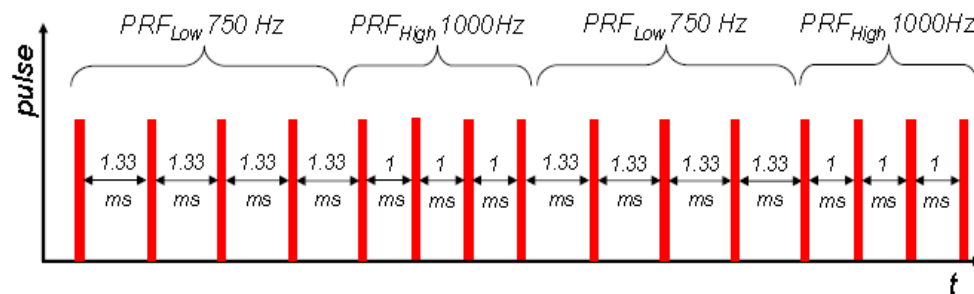
$$V_{\max} = \frac{PRF \cdot \lambda}{4}$$

$$V_{\max} \cdot r_{\max} = \frac{c \cdot \lambda}{8} = \text{const.}$$



# Techniques to manage velocity Folding

## Dual-PRF (Staggering)



Single-PRF

Dual-PRF

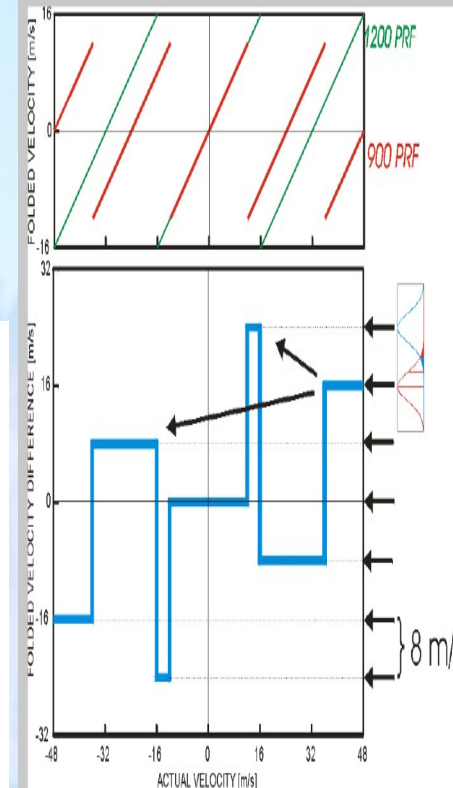
$$v_u = \frac{\lambda}{4 \cdot \Delta t} = \frac{\lambda}{4} PRF$$

$$v_u = \frac{\lambda}{4} PRF_{High} \cdot \frac{PRF_{Low}}{(PRF_{High} - PRF_{Low})}$$

## Unfolding method to extend unambiguous velocity:

PRF <sub>High</sub>	Stagg.	PRF <sub>Low</sub>	S-Band	C-Band	X-Band
1000 Hz	non	----	27 m/s	13 m/s	9 m/s
1000 Hz	3 : 2	667 Hz	54 m/s	27 m/s	18 m/s
1000 Hz	4 : 3	750 Hz	81 m/s	40 m/s	27 m/s
1000 Hz	5 : 4	800 Hz	108 m/s	54 m/s	36 m/s

## Dual PRF Unfolding



$$\text{Let } 2[V_m(h) - V_m(l)] = T$$

$$\text{Let } V_h - V_l = D$$

$$\text{If } D = 0 \text{ or } 3T, \\ V = V_h$$

$$\text{If } D = -T \text{ or } +2T,$$

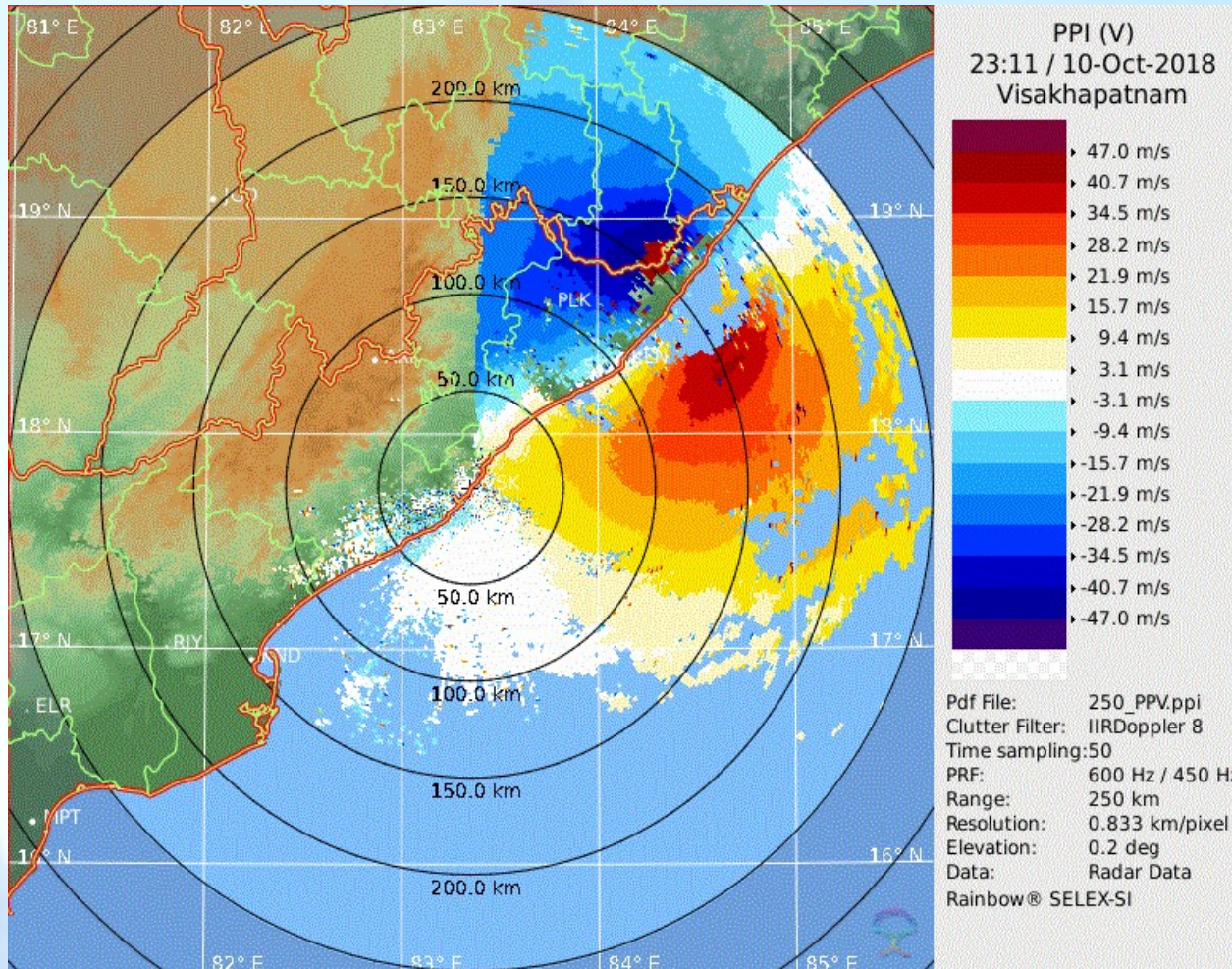
$$V = V_h + 2V_m(h)$$

$$\text{If } D = +T \text{ or } -2T,$$

$$V = V_h - 2V_m(h)$$



# Manual unfolding



V max = -47 m/s  
= 169 km/hr for  
600/450Hz

1<sup>st</sup> Folding Max=  
340 km/hr

Cyclone cannot  
have wind speed to  
give 2<sup>nd</sup> folding

Manually convert  
the max velocity for  
Bulletin



Works for 1<sup>st</sup> Folding only

Unfolded velocity

=  $2V_{\text{max}} + \text{folded velocity}$

=  $-2V_{\text{max}} + \text{folded velocity}$

Cyclone Bulletin Tool Developed by DWR Machilipatnam Team

Radar Beam Height Calculator Distance and Bearing Doppler Velocity Unfolding

## Doppler Velocity Unfolding

Please enter the maximum radial velocity  m/s

Enter magnitude of folded velocity  m/s

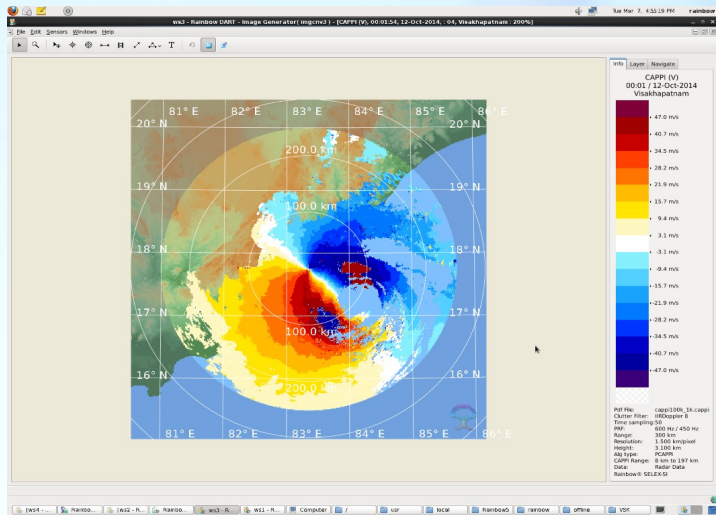
Unfolded Radial Velocity  m/s

[HELP](#) [Calculate Unfolded Velocity](#)

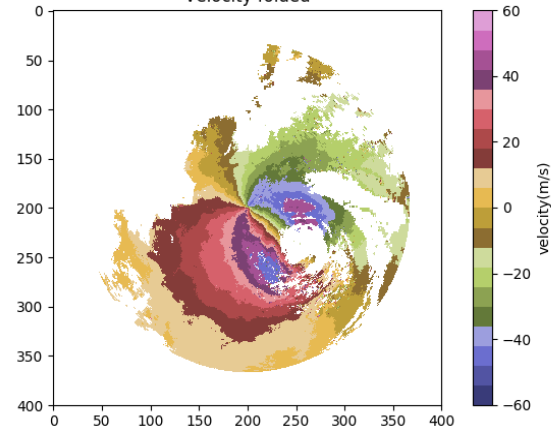




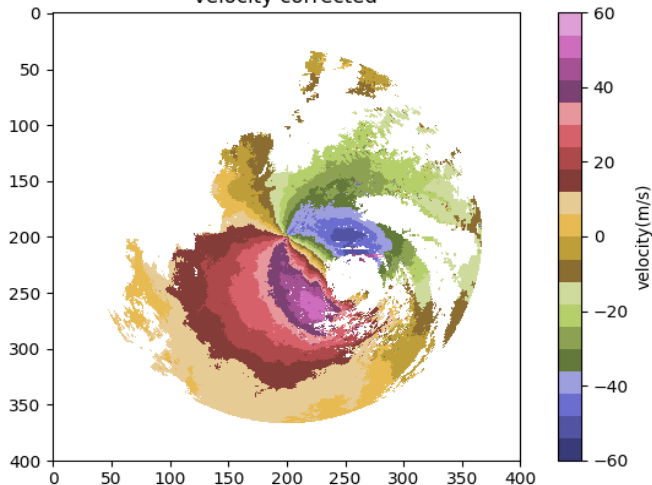
# Algorithms for de-aliasing



Visakhapatnam 00:01:54 2014-10-12 17.748133N 83.345592E  
Velocity folded



Visakhapatnam 00:01:54 2014-10-12 17.748133N 83.345592E  
velocity corrected



” De-aliasing velocity folding and estimation of surface wind speed in Cyclone using Doppler weather Radar products “ ,  
Bibraj R, K Ramachandra Rao , Journal of Polytechnics in Andhra Pradesh, 3(1), 51-55, 2019





# Spectrum width

The width of the Doppler power spectrum can tell us more about the scatterers:

The spread of the Doppler power spectrum, referred to as the **spectral width**, is found by computing the variance. The spectral width depends on:

1. the spread, range of terminal fall speeds of the scatterers (more pronounced for rain than for snow)

1. spectra for rain

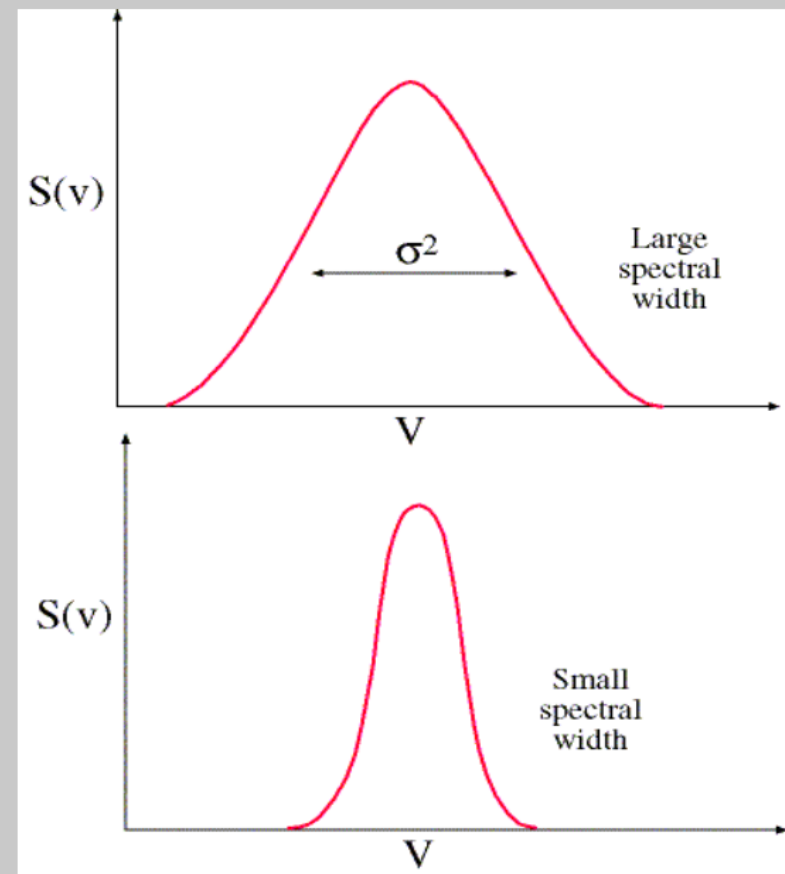
2. spectra for snow

2. turbulence of the air (upper levels in severe convection)

3. vertical wind shear (e.g., along a gust front)

4. antenna motion

Then, the total spectral width is due to the sum of the aforementioned effects



High Spectrum Width



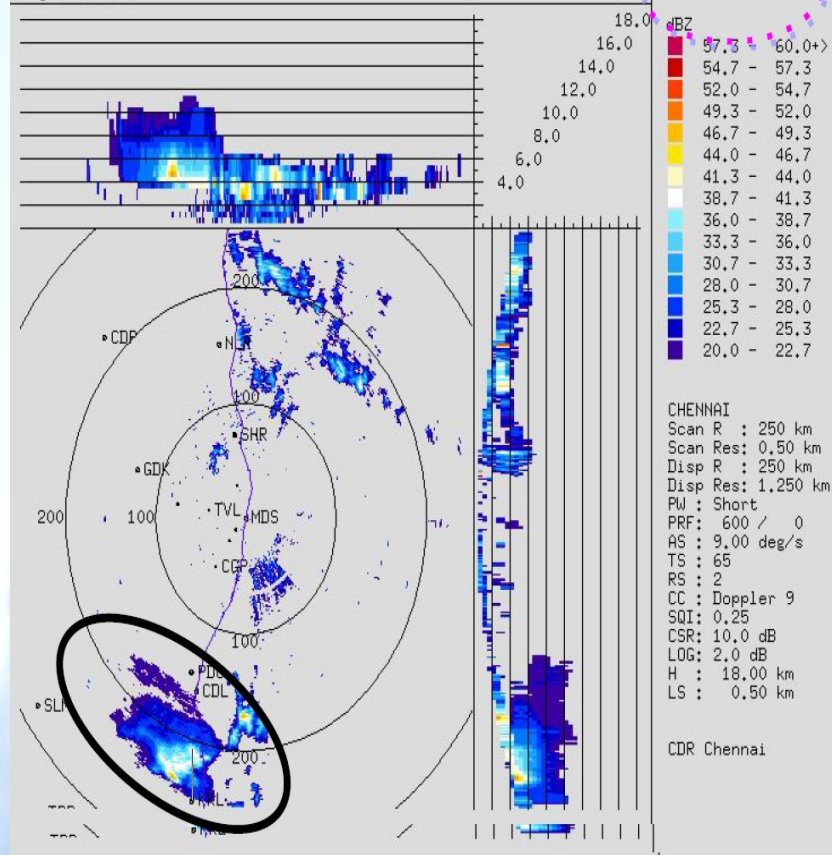
Low Spectrum Width





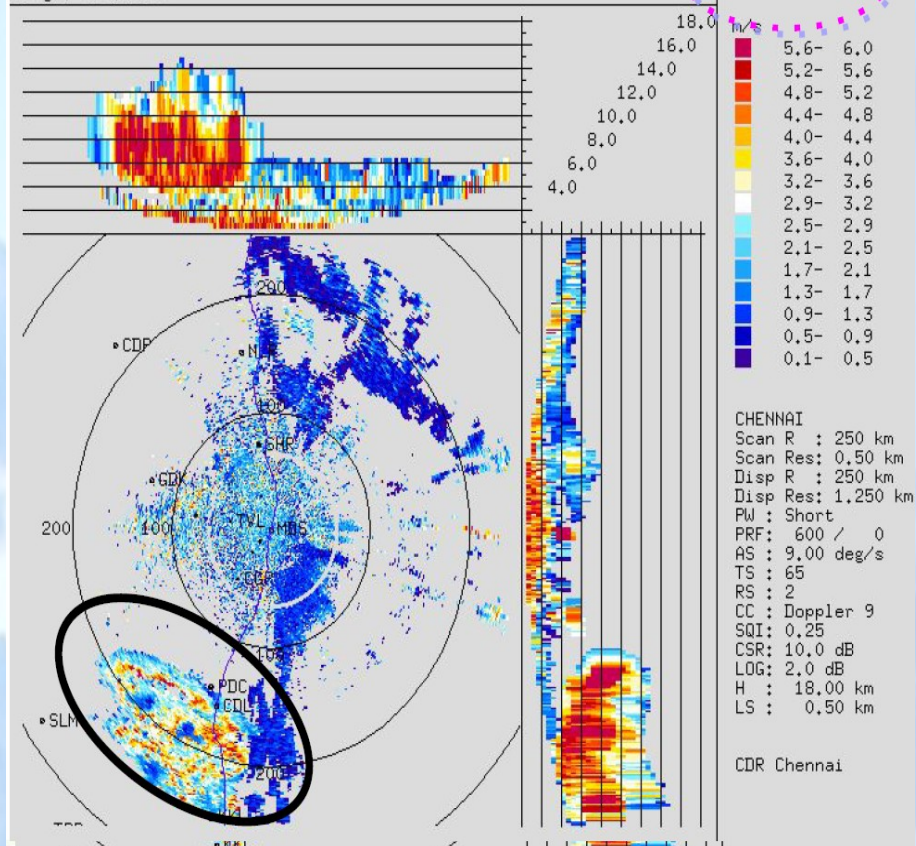
File : 2003051716432958.caz  
Type : MAX(Z)  
Range: 250.0 km

17.05.2003  
16:43:29



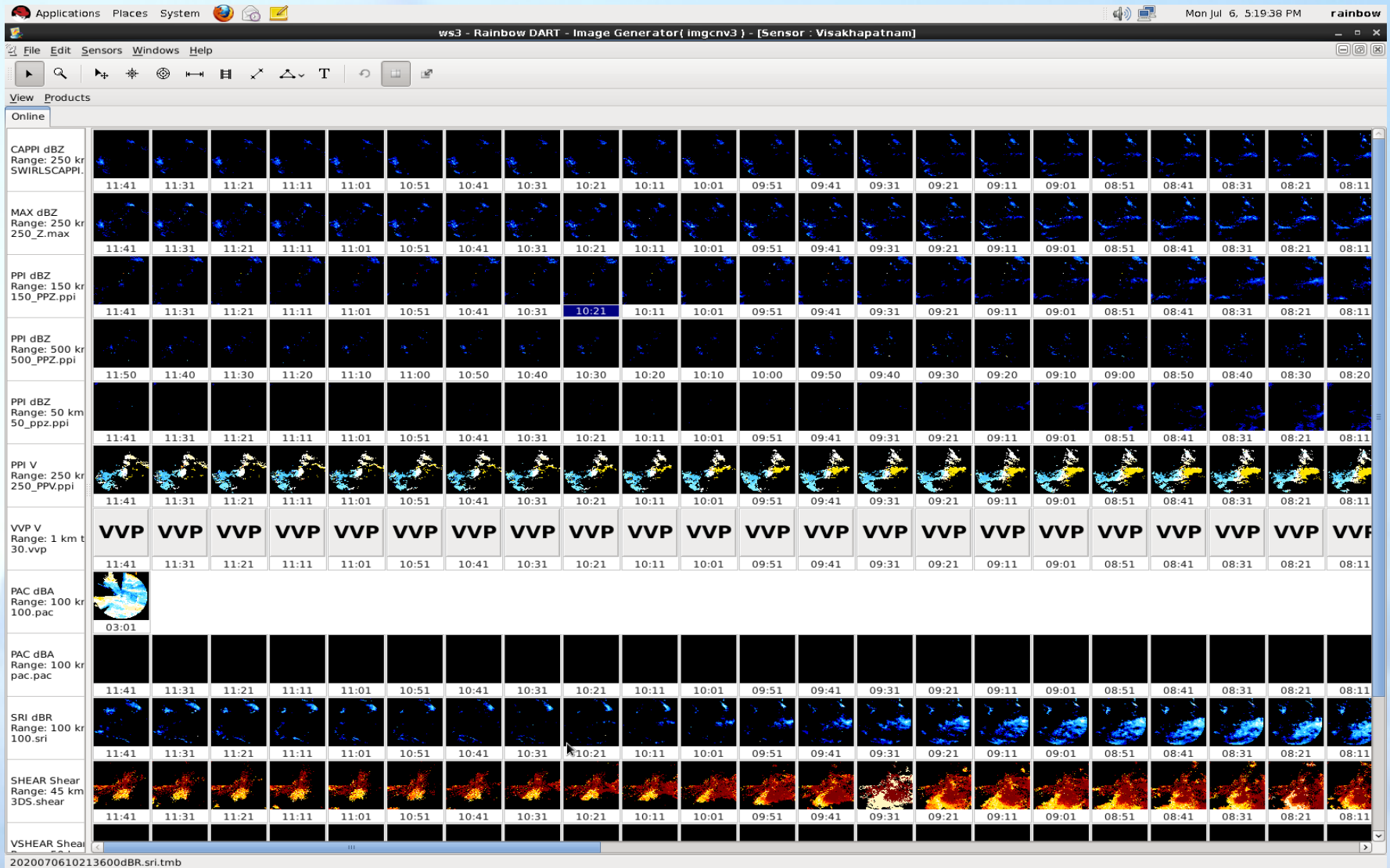
File : 2003051716432948.caw  
Type : MAX(W)  
Range: 250.0 km

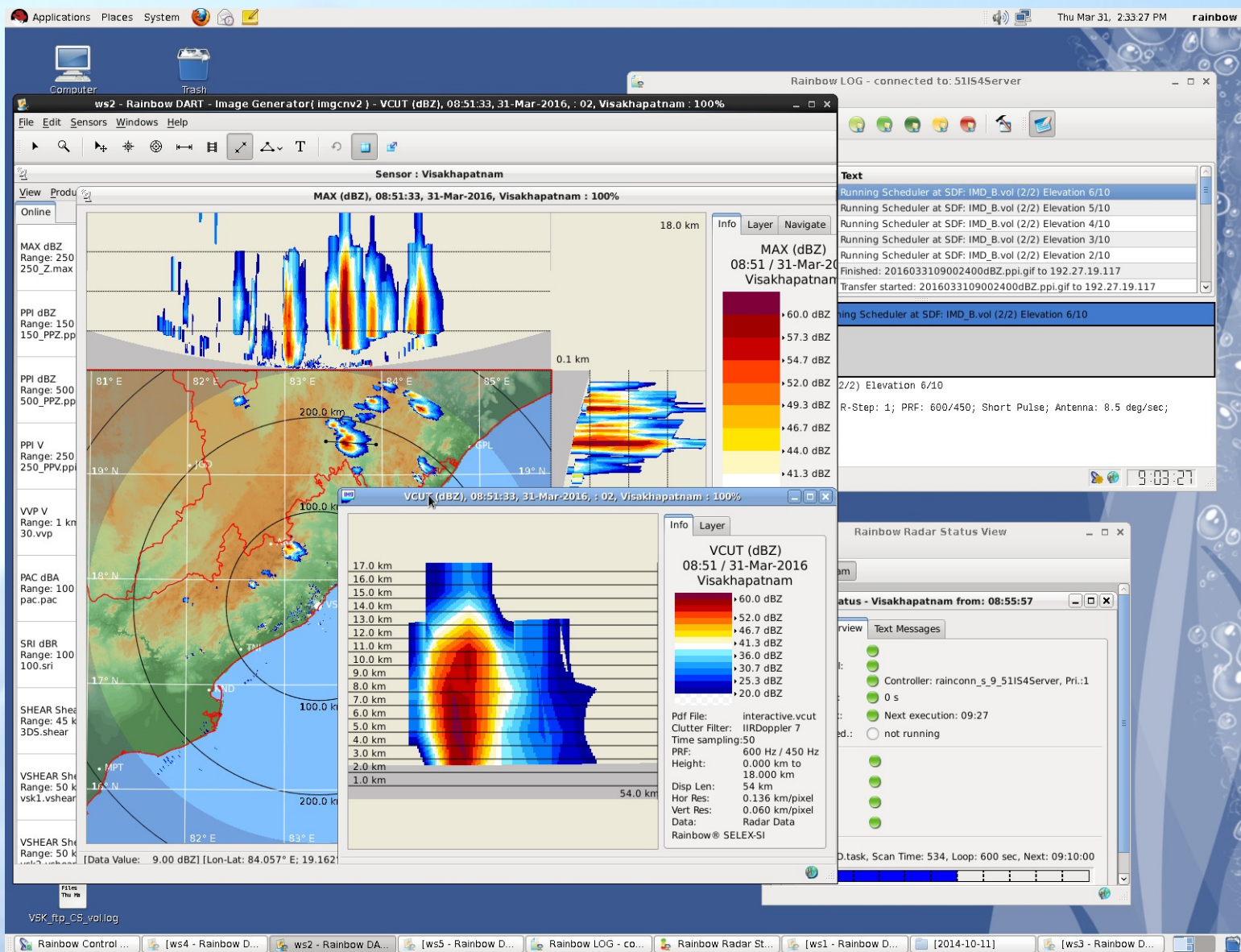
17.05.2003  
16:43:29





# Rainbow Software

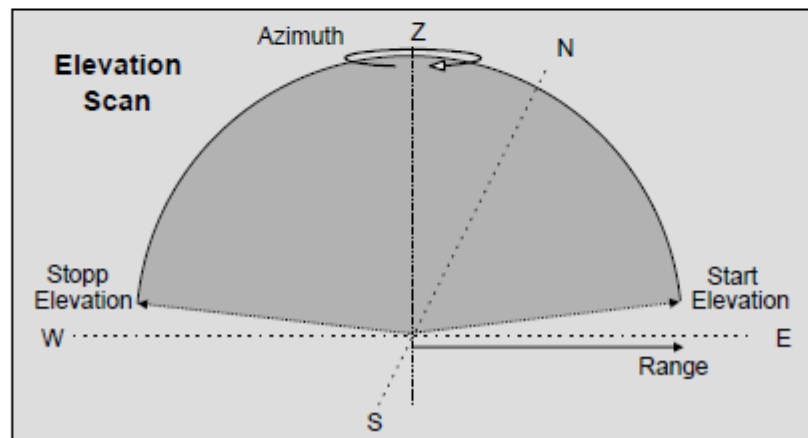
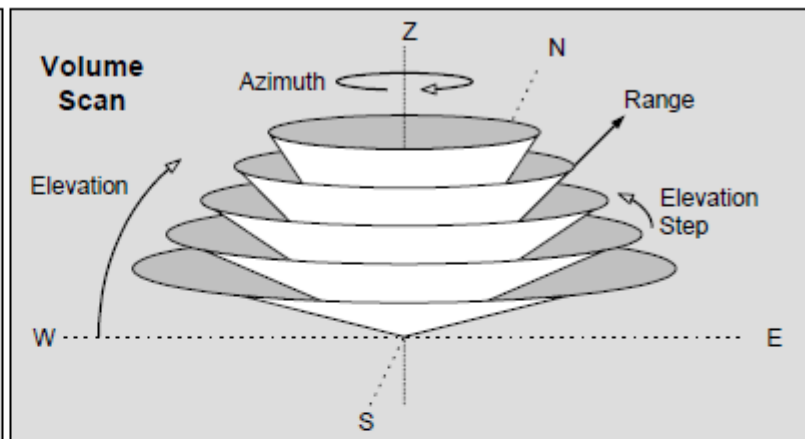
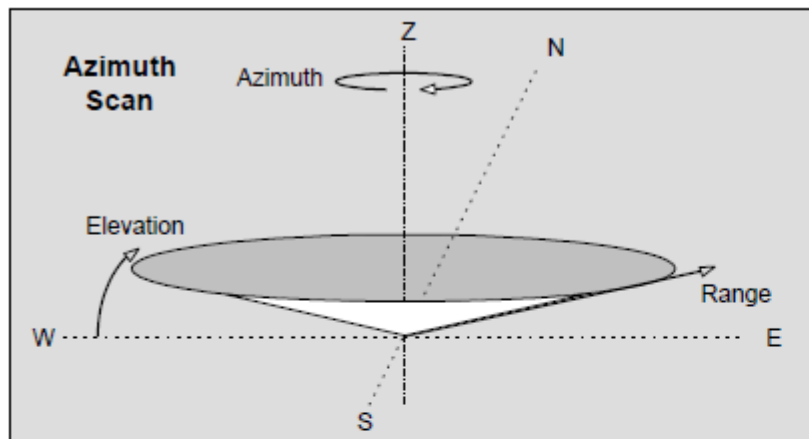






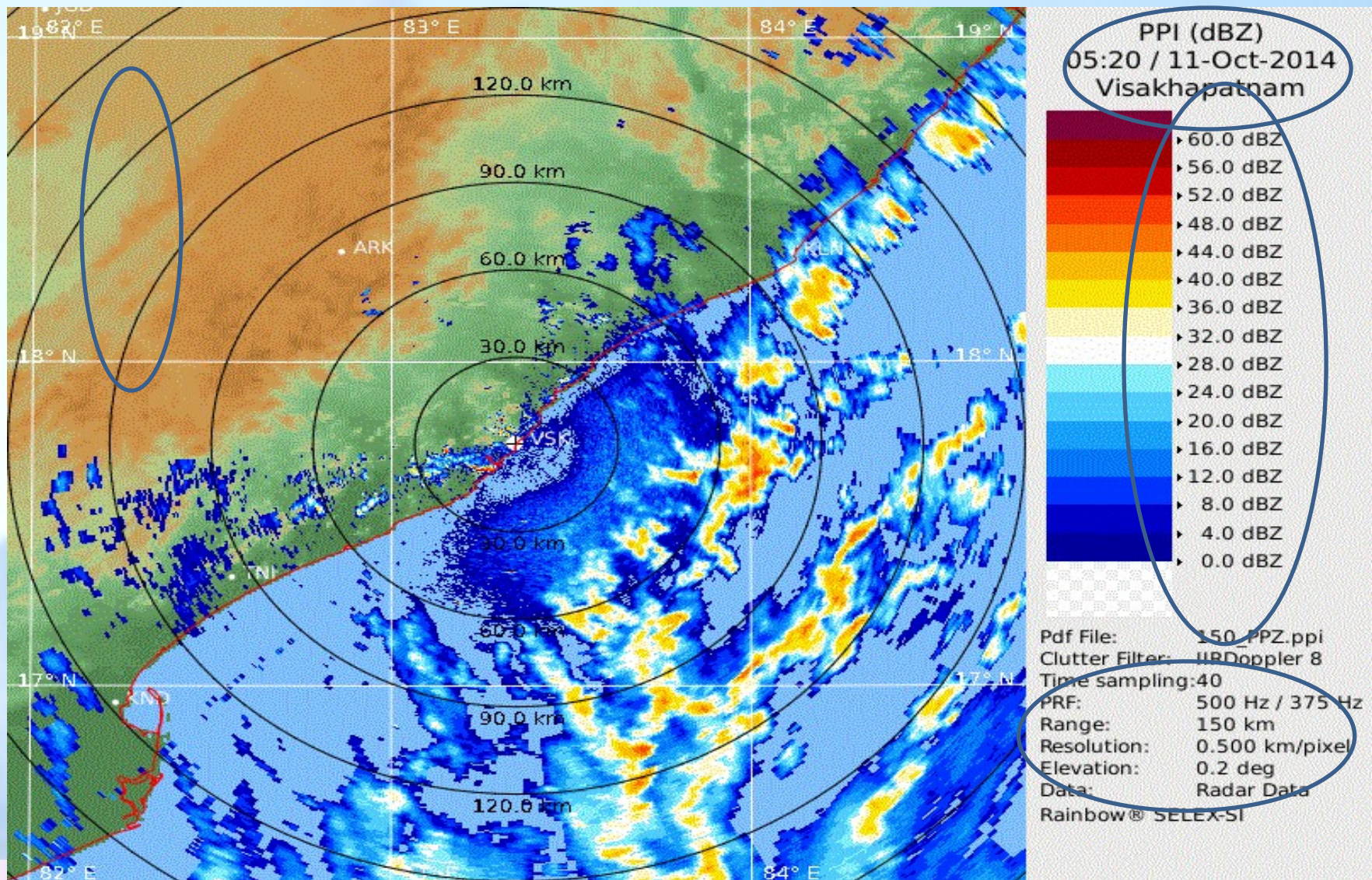


# Scan Types



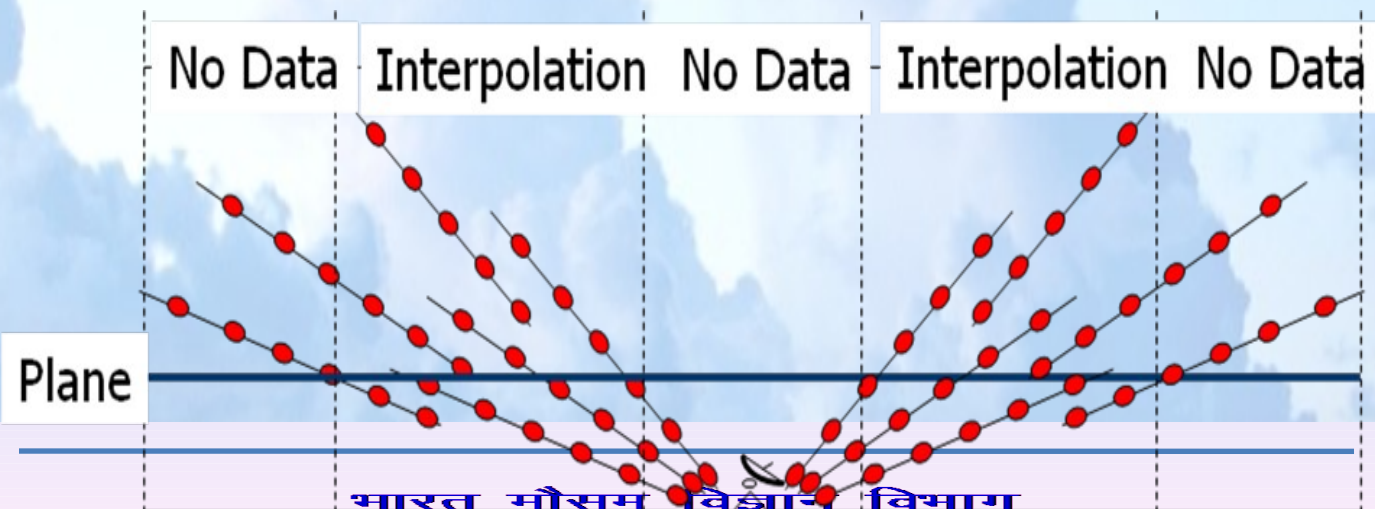
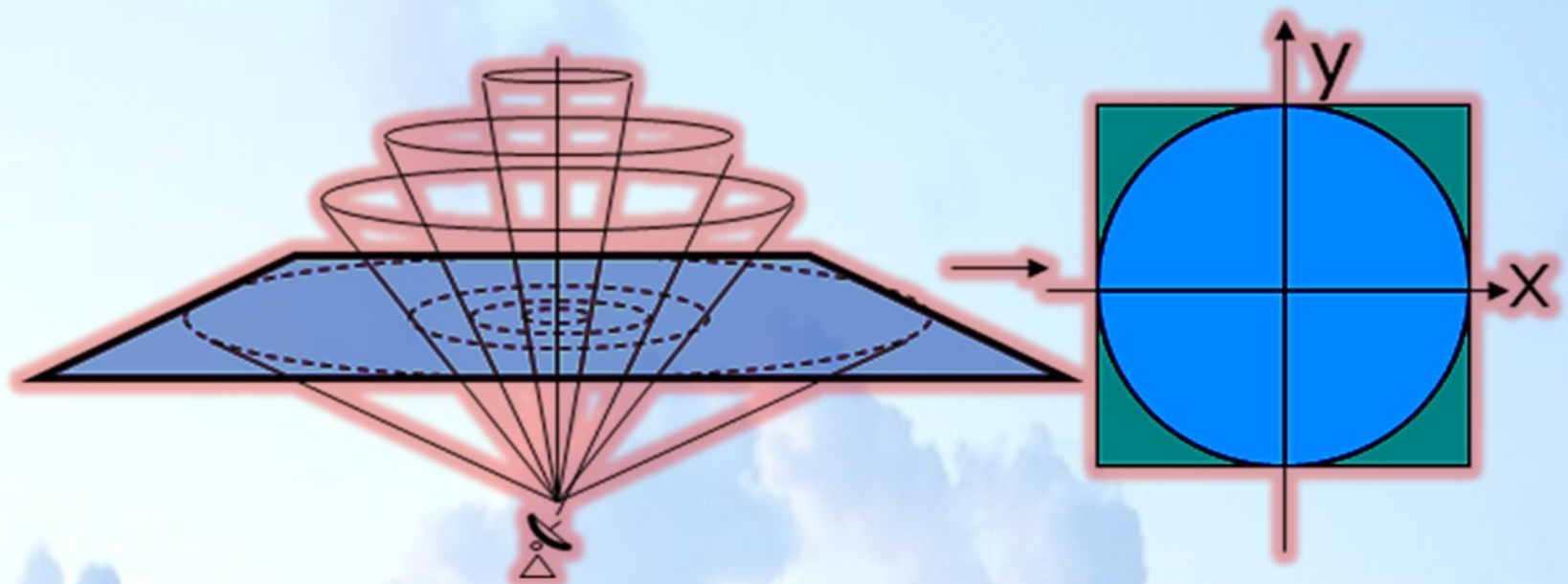


# PPI(dbZ)





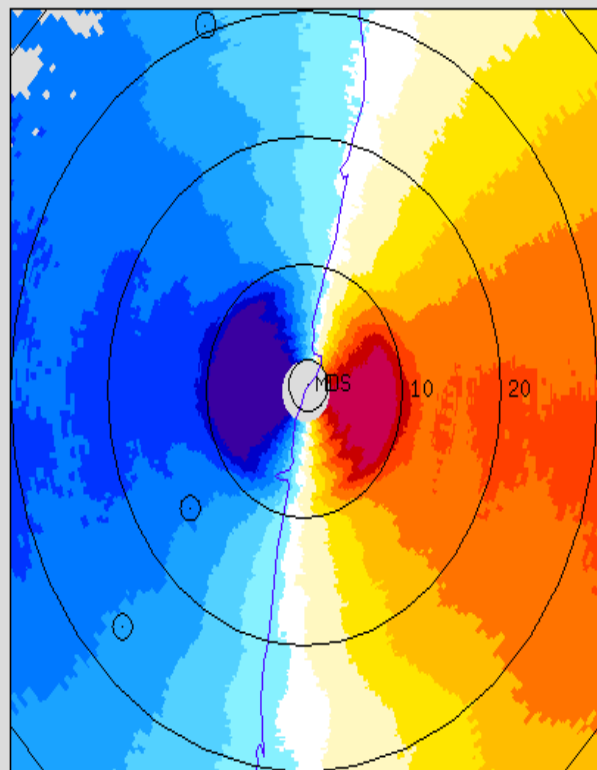
# Constant Altitude PPI





File : 2007061905303407.hcv  
Type : CAPPI(V)  
Range: 30.0 km

19.06.2007  
05:30:34



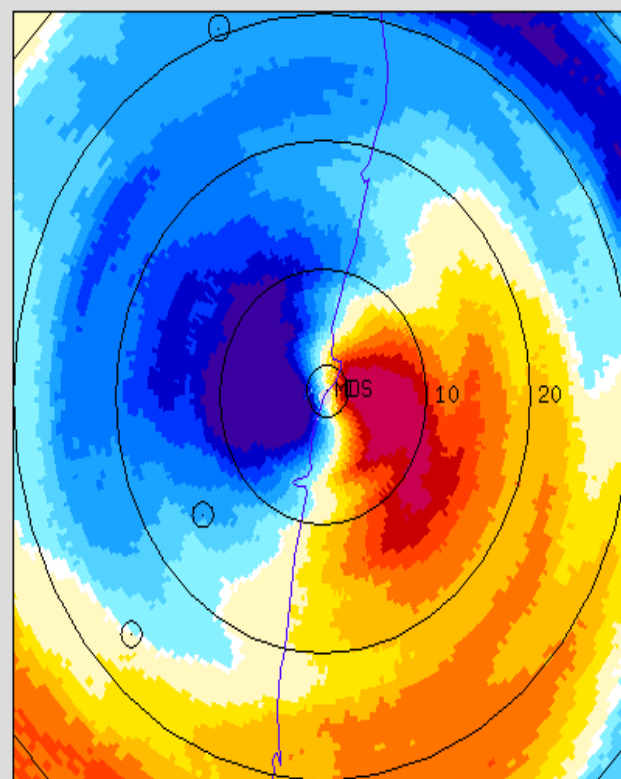
m/s  
13.0- 15.0  
11.0- 13.0  
9.0- 11.0  
7.0- 9.0  
5.0- 7.0  
3.0- 5.0  
1.0- 3.0  
-1.0- 1.0  
-3.0- -1.0  
-5.0- -3.0  
-7.0- -5.0  
-9.0- -7.0  
-11.0- -9.0  
-13.0- -11.0  
-15.0- -13.0

CHENNAI  
Scan R : 250 km  
Scan Res: 0.50 km  
Disp R : 30 km  
Disp Res: 0.150 km  
PW : Short  
PRF: 600 / 450  
AS : 8.50 deg/s  
TS : 39  
RS : 2  
CC : Doppler 8  
SQI: 0.35  
CSR: 15.0 dB  
LOG: 2.0 dB  
RoD: 2.4-42.5 km  
H : 1.00 km

CDR Chennai

File : 2007061905303430.ppv  
Type : PPI(V)  
Range: 30.0 km

19.06.2007  
05:30:34



m/s  
13.0- 15.0  
11.0- 13.0  
9.0- 11.0  
7.0- 9.0  
5.0- 7.0  
3.0- 5.0  
1.0- 3.0  
-1.0- 1.0  
-3.0- -1.0  
-5.0- -3.0  
-7.0- -5.0  
-9.0- -7.0  
-11.0- -9.0  
-13.0- -11.0  
-15.0- -13.0

CHENNAI  
Scan R : 250 km  
Scan Res: 0.50 km  
Disp R : 30 km  
Disp Res: 0.150 km  
PW : Short  
PRF: 600 / 450  
AS : 8.50 deg/s  
TS : 39  
RS : 2  
CC : Doppler 8  
SQI: 0.35  
CSR: 15.0 dB  
LOG: 2.0 dB  
AZ : 0.0-359.0  
EL : 9.0 deg

CDR Chennai

CAPPI

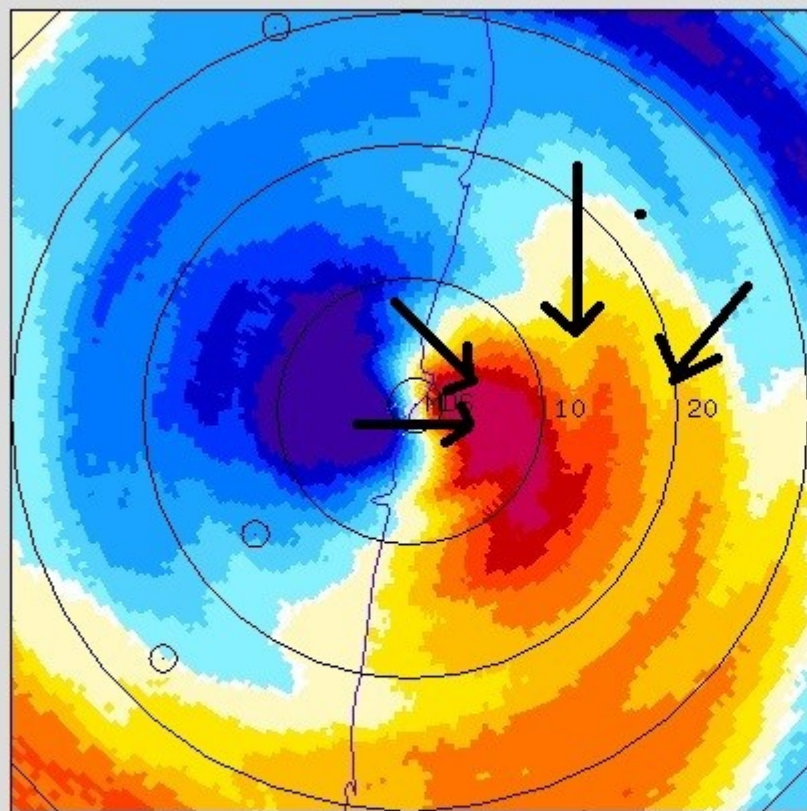
PPI



भारत मौसम विज्ञान विभाग  
INDIA METEOROLOGICAL DEPARTMENT



File : 2007061905303430.ppv  
 Type : PPI(V)  
 Range: 30.0 km



19.06.2007  
 05:30:34

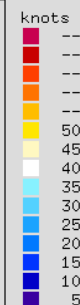
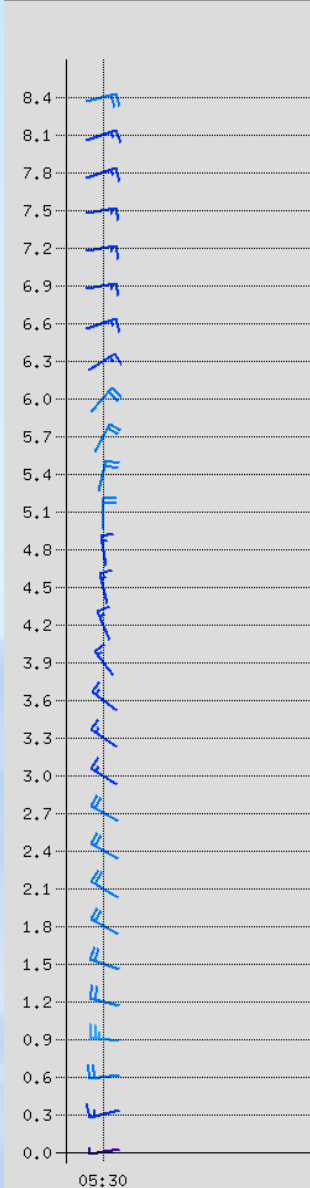


CHENNAI  
 Scan R : 250 km  
 Scan Res: 0.50 km  
 Disp R : 30 km  
 Disp Res: 0.150 km  
 PW : Short  
 PRF: 600 / 450  
 AS : 8.50 deg/s  
 TS : 39  
 RS : 2  
 CC : Doppler 8  
 SQI: 0.35  
 CSR: 15.0 dB  
 LOG: 2.0 dB  
 AZ : 0.0-359.0  
 EL : 9.0 deg

CDR Chennai

File : 2007061905303476.vp2  
 Type : VVP\_2  
 Range: 30.0 km

19.06.2007  
 05:30:34



CHENNAI  
 R : 30 km  
 PW : Short  
 PRF: 600 / 450  
 AS : 8.50 deg/s  
 TS : 39  
 RS : 2  
 CC : Doppler 8  
 SQI: 0.35  
 CSR: 15.0 dB  
 LOG: 2.0 dB  
 NPAR: 9  
 MAXH: 8.50 km  
 MINH: 0.00 km  
 LS : 0.30 km

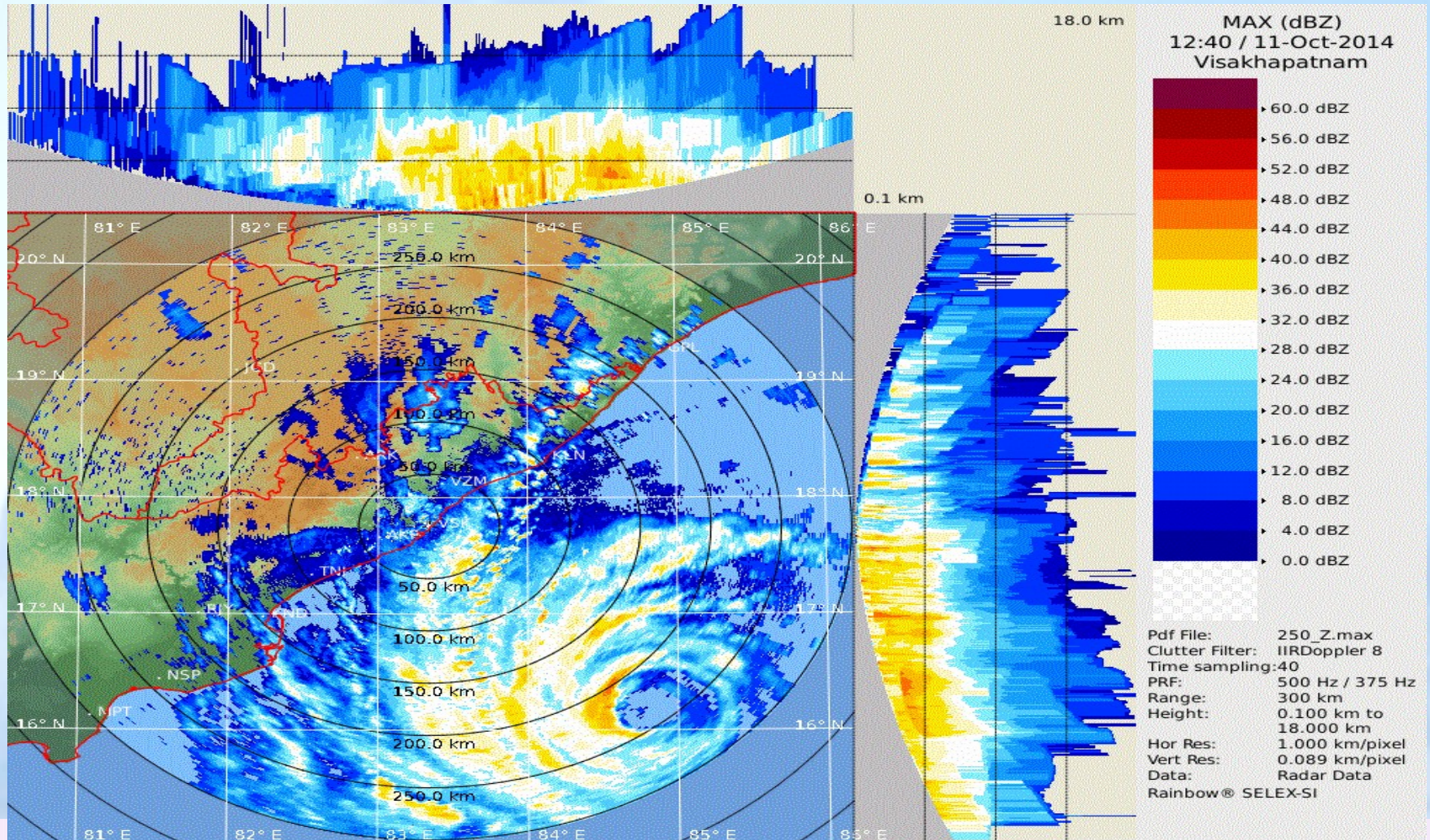
CDR Chennai

05:30



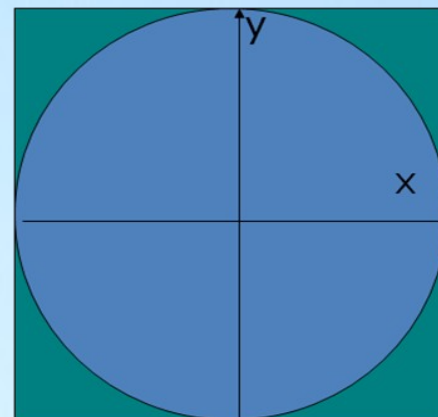
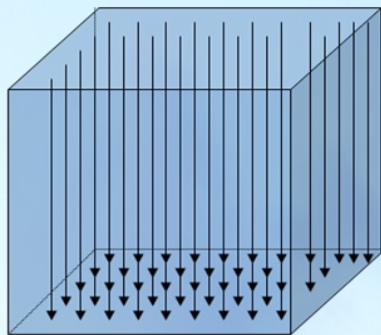


# Max(Z)

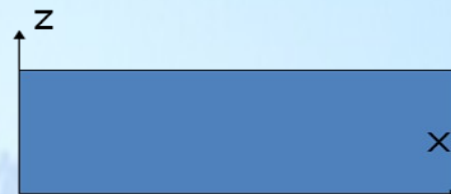
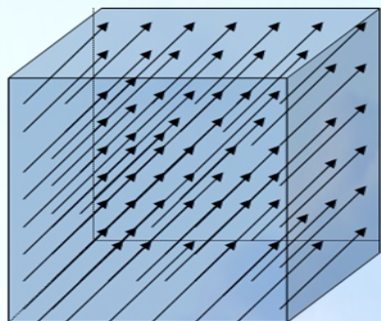




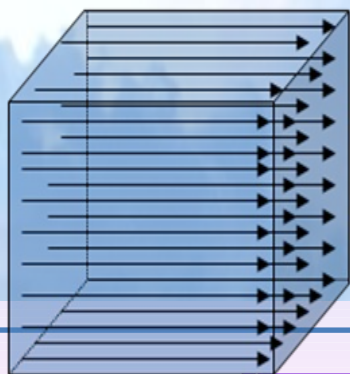
TOP VIEW



N-S VIEW



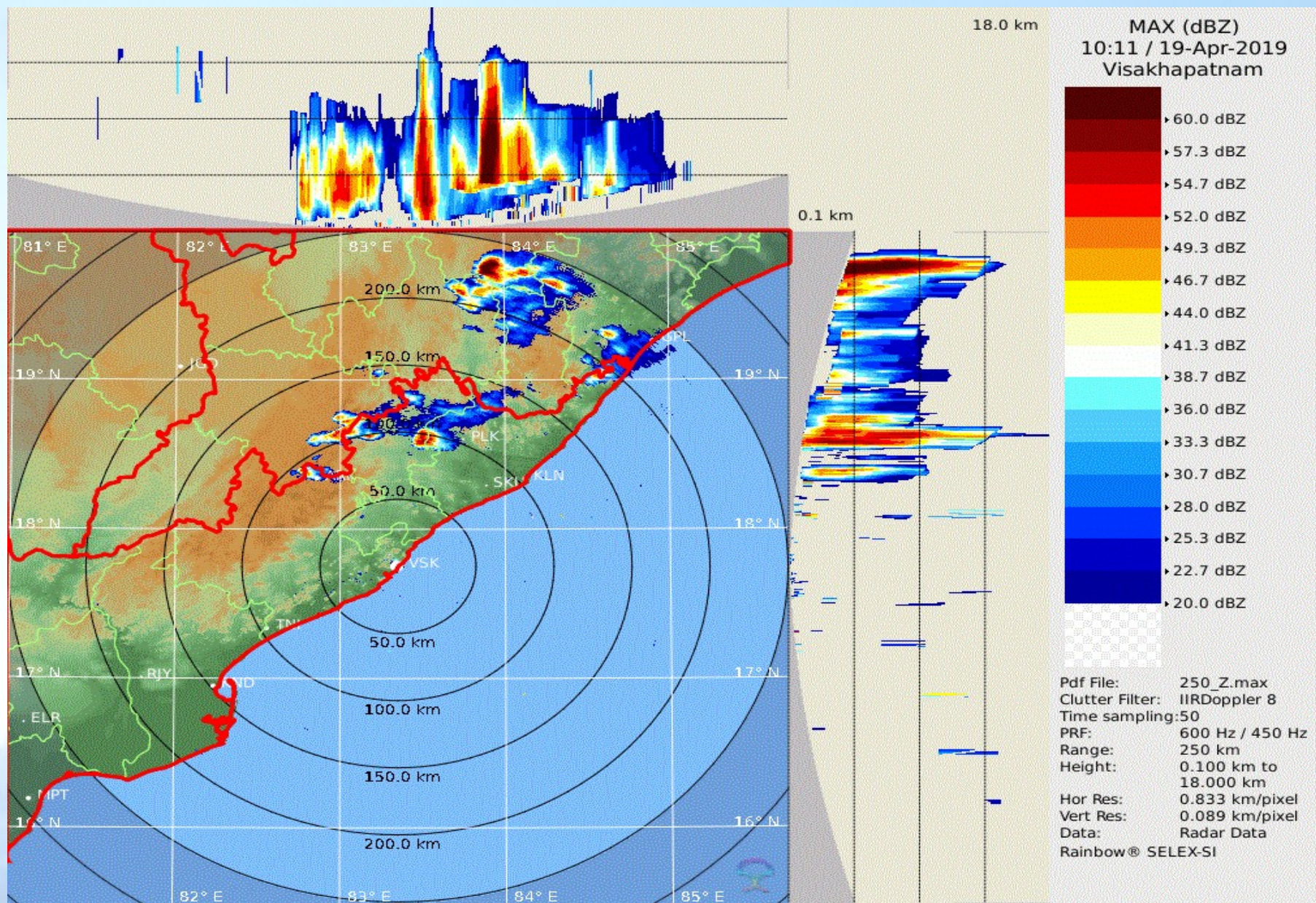
E-W VIEW





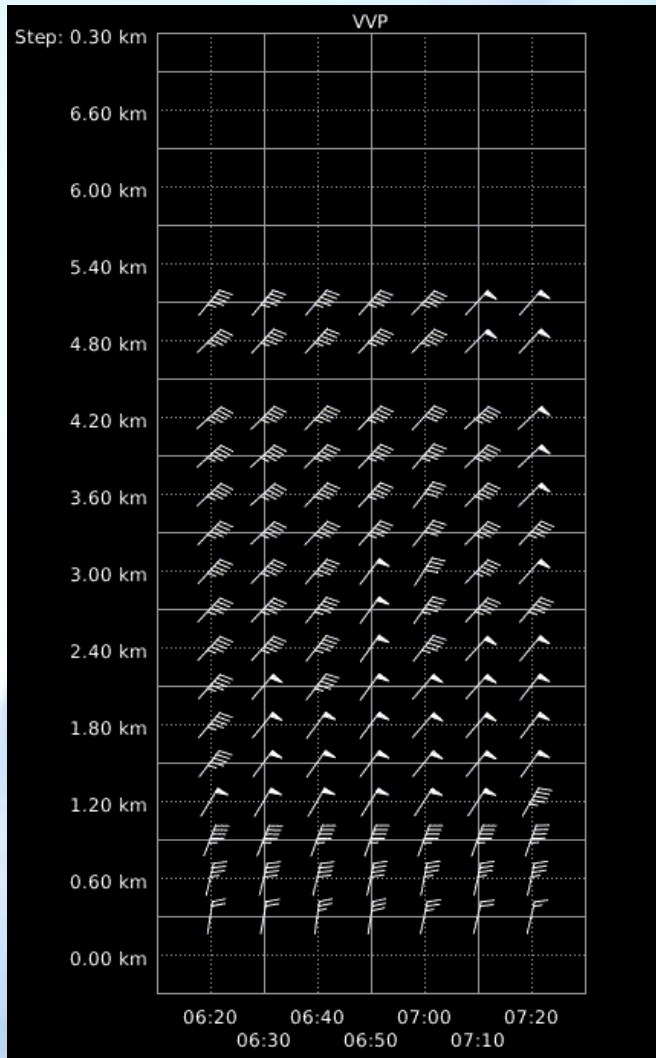








# VVP 30 Km



VVP (V)  
07:20 / 11-Oct-2014  
Visakhapatnam

Pdf File: 30.vvp  
Range: 1 km to 30 km  
Clutter Filter: IIR Doppler 8  
Time sampling: 40  
PRF: 500 Hz / 375 Hz  
Alg type: Complete  
Elevation: 0.2 deg to 21.0 deg  
Second reg: On

Rainbow® SELEX-SI

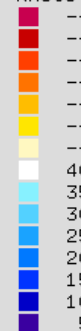
The *wind barb* presentation displays the horizontal wind velocity and direction of a vertical cylinder around the radar site over the time axis.

- Moisture influx at lower level
- Cloud Movement at higher levels
- Veering at low to mid and backing from mid to high (instability)
- Backing at low levels (stability)





knots



KOLKATA\_India

R : 50 km  
 PW : Short  
 PRF : 800 / 0  
 AS : 11.90 deg/s  
 TS : 64  
 RS : 2  
 CC : Doppler 12  
 SQI : 0.35  
 CSR : 20.0 dB  
 LOG : 2.0 dB  
 MAXH : 7.500 km  
 MINH : 0.000 km  
 LS : 0.300 km

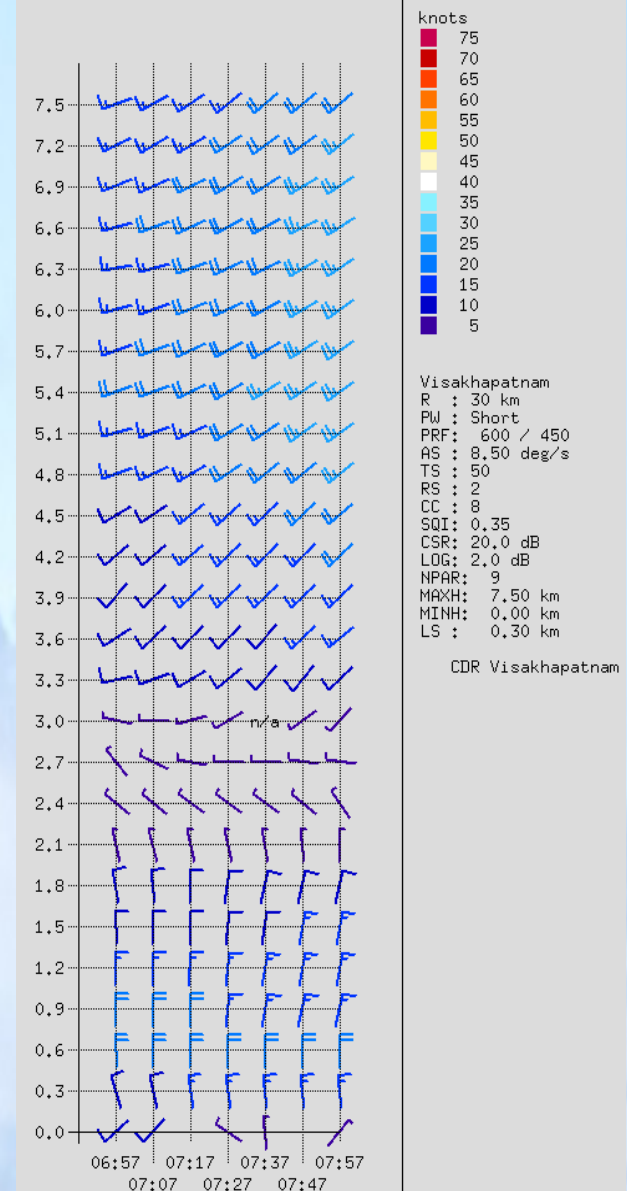
C.D.R. KOLKATA



# Prediction of Shear Zone

File : 2010100707570853.vp2  
Type : VVP\_2  
Range: 30.0 km

07.10.2010  
07:57:08

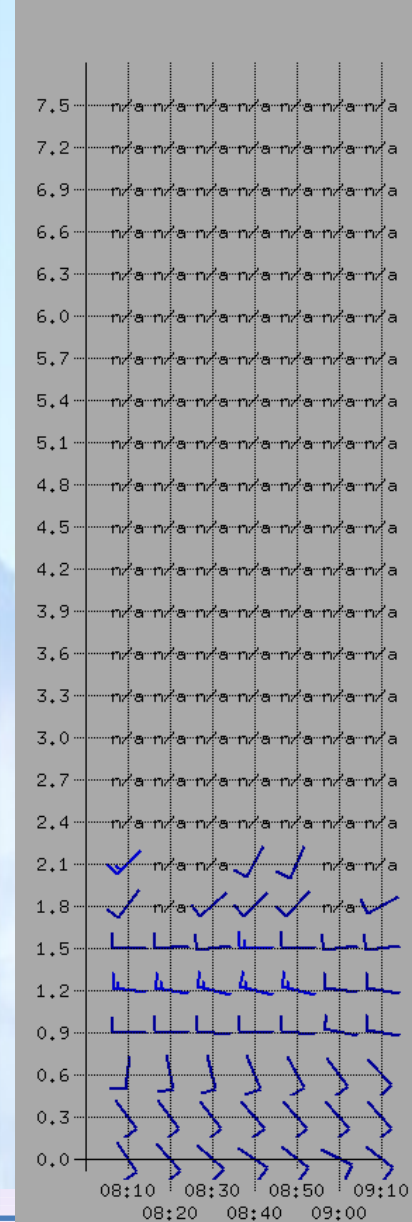




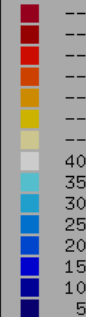
# Low level Wind Shear

File : 2010101809101874.vp2  
Type : VVP\_2  
Range: 30.0 km

18.10.2010  
09:10:18



knots



CHENNAI

R : 30 km  
PW : Short  
PRF: 800 / 0  
AS : 11.90 deg/s  
TS : 64  
RS : 2  
CC : Doppler 12  
SQI: 0.35  
CSR: 20.0 dB  
LOG: 2.0 dB  
NPAR: 9  
MAXH: 7.50 km  
MINH: 0.00 km  
LS : 0.30 km

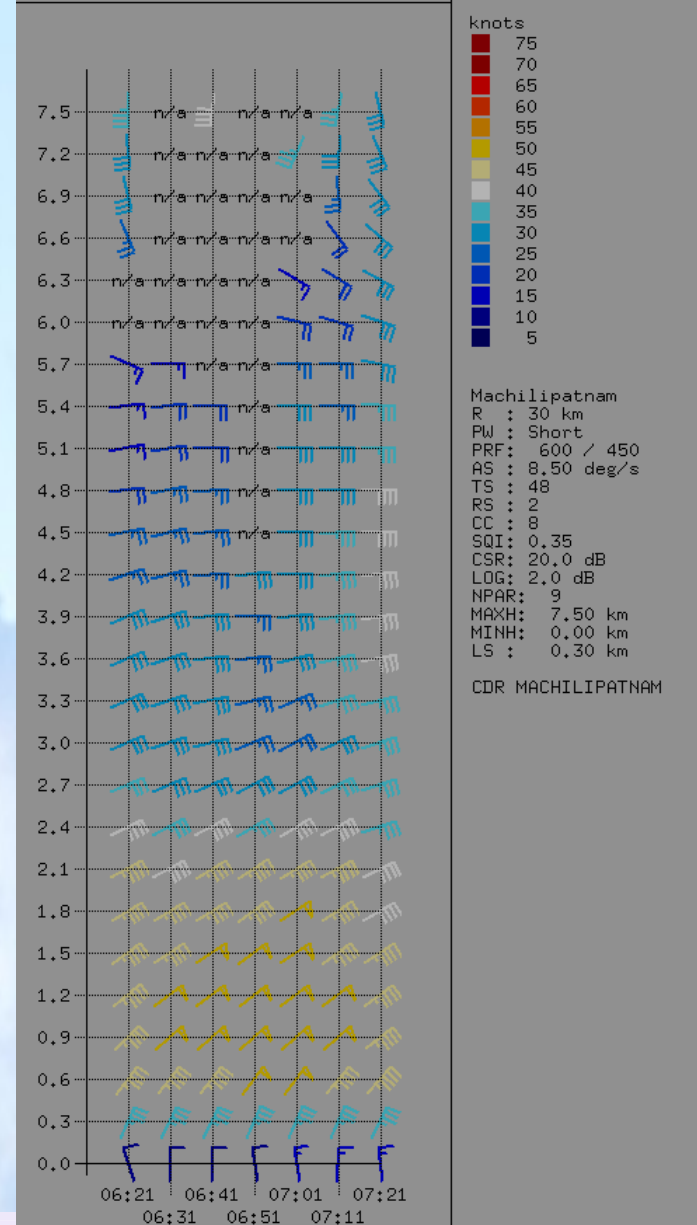
CDR Chennai



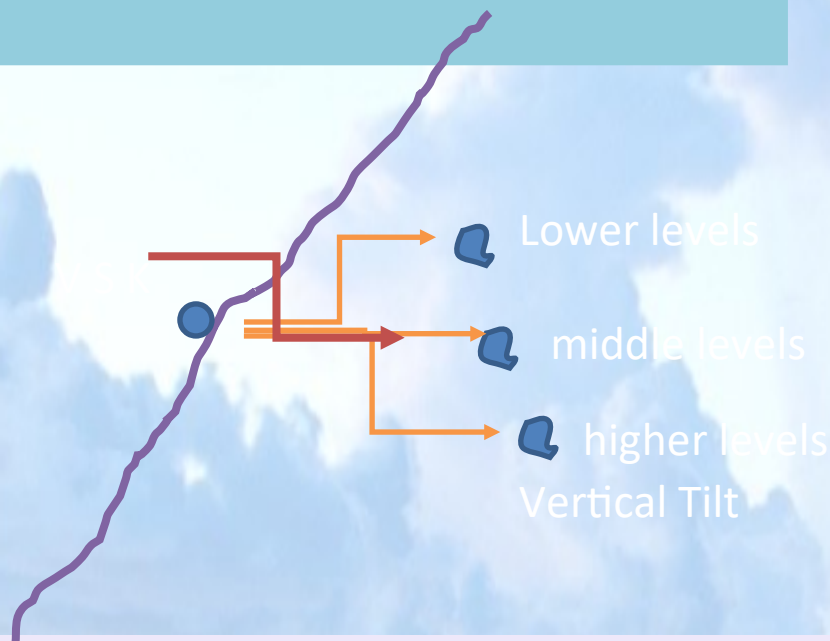
# Low level Jet

File : 2008111507213486.vp2  
Type : VVP\_2  
Range: 30.0 km

15.11.2008  
07:21:34

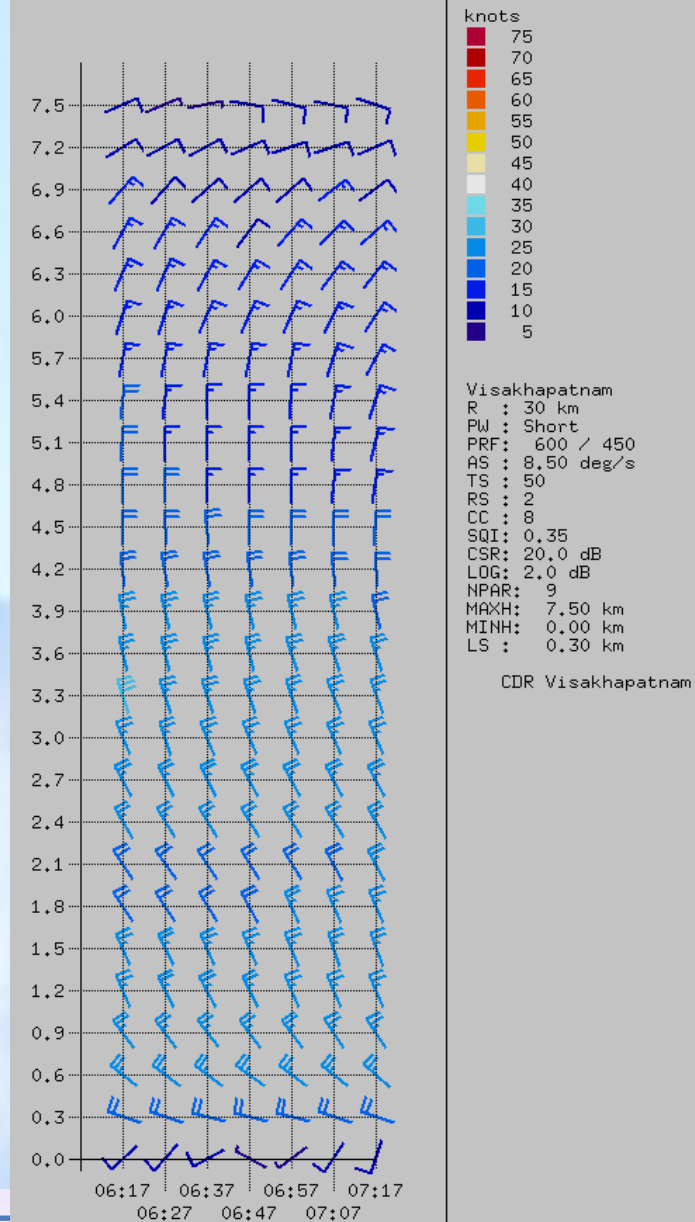


# Prediction of Vertical TILT of circulation vortex (Depression)



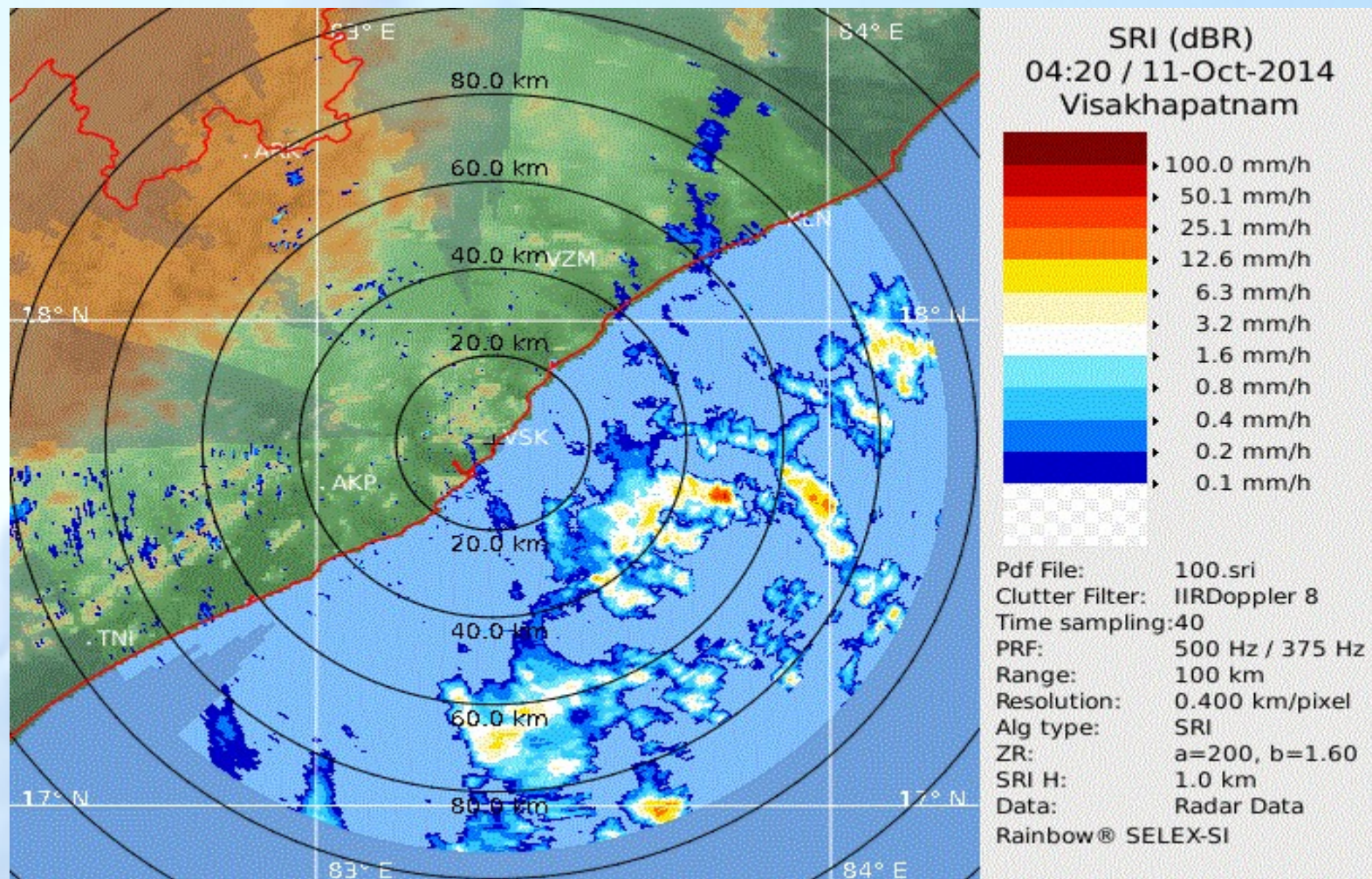
File : 2010101507171007.vp2  
Type : VVP\_2  
Range: 30.0 km

15.10.2010  
07:17:10





# Surface rainfall Intensity



# Surface Rainfall Intensity (SRI)

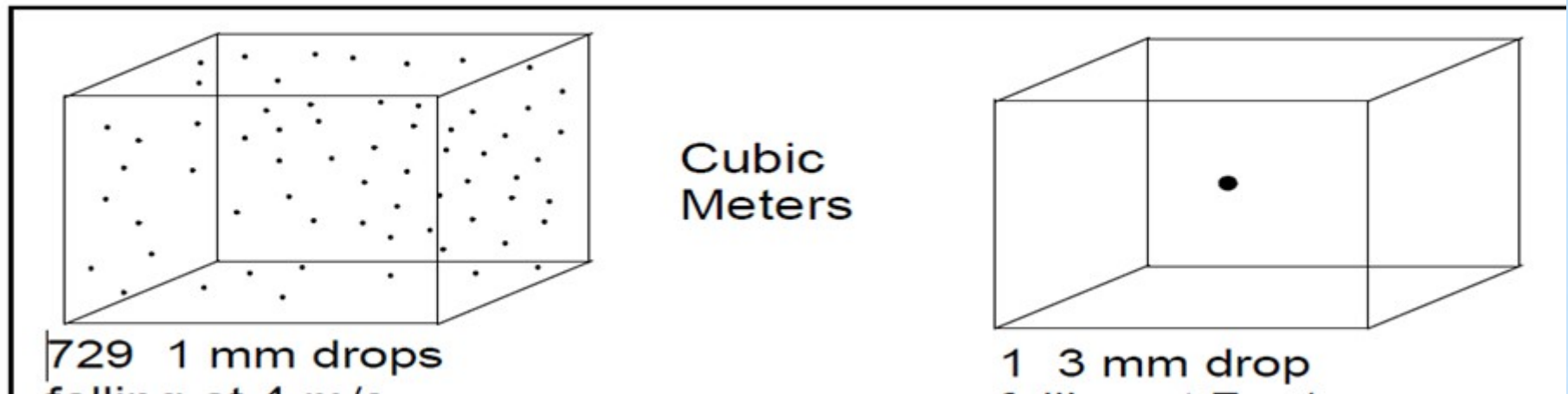
It is pictorial presentation of the rainfall intensity around a radar station based on the reflectivity of clouds.

The **rain rate** is calculated using Marshall-Palmer equation  $Z=AR^b$  where **R** is the rainfall intensity and **A** and **b** are constants. The value of A & b varies from season to season and place to place.





# Surface Rainfall Intensity



$$Z = \int N(D) D^6 dD$$

$$(729 \text{ drops/m}^3)(1 \text{ mm})^6$$

$$729 \text{ mm}^6/\text{m}^3$$

$$29 \text{ dBZ.}$$

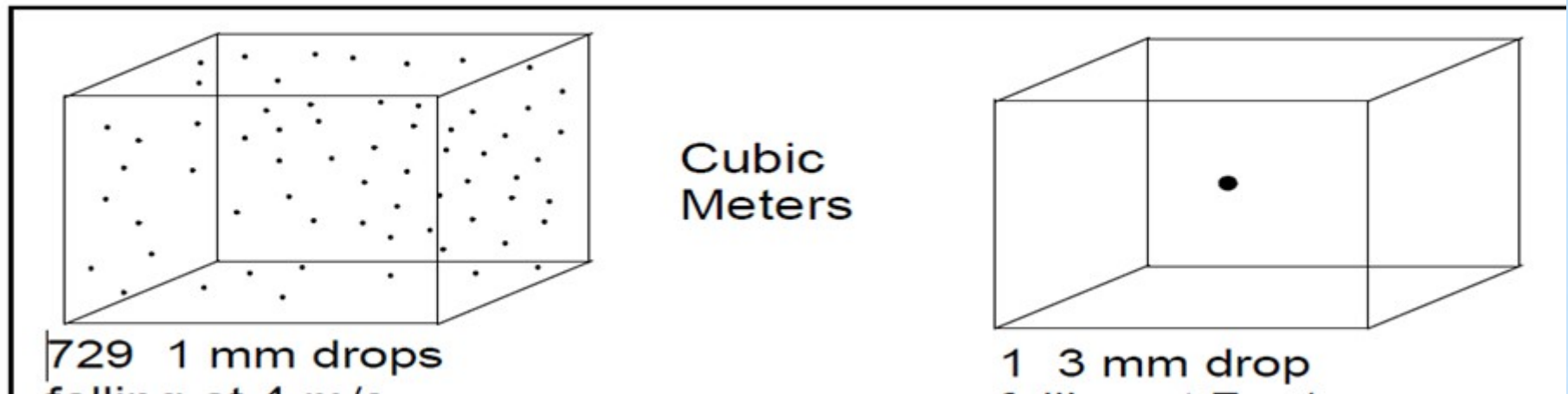
$$(1 \text{ drop/m}^3)(3 \text{ mm})^6$$

$$729 \text{ mm}^6/\text{m}^3$$

$$29 \text{ dBZ.}$$



# Surface Rainfall Intensity



$$R = \frac{\pi}{6} \int N(D) D^3 w_t(D) dD$$

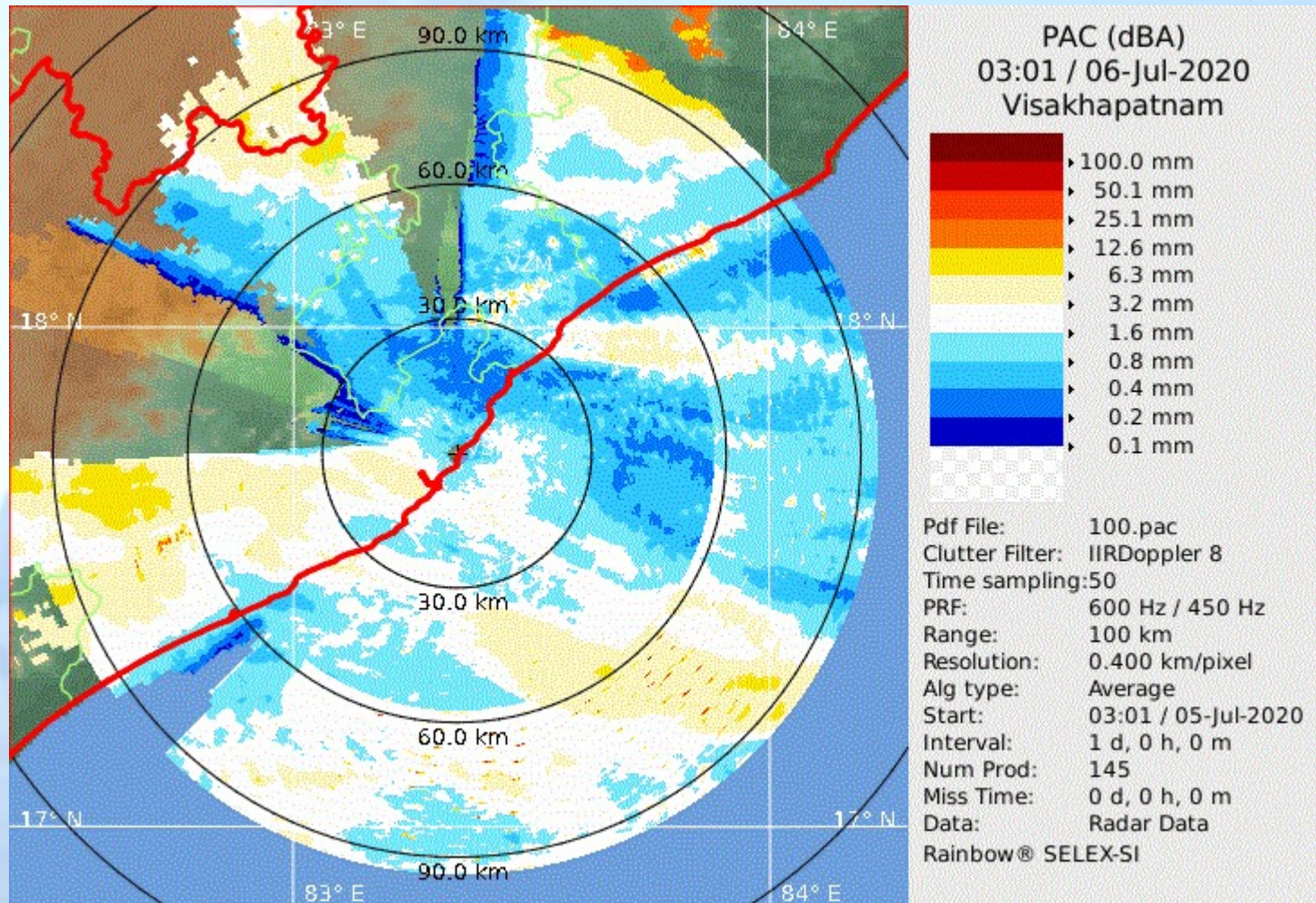
29 dBZ.

$R_1 = 5.55 \text{ mm/hr.}$

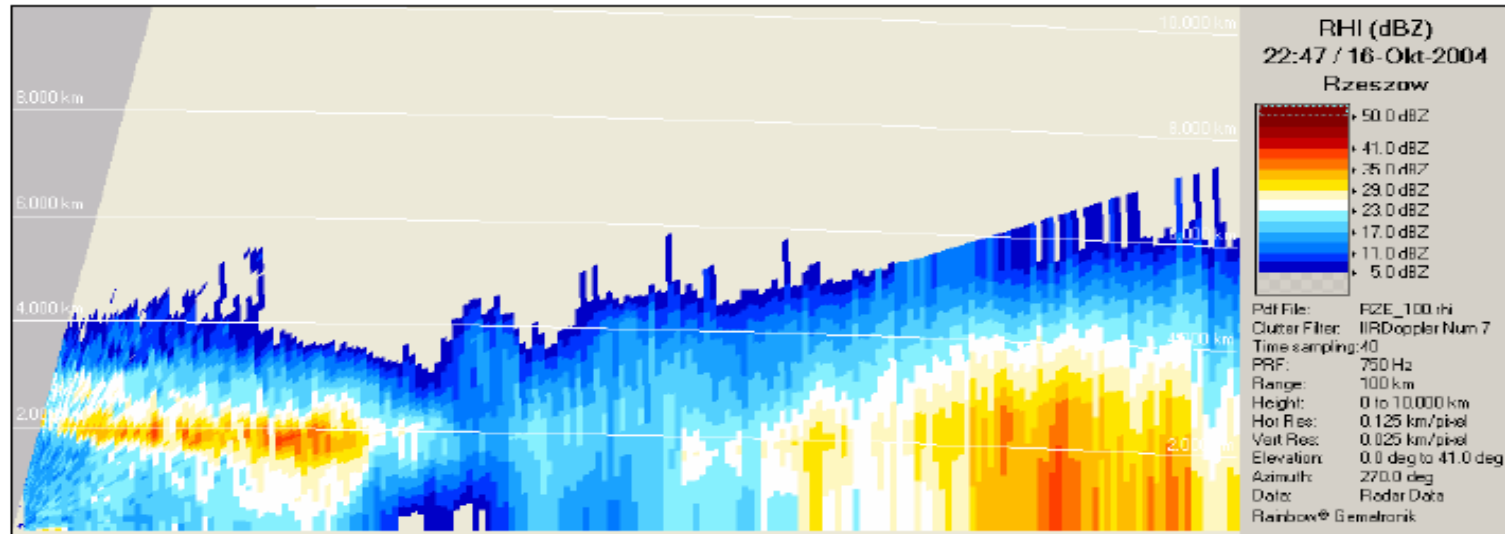
29 dBZ.

$R_2 = 0.3564 \text{ mm/hr}$

# PAC



# Range Height Indicator

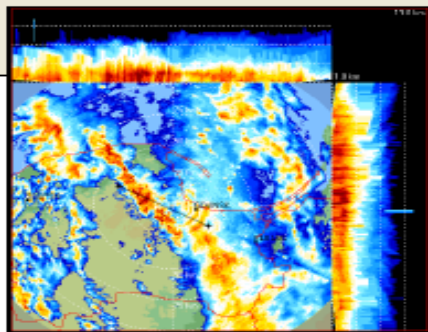
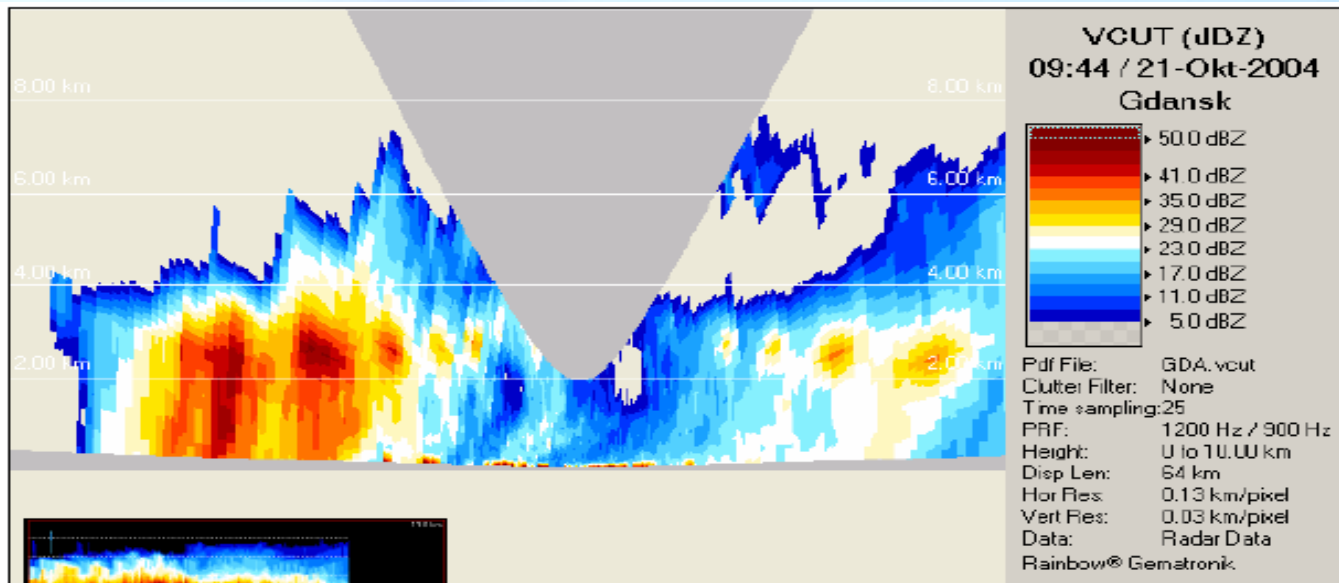


The RHI algorithm takes an elevation scan at a fixed azimuth as input. A vertical display (range vs. height) is displayed.





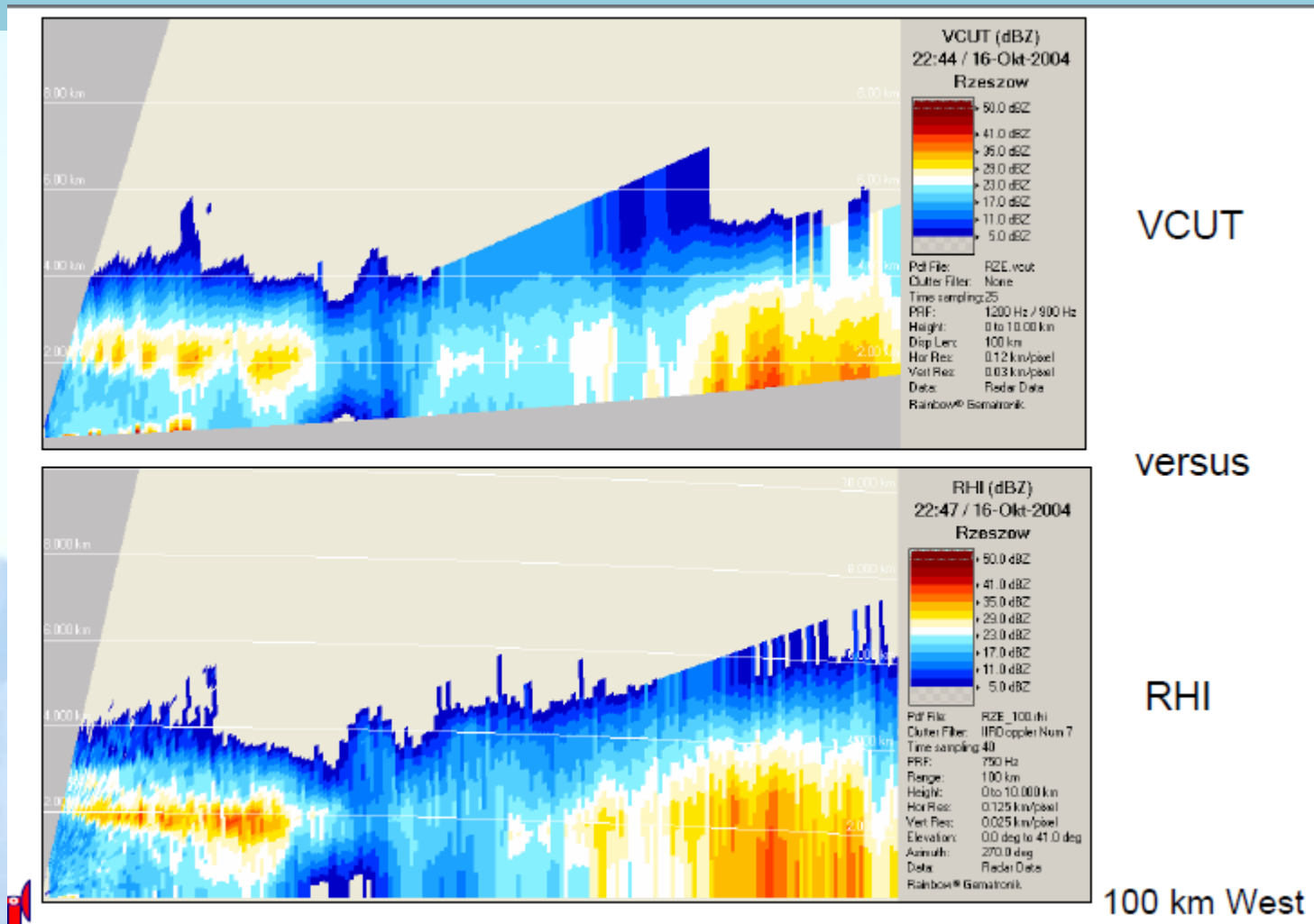
# Vertical Cut



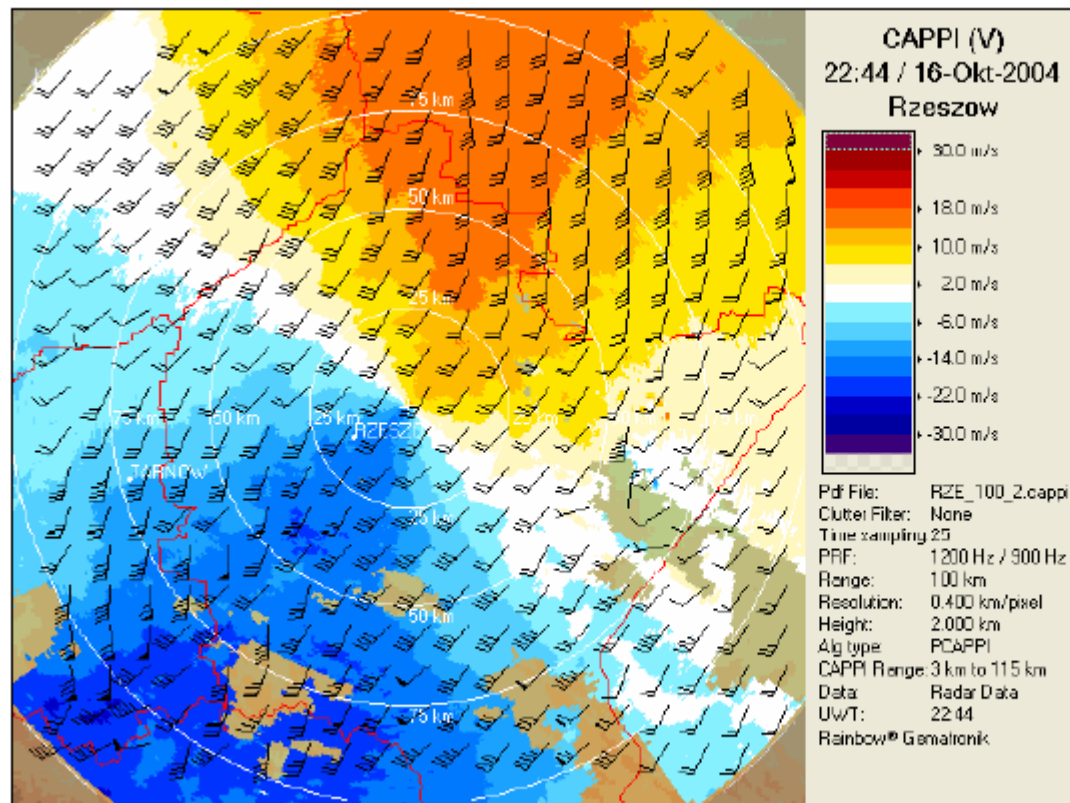
The VCUT displays a vertical cross section through a polar volume set. *Start* and *Stop* point can be selected interactively by mouse.

In case of MLVCUT the vertical cross section is generated along a multiple line.

# VCUT vs RHI



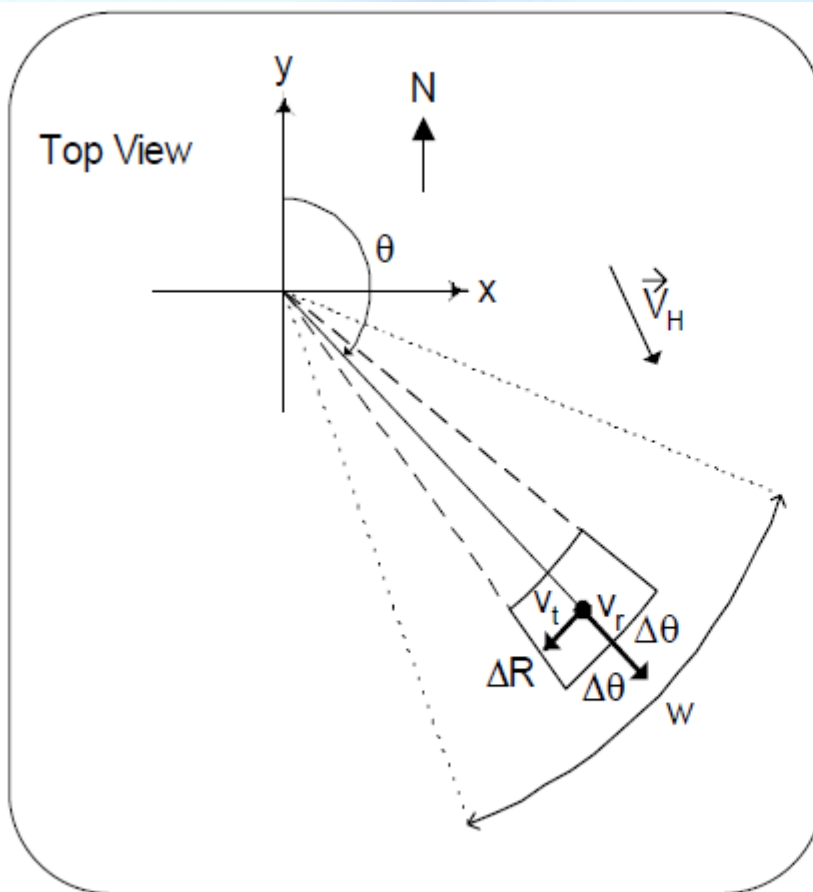
# Uniform Wind technique



This product shows horizontal wind vectors in any top projection image as dynamic overlay. The standard algorithm for uniform wind technique of SMI has been applied.



# Uniform Wind technique



$V_H$  is the horizontal wind vector. At the analysis location,  $V_H$  is indicated by its components  $v_r$  and  $v_t$ .

$v_r = \text{radial velocity}$

$v_t = \partial v_r / \partial \theta_{\text{rad}}$

$u = v_r \cdot \sin(\theta) + v_t \cdot \cos(\theta)$

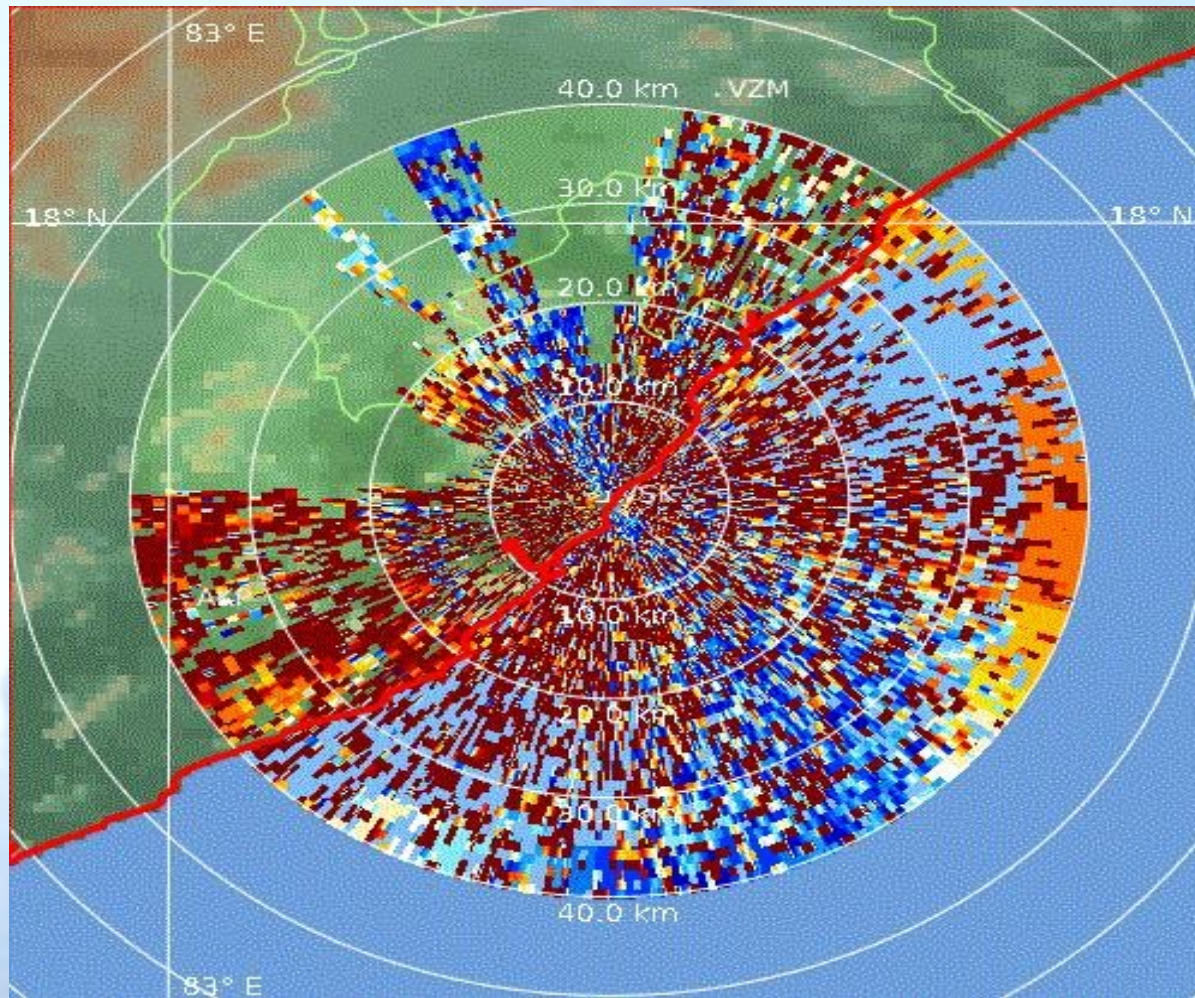
$v = v_r \cdot \cos(\theta) - v_t \cdot \sin(\theta)$

$\text{Speed} = \sqrt{u^2 + v^2}$

$\text{Direction} = \arctan(u / v)$



# Vertical Wind shear



VSHEAR (Shear)  
18:01 / 22-Mar-2018  
Visakhapatnam

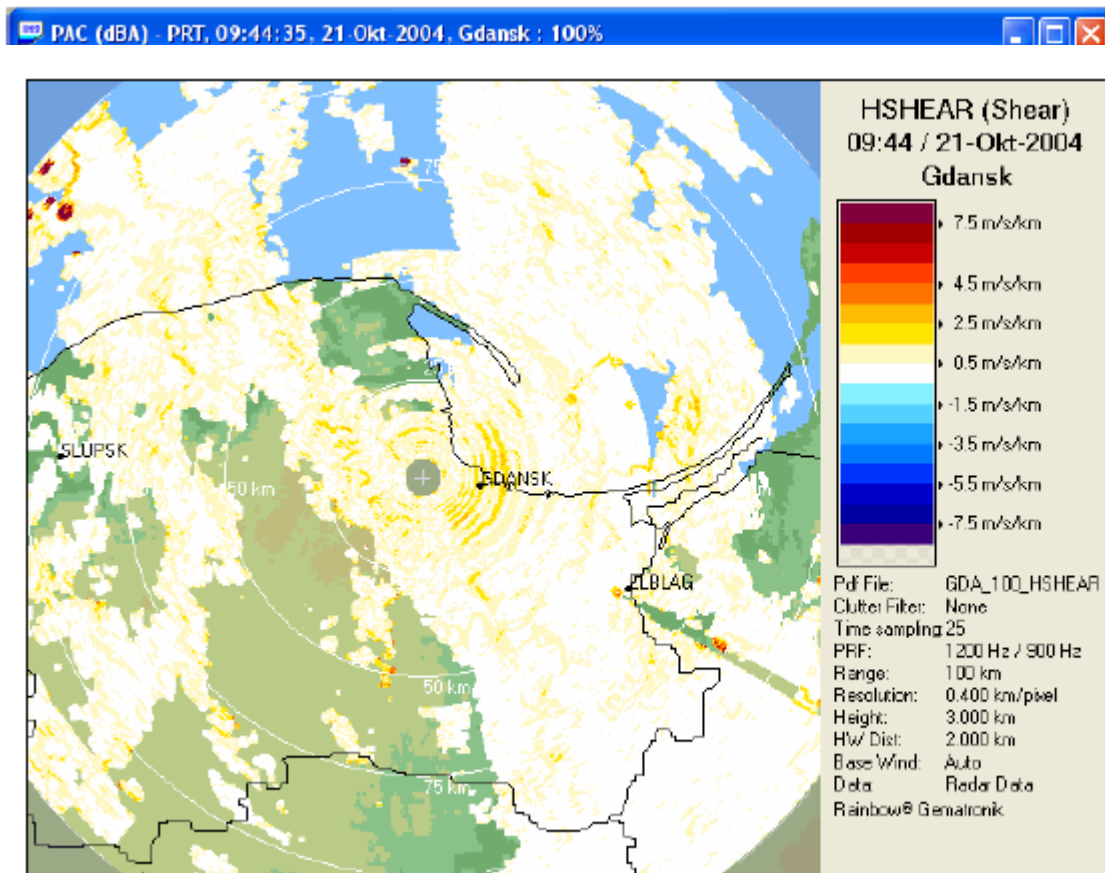


Pdf File: vsk2.vshear  
Clutter Filter: IIRDoppler 7  
Time sampling: 50  
PRF: 600 Hz / 450 Hz  
Range: 50 km  
Resolution: 0.200 km/pixel  
Height: 0.400 km to 0.600 km  
Base Wind: Auto  
Data: Radar Data  
Rainbow® SELEX-SI





# Horizontal Shear



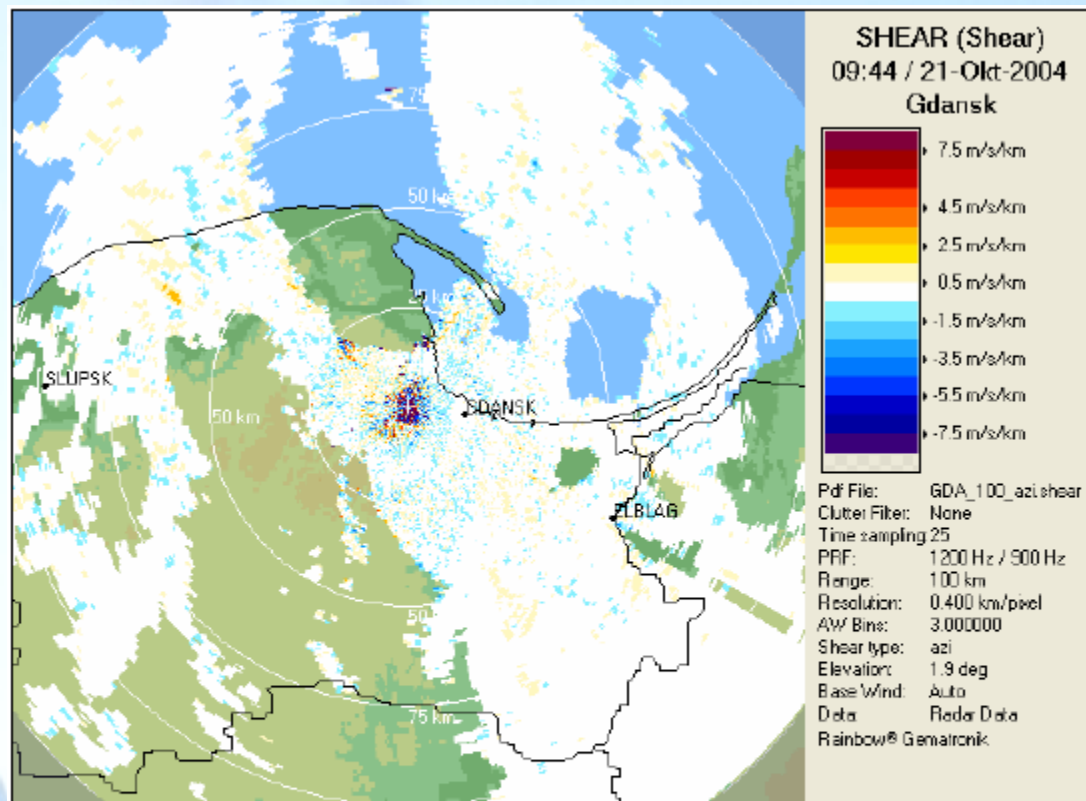
The PRT product

The change of the wind velocity in north-south direction and in east-west direction in a single layer of constant height above MSL is calculated, and combined to find the value of the horizontal shear.

PRT overlay with tool tip information

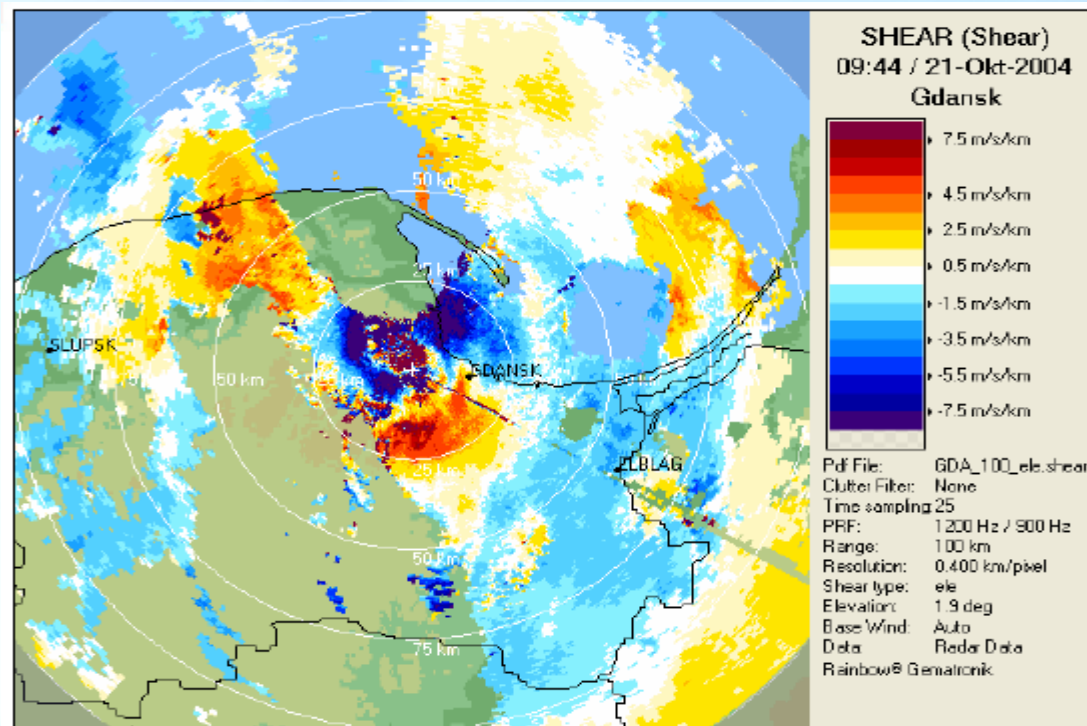


# Azimuth Shear



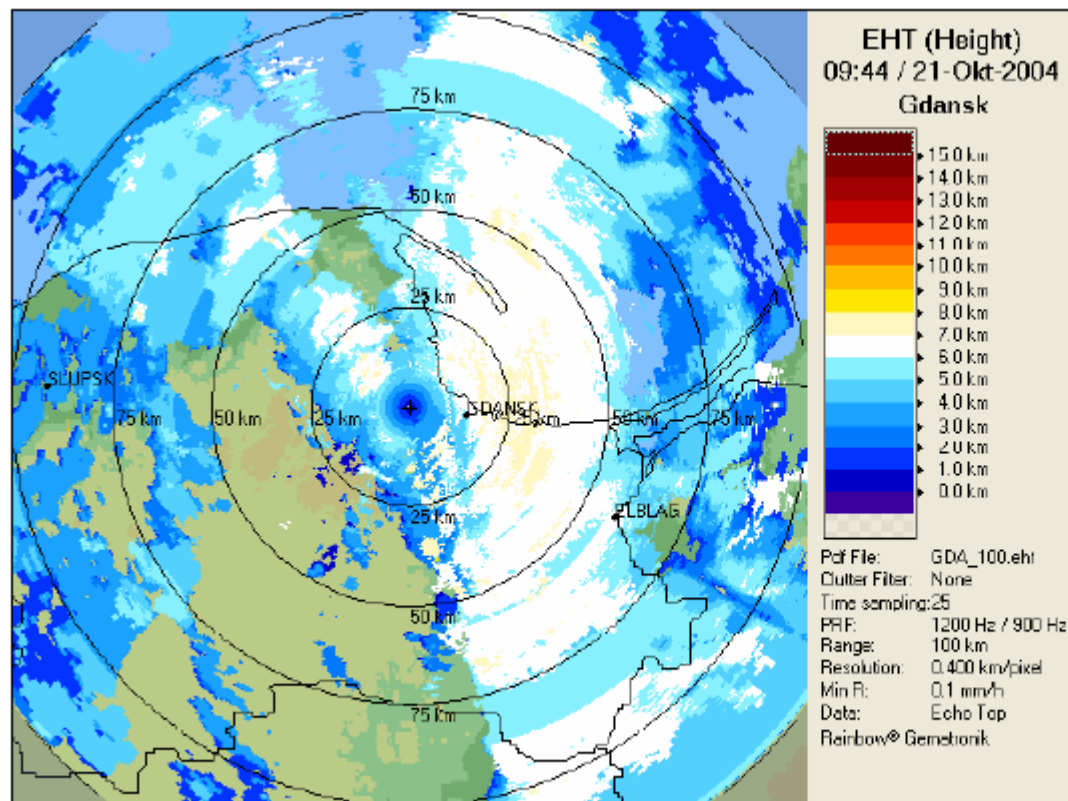
The *azimuth* shear (AZS) evaluates the derivative of the radial wind velocity in azimuth direction.  
Positive AZS → *counter clockwise (cyclonic) rotation*.  
Negative AZS → *clockwise (anti-cyclonic) rotation*.

# Elevation Shear



The *elevation* shear (ELS) evaluates the derivative of the radial wind velocity in elevation direction. Two planes of constant elevation are taken as input.  
The ELS is similar to the vertical shear product VSHEAR.

# Echo Top/Base



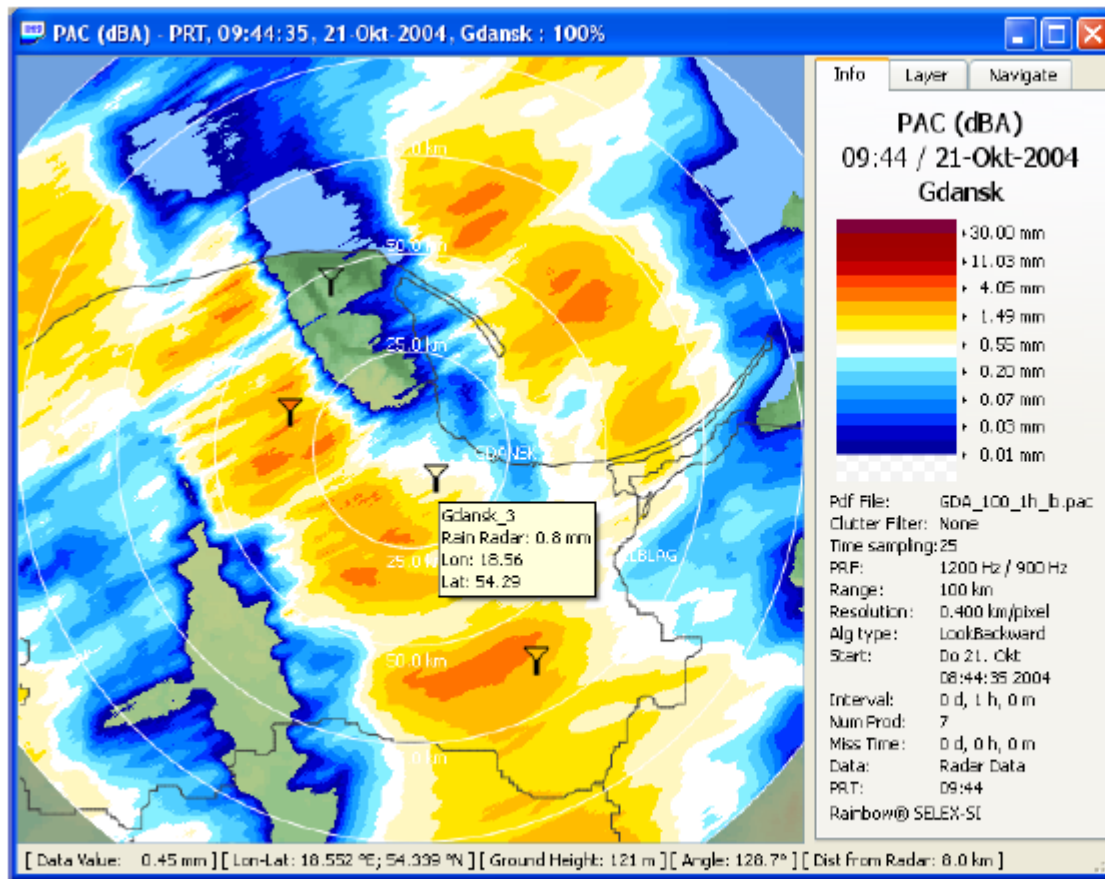
The EHT product shows e.g the uppermost height where the measured value is greater than a user-defined threshold.

Selectable are ...

- Echo Top
- Echo Base
- Height of  $Z_{\max}$



# Point Rainfall Total

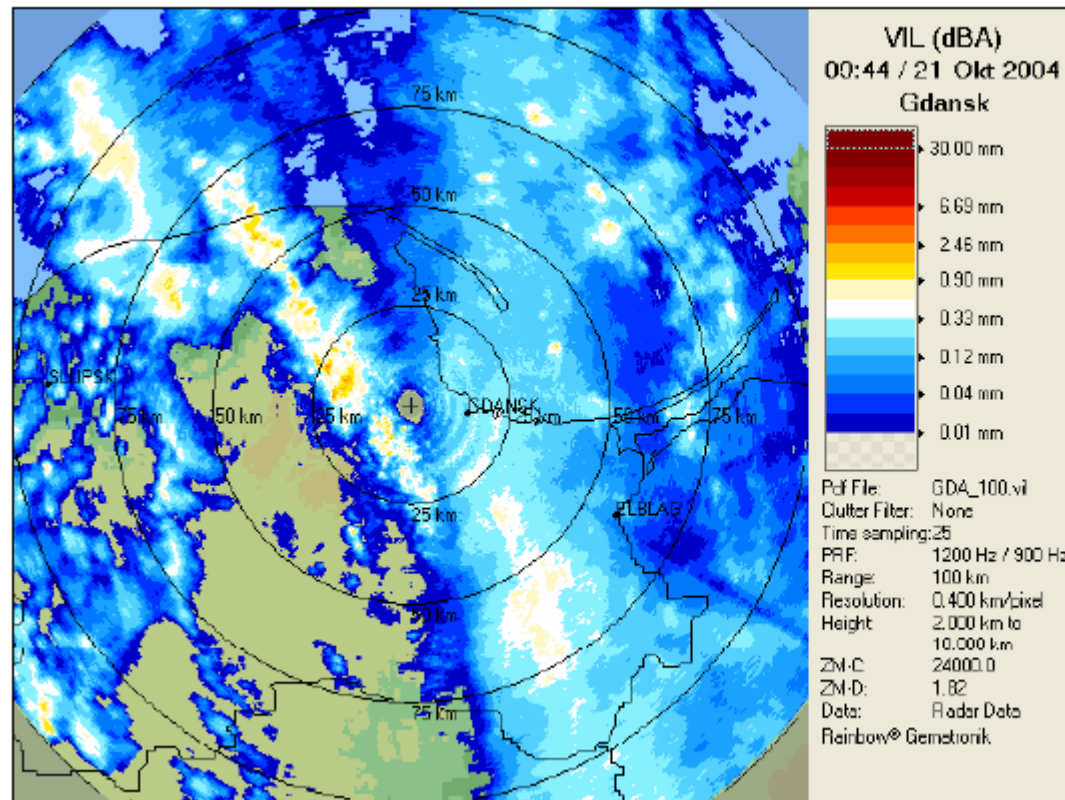


The PRT product provides information about the rainfall total (accumulated rainfall) at a variety of selectable locations within the radar coverage. The accumulation time interval corresponds to that defined for the input PAC. DART shows colored symbols with

- location name
- radar total
- lon/lat coordinates

PRT overlay with tool tip information

# Vertical Integrated Liquid



The aim of the VIL product is to give an instantaneous estimate of the water content residing in an user-defined atmospheric layer in order to indicate the rainfall potential of a e.g. severe storm.